

Vol. 24, No. 5-6, December, 2022, pp. 273-279

Journal homepage: http://iieta.org/journals/ejee

Identification of Photovoltaic Panel MPPT Using Neuro-Fuzzy Model

Aouiche Abdelaziz^{1*}, Aouiche El Moundher², Aouiche Chaima³, Djellab Hanane¹



¹Department of Electrical Engineering, LABGET Laboratory, Faculty of sciences and Technology, Echahid Cheikh Larbi Tebessi University, Tebessa 12000, Algeria

² School of Electrical and Electronic Engineering, Hebei University of Technology, Tianjin 300130, China

³ Department of Electrical Engineering, (LAMIS) Laboratory of Mathematics, Informatics and Systems, Faculty of sciences and Technology, Echahid Cheikh Larbi Tebessi University, Tebessa 12000, Algeria

Corresponding Author Email: abdelaziz.aouiche@univ-tebessa.dz

https://doi.org/10.18280/ejee.245-606
Received: 16 November 2022
Accepted: 16 December 2022

Keywords:

fuzzy inference systems, maximum power point tracking, modeling, photovoltaic panel

ABSTRACT

A photovoltaic (PV) panel produces energy that is influenced by external factors including temperature, irradiation, and the fluctuations in the load related to it. The PV system should perform at maximum power point (MPP) in order to adjust towards the rapidly increasing interest in energy. Because of the changing climatic conditions, it becomes has a limited efficiency. In order to maximize the PV system's efficiency, a maximum power point technique is necessary. In the present paper a maximum power point (MPP) of photovoltaic (PV) panel is designed and simulated to optimize system performance, accurate synthesis model based on the hybrid neural fuzzy systems is proposed to directly obtain the MPP. So, photovoltaic panel (PV) is analyzed with the mathematical model to obtain the training data. Three cases were used to test the identification of the structure proposed. The results show neuro-fuzzy (Sugeno Model) used were efficient in modeling the MPP of our PV panel. The Mean square error (MSE) is used as the fitness function to guarantee that the MSE is small, the algorithm synthesis model is validated by the MPP PV Panel analysis, simulation, and measurements. Neuro-fuzzy models is presented throughout this paper to demonstrate the effectiveness of the method of training suggested.

1. INTRODUCTION

Although a solar panel's ability to absorb solar energy is unaffected by temperature, it does influence how much power is generated. Less power generated from the same amount of sunshine when the solar panels get hotter. The voltage differential that you may theoretically obtain from the solar panel is the result of electrons being at rest (low energy) and being agitated by the sun (high energy). However, temperature also agitates electrons (by warming something, we provide it energy), increasing the energy of the electrons at rest. ("warmer" electrons offer more energy at rest compared to their "cold" equivalents.) .So, the geographic distribution of photovoltaic energy potential is taken into account, as well as the influence of irradiance and temperature on PV panel performance [1-3].

However, The Maximum Power Point (MPP) is the point at which the panel should be operating optimally, so the optimum system performance requires real-time control of the (MPP).

Several MPPT methods have been suggested and used in practice. Included among them are the incremental conductance (Inc-Con), the perturb and observe (P&O), fractional short-circuit current and fuzzy set system (FS). Some updated methods which attempt to reduce the amount of hardware required or to increase performance have also been presented forth [4-6]. These traditional MPPT techniques can offer better performance measurement when the PV Panel's circumstances are stable. but when the atmospheric conditions change rapidly, the traditional techniques may perform substantially worse. Therefore, many researchers have tried to apply intelligent MPP approaches that are effective for conditions that change quickly. They have become an interesting alternative to the conventional or traditional approaches to harvest maximum power from a PV panel [7, 8].

The suggested intelligent solution in this study is more cheap, adaptable, and very efficient; The Adaptive Networkbased Fuzzy Inference System (ANFIS) with its architecture and algorithm, to reach the MPP even when environmental factors are the worst [9].

The ANFIS is a kind of artificial neural network designed on the Takagi-Sugeno fuzzy inference system (FIS). It mixes the advantages of both FISs and artificial neural networks (ANNs) into a unified architecture. Excellent explanation tools in the form of semantic representations fuzzy rules, rapid and precise learning, the capacity to take into account data as well as the problem's existing expert knowledge, Neuro-fuzzy systems have become more popular in recent years because to their advantages for generalization and other aspects [4]. So, in this work ANFIS modeling technique is introduced to determine PV Panel MPPT [10].

The suggested MPPT technique is verified, validated, and simulated using the Matlab software platform while temperature and irradiance are dynamically changed. In comparison to existing conventional-based MPPT methods, the suggested ANFIS's MPPT performance is superior. The proposed method is tested with three different cases; the first one when the irradiation varies and the temperature stays constant, the second case when the temperature varies and the irradiation is constant and the last case is the difficult one when the temperature and the irradiation change together. The simulation results show that the ANFIS can replace the real model of PV panel in terms of delivering better efficiencies and rise time, with and without the appearance uncertainties in the model and the tracking error between the model and the system was decreased to a minute level.

This paper is divides in four sections, the second section describes the process that modelling MPPT, the design of ANFIS is explained shortly in section 3, and then the implementation of this technique to the tracking of MPP is showed and simulated. At the end of this paper, we will show how our selected method can achieve very robust and satisfactory performance.

2. BACKGROUND

2.1 Solar cell equivalent model

The electronic component that transforms solar energy into electricity is considered as a cell [11, 12]. A Photovoltaic Panel (PV) module is an array of cells that have been connected in series, there are parallel and series connections between the modules. The majority of mathematical models that have been created are based on the single-diode model's current-voltage relationship as shown in the following Figure 1, which makes the assumption PV cell's characteristics can be described by a single lumped diode mechanism [13].



Figure 1. Equivalent solar cell circuit

By the current law of Kirchoff:

$$I = I_{irr} - I_{dio} - I_p \tag{1}$$

 I_{irr} : is the irradiance current or the photo-current, where, for a given cell temperature, is produced after the cell has been exposed to direct sunlight.

The solar cell's non-linear properties are produced by the current passing through the anti-parallel diode I_{dio} . where,

$$I_{dio} = I_0 \left\{ exp(\frac{q(\nu + IR_s)}{nKT}) - 1 \right\}$$
(2)

The shunt current I_P given to the branch of the shunt resistor R_P is given as follow:

$$I_P = \left(\frac{\nu + IR_s}{R_P}\right) \tag{3}$$

Substitution the important expressions of I_{dio} and I_P ,

$$I = I_{irr} - I_0 \left\{ exp(\frac{q(\nu + IR_s)}{nKT}) - 1 \right\} - (\frac{\nu + IR_s}{R_P})$$
(4)

where,

 $q = 1.602 \times 10^{-19}$ C is the electronic charge,

 $K = 1.3806503 \times 10^{-23}$ J/K is the Boltzmann constant,

n: is the ideal constant of the diode,

T: is the cell's temperature,

 I_0 : is the diode saturation current,

 R_P and R_s represent the shunt and series resistance, respectively [13].

2.2 Photovoltaic module current-voltage relationship

A PV module typically consists of several solar cells connected in series. N_S denotes the quantity of solar cells arranged in series for a single module.

As an illustration: N_S = 36 for BP Solar's BP365 Module, N_S = 72 for ET-Solar's ET Black Module ET-M572190BB etc. When N_S solar cells constructed into a module by connecting them in series, the module's output voltage V_M and output current I_M have the following relationships:

$$I_{M} = I_{irr} - I_{0} \left\{ exp(\frac{q(V_{M} + I_{M}N_{S}R_{s})}{N_{S}nKT}) - 1 \right\} - (\frac{V_{M} + I_{M}N_{S}R_{s}}{N_{S}R_{p}})$$
(5)

This equation can be expanded to any number of cells in series (N_S) , hence it is not constrained to only one module. If each module has NC cells in series and N_M modules are connected in series, then [14]:

$$N_S = N_M \times N_C$$

2.3 Basic model parameters

It is important to talk about the primary model characteristics and how they vary with operational situations.

Irradiance and temperature both influence the photocurrent (6):

$$I_{ph} = I_{irr,ref}\left(\frac{G}{G_{ref}}\right) \left[1 + \alpha'_{T}(T - T_{ref})\right]$$
(6)

G: Irradiance W/m^2

 $G_{\rm ref}$: Irradiance at 1000 W/m2,

where $I_{irr,ref}$ is the photo current at SRC.

 α'_{T} is the short-circuit current's relative temperature coefficient, which shows how quickly the short-circuit current changes as a function of temperature. The absolute temperature coefficient of the short-circuit current is infrequently provided by manufacturers α_{T} for a particular panel [15-17].

The relationship between α_T and α_T is,

$$\alpha_T = \alpha'_T \times I_{irr,ref}$$

 $I_{irr,ref}$: is the second unknown parameter in the model. I_0 : is mostly influenced by the cell's temperature:

$$I_0 = I_{0,ref} \left[\frac{T}{T_{ref}} \right]^5 exp \left[\frac{E_{g,ref}}{kT_{ref}} - \frac{E_g}{kT} \right]$$
(7)

T: Cell temperature in its actual state (K)

 $T_{\rm ref}$: Cell temperature at 25°

 $I_{0,ref}$: The third undefined model's parameter is the saturating diode current during cell temperature at SRC.

 E_q : the bandgap energy [eV] defined as:

$$E_g = 1.16 - 7.02 \times 10^{-4} \left(\frac{T^2}{T - 1108} \right) \tag{8}$$

The power-voltage derivative is equal to zero at the point of maximum power in the SRC

$$\frac{\partial p}{\partial v} | p = p_{max, SRC=0} (P = V_A \times I_A)$$
(9)

Normative test conditions or the nominal condition (STC_s) of solar irradiation and temperature are always used to produce this information [18, 19].

Some manufacturers provide *I-V* curves for several irradiation and temperature conditions. These curves make easier the adjustment and the validation of the desired mathematical *I-V* equation. Basically, the Table 1 presents all the information one can get from datasheet of PV Panel) [20, 21].

Table 1. Electrical parameters of the BP SX 150S PV array
at 25°C,1000W/m2

Electrical characteristics	Value
Maximum Power (P _{mpp})	150 W
Voltage at $P_{mpp}(V_{mpp})$	34.5 V
Current at P_{mpp} (I_{mpp})	4.35 A
Short-circuit current (I_{sc})	4.75 A
Open-circuit voltage (V_{oc})	43.5 V
Temperature coefficient of <i>Isc</i>	$(0.065 \pm 0.015)\%/^{\circ}C$
Temperature coefficient of Voc	$-(160 \pm 20) \text{mV/}^{\circ}\text{C}$
Number of cells series (N_S)	72

3. MAXIMUM POWER POINT TRACKING (MPPT)

The most famous conventional MPPT methods are the Perturb and Observe (Hill climbing) method [22, 23], the Incremental Conductance method [24, 25], the Fractional open circuit voltage method [26, 27] and the Fractional short circuit Current method [28, 29]. And the artificial intelligence methods Fuzzy logic based MPPT [30] and Neural Networks based ones [31] and hybrid Neuro-fuzzy technique is the objective of this paper.

4. NEURO-FUZZY NETWORK STRUCTURE

ANFIS give better solutions to nonlinear problems because it merges fuzzy logic and neural networks approaches. It may fast arrive to the best possible result even if the targets are not defined [32].

In our study a five-layer neuro-fuzzy network is used to reach MPP, the selected ANFIS architecture is shown in Figure 2 based on the empirical analysis to obtain the final model who performs very well as predicting output data. An optimal ANFIS model consists of 2 input variables irradiance (E) and temperature (T), two membership functions and minimum number of rules, in our study we selected only two rules, the output of our ANFIS model is the maximum power of MPP (P_{mpp}). Whereas the circular nodes indicate nodes that are fixed.



Figure 2. ANFIS architecture for a Sugeno system with two rules

Our Sugeno ANFIS model contains the following two rules:

Rule 1: If x is A_1 and y is B_1 THEN $f_1 = p_1 x + q_1 y + r_1$

Rule 2: If x is
$$A_2$$
 and y is B_2 THEN $f_2 = p_2 x + q_2 y + r_2$

There are forward and backward passes possible for the network's training. Now, we check each layer separately for the forward pass. The input vector is passed forward, propagating layer by layer through the network. Similar to back-propagation, the error is propagated back through the network during the backward pass [33].

Layer 1

Each node's output is:

$$O_{1,i} = \mu_{A_i}(x)$$
 for $i = 1,2$ (10)

$$O_{1,i} = \mu_{B_{i-2}}(y)$$
 for $i = 3,4$ (11)

So, the $O_{1,i}(x)$ is essentially the membership grade for x and y.

The membership functions could be anything but for illustration purposes we will use the bell-shaped function given by:

$$\mu_A(x) = \frac{1}{1 + \left|\frac{x - c_i}{a_i}\right|^{2b_i}}$$
(12)

where, the premise parameters to be learned are a_i , b_i and c_i .

Layer 2

In this layer, each node is fixed. Here, the t-norm is applied to 'AND' the membership functions; as the following product:

$$O_{2,i} = w_i = \mu_{A_i}(x)\mu_{B_i}(y), \quad i = 1,2$$
 (13)

Layer 3

This layer has fixed nodes which determines the firing strength ratio according to the rules:

$$O_{3,i} = \overline{w_i} = \frac{w_i}{w_1 + w_2} \tag{14}$$

Layer 4

The nodes in this layer are adaptive and perform the consequent of the rules:

$$O_{4,i} = \overline{w_i} f_i = \overline{w_i} (p_i x + q_i y + r_i)$$
(15)

The parameters in this layer (p_i, q_i, r_i) are the consequent parameters and must be determined.

Layer 5

Here, the complete output function is performed by a single node [34]:

$$O_{5,i} = \sum_{i} \overline{w_i} f_i = \frac{\sum_{i} w_i f_i}{\sum_{i} w_i}$$
(16)

We verify that the neuro-fuzzy models after learning are actually able to predict the desired output for values given at the entry which are not used in the learning. We always should compare the true output of the networks using *V*-*I* properties of the desired PV (Tab 1) for comparisons.

The training data sets were obtained from PV Panel with about 432 data were used to train the neuro-fuzzy models.

To train the model, some data must be obtained for the input and output variables. As a consequence, the distinct layers of the neuro-fuzzy model acquire their rules. To obtain data, PV model coding in MATLAB is performed.

The rules have been specified after the fuzzy model has been trained, for any T and E inputs, and P_{mpp} output of our ANFIS. Now, likewise, maximum power P_{mpp} is obtained by multiplying v_{mpp} and I_{mpp} .

5. SIMULATION RESULTS

We incorporate in this work five-layer cascading neurofuzzy model that predicts the PV panel voltage at which the maximum power is attainable.

V-I characteristics of modeled PV are shown in Figures 3 and 4.



Figure 3. Characteristic of PV, P=f(V)



Figure 4. Characteristic of PV, I=f(V)

5.1 Learning step

The following Figures 5 and 6 present the learning data and error obtaining of our ANFIS.



Figure 5. Training data



Figure 6. Training error

The following Table 2 presents the architecture of our Model (ANFIS) for PV learning:

Neuro-fuzzy model	Training parameters
Number of fuzzy rules	04
Training input	$10^{\circ}\text{C} \le T \le 80^{\circ}\text{C}$ $100\text{W/m}^2 \le G \le 1000\text{W/m}^2$
Number of nodes	21
Number of linear parameters	12
Number of nonlinear parameters	12
Total number of parameters	24
Number of training data pairs	432
Mean Square Error (MSE)	0.0010

 Table 2. ANFIS model architecture used to predict the MPPT

5.2 Validation step

Now we verify that our model after learning is actually able to predict the desired output for values given at the entry which are not used in the learning. We always should compare the true output of the networks with the model of the PV for comparisons using mean square error (MSE). For this we study three cases: two extreme cases and a general one.

5.2.1 Case 01: the irradiation varies and the temperature is constant as shown in Figures 7 and 8.

$\checkmark 100 \text{W/m}^2 \le E \le 1000 \text{W/m}^2 \text{ and } T = 2^{\circ} \text{C}$



Figure 7. '+'ANFIS model and 'O' PV panel MPPT for T = 2°C with MSE=0.17

✓ $50 \text{W/m}^2 \le E \le 550 \text{W/m}^2$ and $T = 60^{\circ}\text{C}$

Characteristic MPPT, E=50W/m² TO E=550W/m² and T=60°C 70 E=550W/m² ANFIS MPPT + PV Panel MPPT 0 60 E=450W/m 50 E=350W/m² 40 (M) 140 14 dw E=250W/m² E=150W/m² 20 10 ==50W/m² 2 2.5 3 3.5 4 4.5 5 5.5 6 1.5 Number of samples

Figure 8. ANFIS model and PV panel MPPT for $T = 60^{\circ}$ C with MSE=0.041

5.2.2 Case 02: The temperature varies and the irradiation is constant as shown in Figures 9 and 10.

$$25^{\circ}\text{C} \le T \le 65^{\circ}\text{C} \text{ and } E = 900 \text{W/m}^2$$



Figure 9. ANFIS model and PV panel MPPT for G = 1000 W/m² with MSE= 7.5577e-004

✓ $30^{\circ}C \le T \le 70^{\circ}C$ and $E = 700W/m^2$



Figure 10. ANFIS Model and PV Panel MPPT with MSE= 2.7117e-004

5.2.3 Case 03: The temperature varies and the irradiation varies too as presented in Figure 11.

✓ $0^{\circ}C \le T \le 75^{\circ}C$ and $100W/m^2E \le 850W/m^2$



Figure 11. '+' ANFIS model and 'O' PV Panel MPPT for T and E vary with MSE 1.6032e-004

By examining the errors of all the considered cases of the variation of the irradiation and the temperature, it can be seen that the implemented ANFIS is able to predict the MPPT of the PV panel for any set of values of the inputs (E, T) belonging to their prescribed domain of variations

6. CONCLUSION

The ANFIS model's algorithm is presented to extract the maximum power from the PV Panel. The suggested approach

is very efficient for creating sophisticated, nonlinear connections between a set input/output information.

Quickly and accurately ANFIS model can be produced from measured or simulated PV Panel data. Once generated, after having received the necessary training, for newly presented situations, a neuro-fuzzy system entirely eliminates using complex iterative processes again. In this paper. The simulation results demonstrated that the ANFIS technique performs well for following the maximum power point, its speed, and the reliability of its outputs in all studied cases.

The recommendations that can be made in the future investigation, is the real-time implementation of this algorithm and hardware testing are both possible in Python and C++. Moreover, design of a web source containing simulations of the PV system, the MPPT controller, and the most used and popular algorithms in MATLAB and other technologies. To test the recently created algorithms, it may be possible to develop and implement a reprogrammable MPPT controller in the hardware under an open license. For this reason, we propose using 32-bit ARM microcontrollers.

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