

Comparative analysis of chronic kidney disease detection using K-means and FCM technique

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ABSTRACT

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About these study, we would like to existent Chronic Kidney Disease revealing procedures, established on the conservative a new Spatial Fuzzy-technique and K-means technique investigation of kidney MRI images. Although, the K-means was previously utilized in kidney MRI segmentation of image, along with segmentation of image at overall, this miss the mark to exploit the robust spatial association amongst neighbouring pixels. A spatial Fuzzy C-means (SFCM's) procedure, that is exploit the evidence of spatial accurately and generate extraordinary kidney images segmentation. To check the segmentation performance of Spatial Fuzzy C-means and K-means method, we have used 5 ground truth images. The outcomes of segmentation, that are demonstrated extra precise segmentation with the SFCM's matched with that of K-means are offered statistically and graphically.

1. INTRODUCTION

In image, to pinpoint precise entity and limitations, normally segmentation of image is utilized. The consequence of image segmentation is a set of areas that jointly protect whole image, or a set of outlines take out from the image. To excerpt precise and miniscule evidence from composite images is significant procedure of Segmentation. This has comprehensive solicitation within the arena of science of medical. It may divide an image into commonly limited and fatigued areas such that respectively area of concern is spatially adjoining and the pixels within the area are uniform rendering to a predefined benchmark, through the presentation of image segmentation. The nature of kidney images are difficult and inhomogeneous, renovating that inhomogeneous into homogeneous is actual challenging. This is actual challenging to envisage the configuration of the image for radiologists or urologists, without image segmentation. Hereafter, nearby is requisite of spontaneous segmentation methods on MRI images of kidney. The idea of spontaneous segmentation of kidney is the compactness of the study. Using CT scan or MRI scan, anatomy of the Kidney can be observed. For the whole procedure, the MRI scanned image is occupied in this study. For identification, the MRI scan is extra relaxed than CT scan. Since it is founded on the magnetic field and radio waves, it will not disturb the human body and there will be no radiation.

Due to the uncontrolled growth of the tissues in any part of the body, a tumor is formed. There are two kinds of tumors like secondary or primary. Scattering of existing tumor to another part of the body and grown as its own is called secondary tumor. Certainly, tumors are mass and malignant. Locating the malignant tumor is a little bit difficult whereas mass tumor detection is easy. For kidney tumor detection, there are different types of algorithms used.

We have analysed diverse natures of algorithms for the recognition of kidney tumor using this study. Using Mat Lab, these algorithms are established. For the improvement and

accomplishment, it is stress-free. The approaches for tumor discovery and particular position of the tumor with precise borders is originate out lastly.

1.1 Literature review

To obtain high-resolution images of the kidney, The Magnetic Resonance Imaging (MRI) is an extremely standard compared to Computed Tomography (CT). Normally, kidneys are unprotected of advanced concentration of Fluoride (F) of the intake water, in many methods, then any additional human fleshy tissue [7]. To provision the identification of different kidney diseases such as kidney stone, kidney cancer, kidney failure, polycystic kidney disease, hematuria, nephritis, glomerulonephritis. We requisite the investigation of the spatial dissemination of those soft tissue.

Formerly, nearly of the approaches like-manual interactive threshold, slice editing and region painting are utilized for segmentation of medical image, that can be determined by graphical communication on human to describe areas of attention. The approaches of dissimilar for segmentation of image are confidential into 4 leading groups by Yong yang et al. (2007) (1) Threshold region growing and edge based methods are measured as traditional procedures. (2) Origination below statistical technique is the Maximum-Likelihood Classifier (MLC). Fundamentally, these procedures are controlled and be determined by the previous model with its constraints. Since the previous few years, approximately original approaches of segmentation are presented, which might be categorized as Statistical procedures.

For segmenting 3D medical images using a probabilistic administered moderation method was functional by (Matthew Deighton and Maria Petrou, 2003). It will deliver the usage of indications to prime the segmentation. These signals are noticeable by nearly of the limitations such as standard deviation and mean. (10) (Evangelin, Jensly and Suresh, Padma, 2015) worked on a 2D model of segmentation of the

full kidney. Used normalised gradients and a Mahalanobis distance from the time courses of the segmented regions to a training set for supervised segmentation. (11) (Mahdi Marsousi, Konstantinos N. Plataniotis, Stergios Stergiopoulos, 2017) applied shape-to-volume registration, based on a new similarity metric, to detect the kidney shape by fitting the 3-D shape model on 3-D ultrasound volumes. Fitted shape model is used to initialize and evolve a new level-set function, called complex-valued rational level-set with shape prior, to segment the kidney's shape. By the standard fuzzy clustering algorithm, the areas of irregularity of the images are not accurately segmented (Chuang et al., 2006; Indah et al., 2011). However, It was recognized that the time complexity is extra occupied by the fuzzy c-mean algorithm. Since, multi-spectral images collected by different modes are typically capable to deliver wealthier anatomy evidence so the precision of the multi-spectral image segmentation can frequently be greater than that of the single-channel image segmentation. Since the dissimilar modes have their specific sole features and dissimilar handling approaches, multi-spectral image handling algorithms are typically additional composite than the single-channel image handling algorithms.

2. MATERIALS AND METHODS

2.1 K-Means Algorithm

It is an exploratory technique and conservative, that provides improved productivity in clustering of data. This clustering is a cooperating method". This method assembly the evidence by frequently outcome of the statistical mean value for separately cluster in the group with adjacent mean after segmenting the image through categorizing each pixel. It stages apprehensive in the K-Means procedure which are specified below:

- a. Handpicked K primary clusters $z_1(1), z_2(1), \dots, z_K(1)$
- b. Kth recursive stage, proceeds the samples amongst k clusters specified beneath $x \in C_j(k)$ if $\|x - z_j(k)\| < \|x - z_i(k)\|$ For $i = 1, 2, \dots, k, i \neq j$, wherever, $C_j(k)$ indicates the payment of samples those cluster center is $z_j(k)$
- c. Achieve the fresh cluster centers $z_j(K+1)$, $j = 1, 2, \dots, k$, so that the Euclidean distance from points in $C_j(K)$. Thus, ground-breaking cluster is specified by: $Z_i(k+1) = \frac{1}{N_j} \sum x \in C_j$ $X_j = 1, 2, \dots, k$. where N_j is the quantity of examples in $C_j(k)$. If $z_j(k+1)$, $j = 1, 2, \dots, k$, the calculation will be congregated at the finale else go to stage 2.

Afterward kidney MRI image segmentation, it may catch out borders of the image with canny edge detection. Afterward, this catch out marking of the image and lastly precise position of the tumor within the image.

Benefits with K-Means procedure:

- It will have all times K clusters
- In each cluster it will have all times at least one item
- Clusters do not overlay and are non- hierarchical.

Restrictions with K-Means procedure:

- This will be at all times ended
- At all times coming back K digit of clusters

- This is thoughtful to noise
- This necessitates extraordinary arrangement for minimization of energy.

2.2 Fuzzy C-Means clustering (FCM)

Fuzzy-C Means stays spontaneous method which is efficiently utilized in MRI images due to objective documents and image segmentation. Fuzzy C-Means method tags the pixels with separate groups of values of data interested in bunches. Procedures which uses fuzzy segmentation retain extra information from the inventive images than compact techniques of segmentation (Pham, 2003). Fuzzy C-Means is established on classification of fuzzy pixel into precise areas, those fits into one course of pixels. FCM permits pixels to suitable onto numerous lessons taking unpredictable membership degrees. These kind of investigation provides humble presentation with a quantity of segmentation with real time data that is utilized frequently cutting-edge MRI (Christ, C.J. et al, 2011). The membership degree is utilized to gather pixels with decent rate of sorting. It benefits the external to meeting at the points which uses membership function. Inhomogeneity piece do not support in the whole medical (Kannan, 2005; Alizadeh et al., 2008).

Fuzzy C-Means (FCM), a method of barrier into single slice with evidence from double or extra portions. Objective function minimization is specified through:

$$J = \sum_{j=1}^N \sum_c i = 1 \mu_{ij}^m \|X_j - V_i\|^2 \quad (1)$$

Now, u_{ij} designates the pixel of membership function x_j inside the i th cluster, v_i specifies i th cluster centre and m is the ambiguity rate that is reserved as 2.

When pixel is nearby to centroid, the cost function is reduced who has maximum values of function of membership and which has least values of membership function are assign to distant pixel commencing the centroid. Therefore, the function of membership provides pixel probability goes to specific cluster. The procedure depends on the extent of space among pixel and separable group taking the centroid through the domain of feature of the image.

The grade of function of membership and cluster centres stay produced with new values for each time by utilizing calculation:

$$\mu_{ij} = \frac{1}{\sum_{k=1}^c \left(\frac{\|x_j - v_i\|}{\|x_j - v_k\|} \right)^{\frac{2}{m-1}}} \quad (2)$$

And:

$$V_j = \frac{\sum_{i=1}^N u_{ij}^m X_j}{\sum_{i=1}^N u_{ij}^m} \quad (3)$$

Now $u_{ij} \in [0, 1]$. During early phase each bunch center of FCM meets to a definite v_i , that provide burden topic of the function of cost. Fact of conjunction stands recognized with distinguishing variations with function of membership through cluster centroid at 2 repetition phases. An important piece of MRI image with together pixels take similar type standards and the possibility that the similar cluster is vast however, these relationship of spatial is important on clustering, this is not functional on a traditional FCM procedure.

2.3 Spatial FCM

Preparation of pixels in spatial field stands specified toward grow spatial domain evidence for example:

$$h_{ij} = \sum_{k \in NB(x_j)} (X_j) u_{ik} \quad (4)$$

Anywhere, NB (x_j) symbolizes rectangular kernel centred with pixel x_j in the image. A 3*3 kernel is executed for these techniques. Now, the function h_{ij} signifies coincidental of receiving the pixel x_j fit into i th cluster. The h_{ij} of a pixel on behalf of a cluster stands enormous once common of its neighbourhood partaking the alike cluster. The h_{ij} is announced interested in relationship grade for example charts:

$$U_{ij} = \frac{u_{ij}^p h_{ij}^q}{\sum_{k=1}^c u_{kj}^p h_{kj}^q} \quad (5)$$

Two comparative parameters are used as p and q . Those constraints consolidate the comparative significance of together selection functions. Using the part of homogeneity, the h_{ij} reinforce the actual association and the clustering consequences continue persistent. Nevertheless, with the case of a pixel through noise, these calculation shrinks the worth of a cluster with noise using the tags of its cover pixels. Therefore, not matching confidential pixels with area of noise or incorrect blobs may be forbidden. It is a double based method. In the initial repetition, the function of participation in the domain of frequency is premeditated. In the succeeding repetition, degree of the function of membership of apiece pixel is plotted to the domain with pixel and the h_{ij} is at that time assessed. The FCM repetition remains through a renewed function of membership till resolution congregates. The repetition pauses once the transformation among dual cluster working extreme for double consecutive repetition procedure is a smaller amount of a threshold ($\epsilon = 0,02$). Lastly, the resolution is touched, defuzzification is executed to allocate pixel to a precise cluster where the degree function is utmost.

Afterward kidney MRI image segmentation, it may catch out borders of the image with canny edge detection. Afterward, this catch out marking of the image and lastly precise position of the tumor within the image.

FCM procedure benefits:

- This delivers extra meticulous statistics than typical “rigid” grouping
- In conventional process, the classes number is less than unsupervised classification

FCM procedure restriction:

- It is challenging to select the constraints p and q for different kidney MRI image.
- Challenging the usages of outliers.

3. INVESTIGATIONAL OUTCOMES

With MATLAB modelling, 2 kidney MRI images are deliberated to authenticate the projected procedure. It is produced with Fuzzy C-means algorithm. Algorithm performance stays matched using K-Means methods in relations of time complexity, noise and Quality metrics of individually kidney MR images.

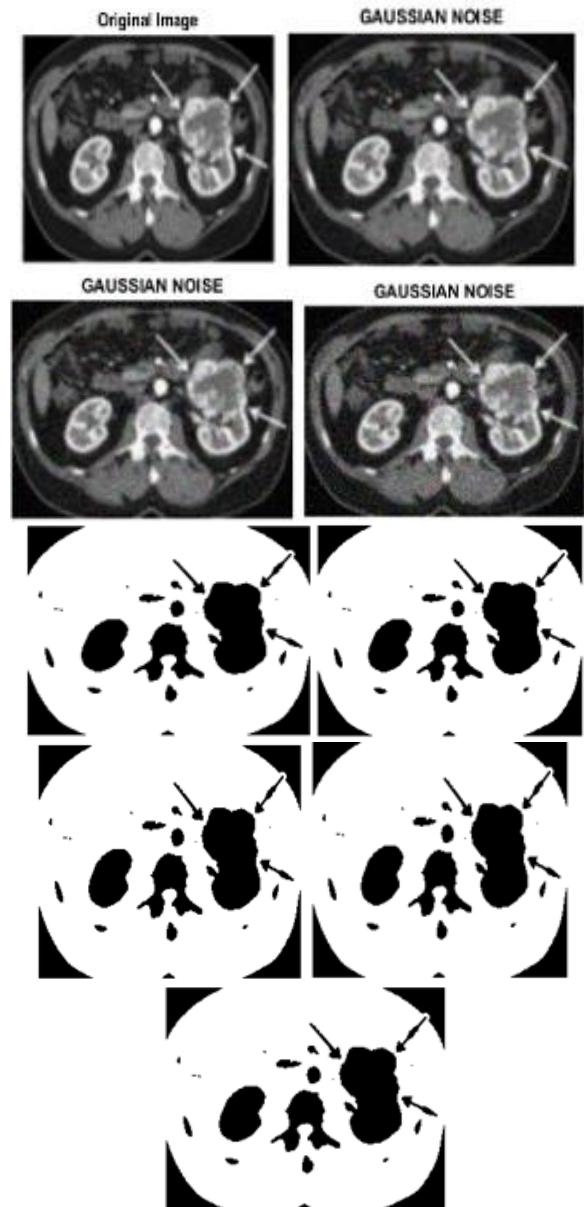
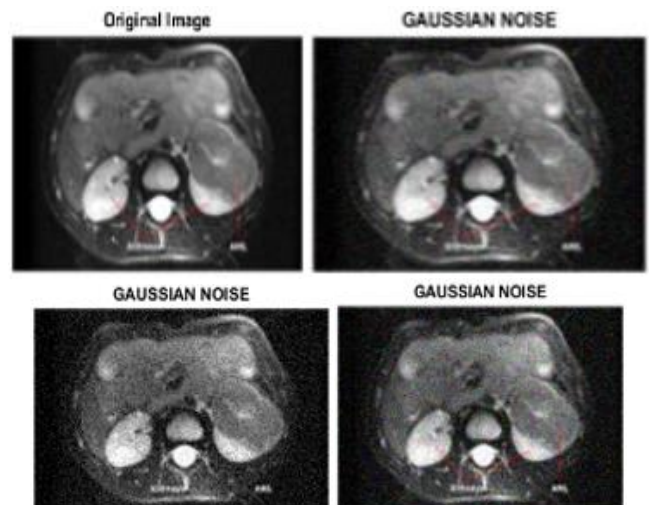


Figure 1. Image segmentation of kidney MR image-(a) original image, (b), (c) and (d) SNR of 3, 5 and 7% of Gaussian noise images correspondingly; (e), (f) and (g) equivalent segmented tumor images with K-Means technique correspondingly; (h), (i) and (j) equivalent segmented images of tumor with Spatial Fuzzy algorithm correspondingly.



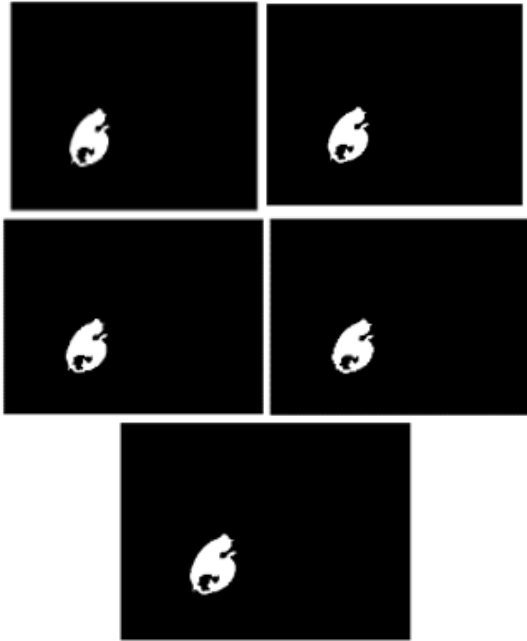


Figure 2. Image segmentation of kidney MR image-(a) original image, (b), (c) and (d) SNR of 3, 5 and 7% of Gaussian noise images correspondingly; (e), (f) and (g) equivalent segmented tumor images with K-Means technique correspondingly; (h), (i) and (j) matching segmented images of tumor with Spatial Fuzzy algorithm correspondingly

The segmentation presentation is assessed by expending unbiased segmentation assessment standards founded on Jaccard Coefficient (JC), Dice Coefficient (DC) formulas are known beneath:

Assume x and y are specified ground accuracy tumor and output images of tumor:

$$JC = \frac{|x \cap y|}{|x \cup y|} = \frac{a}{a+b+c}$$

$$DC = 2 * \text{jaccard} (x,y) / (1 + \text{jaccard} (x,y))$$

$$\text{Peak Signal to Noise Ratio (PSNR): } 10 \log_{10} \left(\frac{MAX1}{\sqrt{MSE}} \right)$$

$$\text{Mean Square Error (MSE): } \frac{\|X-Y\|^2}{N}$$

$$\text{MAXERR: } \sum_{i=1}^n f(y_i) (x_i - x_{i-1})$$

L2RAT: Proportion of the square off model of the image approximation toward the participation image.

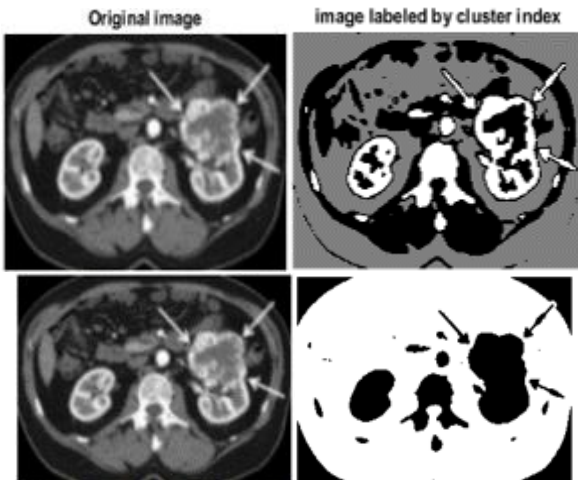


Figure 3. Image segmentation of the first kidney MR image – (a) original image; (b), (c), (d) imgs using boundary, label, segmentation, and tumor segmentation correspondingly by K- Means technique; (e), (f), (g) imgs using sboundary, label, segmentation and tumor segmentation correspondingly by Fuzzy C-Means procedure

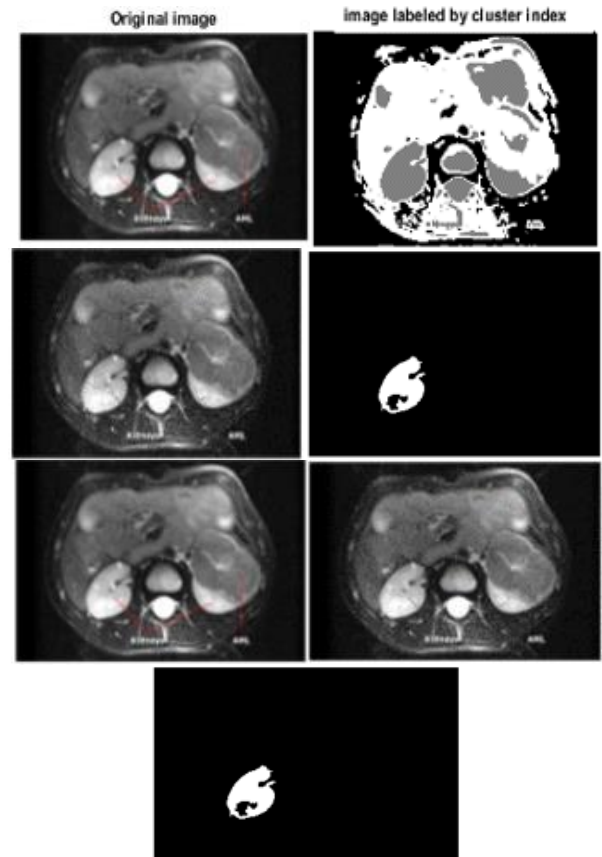


Figure 4. Img segment of the second kidney MRI image – (a) ori img; (b), (c), (d)imgs using boundary, label, segmentation, and tumor segmentation correspondingly by K- Means technique; (e), (f), (g) imgs using sboundary, label, segmentation and tumor segmentation correspondingly by Fuzzy C-Means procedure

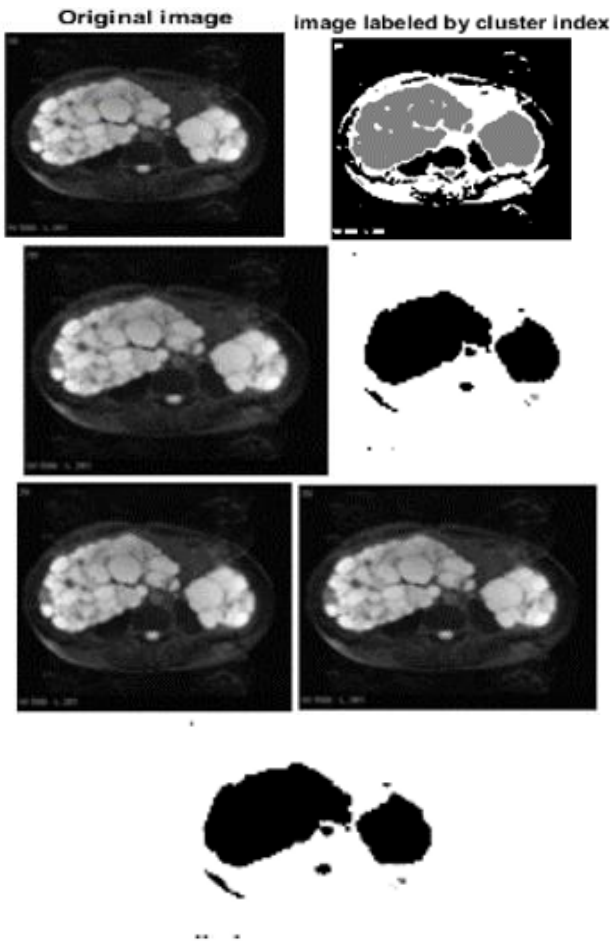


Figure 5. Img segment of the third kidney MRI image – (a) ori img; (b), (c), (d) imgs using boundary, label, segmentation, and tumor segmentation correspondingly by K- Means technique; (e), (f), (g) imgs using sboundary, label, segmentation and tumor segmentation correspondingly by Fuzzy C-Means procedure

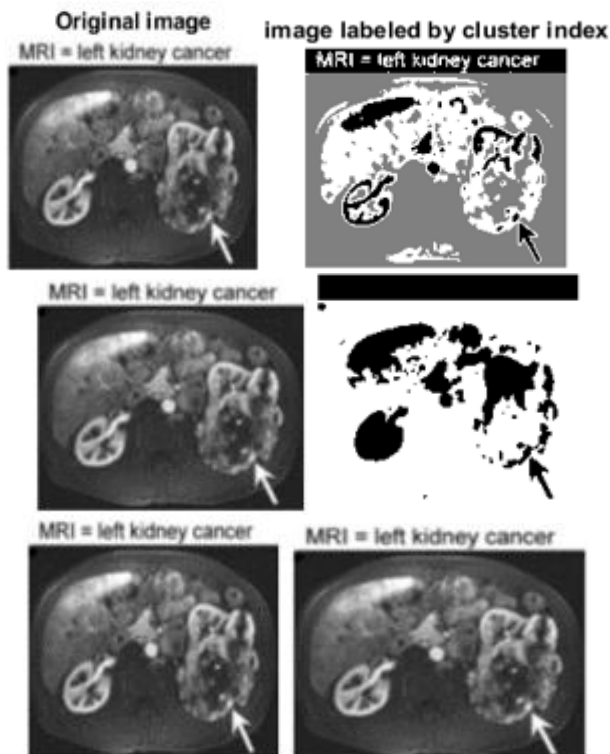


Figure 6. Img segment of the fourth kidney MRI image – (a) ori img; (b), (c), (d) imgs using boundary, label, segmentation, and tumor segmentation correspondingly by K- Means technique; (e), (f), (g) imgs using sboundary, label, segmentation and tumor segmentation correspondingly by Fuzzy C-Means procedure

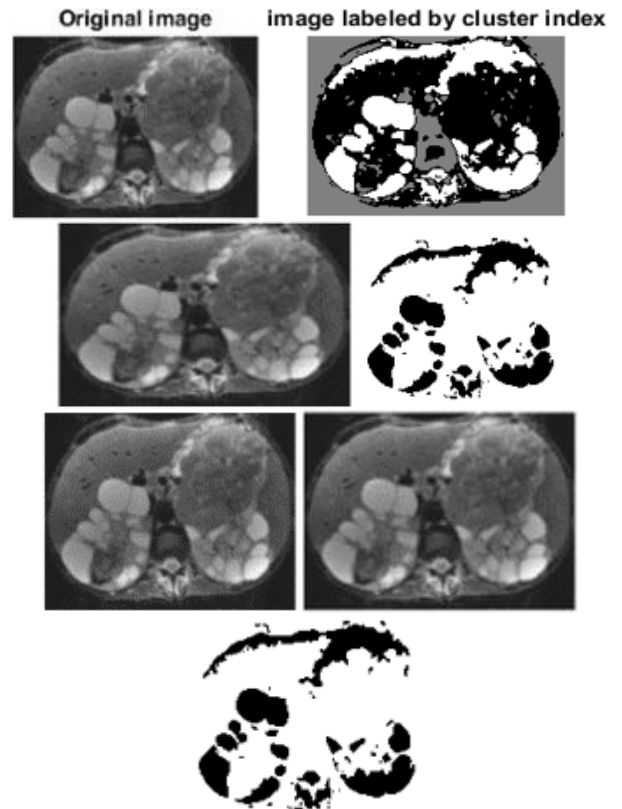


Figure 7. Img segment of the fifth kidney MRI image – (a) ori img; (b), (c), (d) imgs using boundary, label, segmentation, and tumor segmentation correspondingly by K- Means technique; (e), (f), (g) imgs using sboundary, label, segmentation and tumor segmentation correspondingly by Fuzzy C-Means procedure

4. DISCUSSIONS

Two dissimilar kidney MR Images is displayed by Figure. 1 and 2 which are deliberated toward authenticate the procedure. The initial kidney MRI image with dimension (185*165) is presented by Figure. 1. SNR 3, 5 and 7% of the Gaussian noise images are presented correspondingly by the Figure.1. (b), (c) and (d). After relating K-Means procedure for these kidney MRI images, outcomes therefore achieved are presented separately in Figures1. (e), (f) and (g). This is witnessed that the enactment of the procedure progressively worsens through escalation by power of noise. The outcomes gained with using Fuzzy C-Means technique in this kidney

MRI image is planned separately by Figure (h), (i) and (j). In this technique too, algorithm performance progressively worsens due to upturn with power of noise, nevertheless, segmentation outcome is extra precise plus satisfactory which equally matched as achieved with the K-Means.



Figure 8. Jaccard Coeff of 5 variant kidney MRI images applying K-Means and FCM methods



Figure 9. Dice Coeff of 5 variant kidney MRI images applying K-Means and FCM methods



Figure 10. PSNR of 5 variant kidney MRI images applying K-Means and FCM methods



Figure 11. MSE of 5 variant kidney MR images applying K-Means and FCM methods



Figure 12. Maxerr of 5 variant kidney MRI images applying K-Means and FCM methods

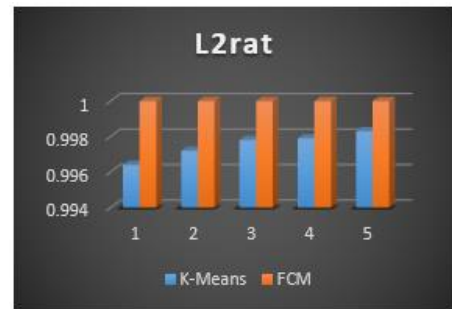


Figure 13. L2rat of 5 variant kidney MRI images applying K-Means and FCM methods

Fig. 8 through 13 demonstrations that K-Means technique contributes 68 toward 70% of correctness now altogether the circumstances with 5 kidney MRI images whereas Fuzzy C-Means provides 80 toward 90% of exactness in altogether the circumstances with 5 kidney MRI images correspondingly. After the beyond segmentation quality metrics, this can be undoubtedly realized that the model established by spending Fuzzy C-Means procedure provides superior outcomes than K-Means approaches.

The time complexity for individually to these approaches are too strongminded. It is observed that the time complexity drops for the event of Fuzzy C-Means procedure equally matched toward that of K-Means technique. The conforming values are correspondingly 0.6206, 0.92000 sec.

5. CONCLUSION

This presentation with diverse approaches for segmentation of image with kidney MRI is offered for these revisions. Projected Fuzzy C-Means procedure produce comparatively precise outcomes for all the circumstances of kidney MR image segmentation. Additional, the projected procedure congregates quicker than K-means approaches.

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