

A NOVEL UNSTEADY MODEL OF PREDICTING THE PRODUCTIVITY OF MULTI-FRACTURED HORIZONTAL WELLS

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ABSTRACT

Forecasting the productivity of hydraulic fractured horizontal wells precisely is vital to develop low permeability gas and oil fields. The presented paper is based on the instantaneous point source function and potential superposition principle, considering the non-uniform flow distribution and the variable mass linear flow in the fractures of a fractured horizontal well. In the study a dynamic model of couple reservoir seepage and the fluid flow in fractures was built using a spatial-time discretization technique, and a solution method was also introduced. The results revealed that when regarding the inflow to the fracture as uniform and neglecting the pressure drop in the fractures, there may be huge deviation in the productivity calculation of a fractured horizontal well. Neglecting the pressure drop in the fractures may lead to a relatively high calculated value as compared to the actual production. The flow exhibited as an unsteady flow in the early stage, with the fracture segments which were closer to the horizontal wellbore showing a higher flow flux, while others had a lower flow rate. As producing time increase, the hydraulic fracturing horizontal well came to a pseudo-steady state phase, the flow distribution in the fractures tended to be uniform and steady. The daily output of hydraulic fractured horizontal well increases as fracture conductivity increases and there is optimized fracture conductivity consistent with the reservoir permeability.

Keywords: Fractured horizontal well, Transient state, Point source function, Superposition, Flow distribution.

1. INTRODUCTION

As horizontal wells with multistage hydraulic fracturing has been proven to be the key technology for successful development of the finite oil and gas resources, it is meaningful to conduct studies on the productivity of fractured horizontal wells[1-4]. The first mathematical model for analyzing productivity of horizontal wells intersecting fractures was presented by Giger [5]. For the cases of short and long horizontal wells, flow in the rock matrix and fractures were formulated separately respectively, and then combined to obtain an equation of radial flow for the whole flow path from external boundary to wellbore. Gringarten [6] considered the uniform flux and infinite conductivity fractures intercepted by a vertical wellbore, and used the Green function for the transient flow of a slightly compressible fluid in a homogeneous and anisotropic porous medium. Joshi [7] pointed out that in most fracture jobs it is difficult to obtain infinite conductivity. Mukherjee[8] developed a simplified steady-state approach to calculation of the number of infinite conductivity fractures equivalent to a drain hole on the basis of the inflow performance relationship suggested by Joshi [9] with Prats' [10] correlation for dimensionless wellbore radius. Raghavan et al [11] used the effective wellbore radius concept to represent the fractures, presenting a steady flow solution based on uniform flux along the fracture length to calculate the productivity of a horizontal

well with multiple transverse hydraulic fractures in a circular and homogeneous drainage area, producing oil under steady-state conditions. Wei [12] suggested an analytical model for a pseudo-steady state productivity index of a horizontal well with multiple transverse hydraulic fractures. In which, the artificial fractures were treated as the fracture's skin. Guo [13] suggested that previous Inflow Performance Relationship (IPR) equations for hydraulic horizontal wells were not accurate due to the unrealistic assumptions used. They proposed a more rigorous mathematical model for predicting performance of vertical and horizontal wells with intersecting fractures. In the more rigorous fractured horizontal well models, a fully penetrating and circular fracture has been assumed, flow in the fractures is taken into account but the circular geometry of the fracture imposes radial flow within the fracture, which is one step closer to the reality in fractured reservoirs. Lei [14] presented a model for fractured wells in low permeability reservoirs which considered the coupling of formation seepage and horizontal flow in the wellbore by using the complex potential theory and potential superposition principle. For the flow in the fracture, considering the length of the fracture is larger than that of the wellbore radius, and the fluid with uniform flux distribution along the fracture accumulates around the borehole as radial fluid flow. Lian [15], based on Green's functions and Newman's product principle, derived a pressure drop formula for considering simultaneous

production of fractures and horizontal wellbores in unsteady states. For the flow in the fracture, with consideration that the cross-sectional area of fractures is larger than that of wellbores, the flow from the edge of the fractures to the wellbore can be treated as radial flow, ignoring gravity.

In general, assuming different fracture geometries may lead to different fracture flow rates. If the fracture is a long rectangle instead of radial flow, it would result in linear flow being dominant in the fracture. Because the estimation of rate is strongly affected by specific characteristics of certain fracture conductivity and half length, the production model should take into account the correct fracture geometry. Larsen [16-17] established a model of fractured horizontal wells in an unsteady state based on numerical integration of Laplace transformed point-source solutions for unbounded reservoirs in three dimensions. Laplace transformed solutions for uniform-flux fractures in unbounded 3D reservoirs are first developed. Raghavan [18] used vertical well fracture models [19-20] with uniform-flux or infinite-conductivity rectangular fractures and the fracture communicates with the wellbore over its entire height to approximate the pressure-transient responses of fractured horizontal wells. Wang [21], according to the principles of potential superposition and continuity, developed a coupling model of variable mass flow in fractures and percolation in reservoir, which was established under steady state conditions.

So far, former scholars have investigated the theoretical models based on the reservoir seepage coupling with artificial fracture flow, but all the above approaches may be considered to be less rigorous because the description of the fluid flow inside the fracture is not comprehensive, but is deduced whilst assuming the flux to be uniform along the fracture. In fact, the interference among the fractures would result in non-uniform flux distribution along the fractures. In this study, a general solution for the rate calculation of a horizontal well intersected by finite conductivity vertical fractures was presented. Based on non-steady flow theory, potential principles, superposition principle and time superposition principle, a new method of predicting the productivity of fractured horizontal wells with the consideration of the non-uniform flux distribution along the fracture is presented, which produces more reasonable results. The factors influencing the productivity and field applications are presented in this article also.

2. ASSUMPTIONS

In order to set up the mathematical model, some proper assumptions should be made for the mathematical model:

(1) The oil reservoir is closed at the top and bottom. The infinite anisotropic reservoir has a constant height h , porosity ϕ , and permeability K . At the initial time $t+=0$, the pressure is uniform throughout the oil reservoir and is equal to p_i .

(2) The fractured horizontal well locates in the center of oil reservoir (Figure 1). The well is parallel to the y -axis with length L , the number of fractures is N . The fractures are perpendicular to wellbore and equally or unequally spaced from each other, the fractures length x_f are equal or unequal with each other, and fully penetrate the reservoir. The width is w , length is x_f and height is h in y , x and z directions respectively.

(3) Single-phased and compressible fluid flows in the oil reservoir. The compressibility coefficient c_t and viscosity μ

are constant. The pressure drop of the fluid flow in the horizontal well bore is ignored.

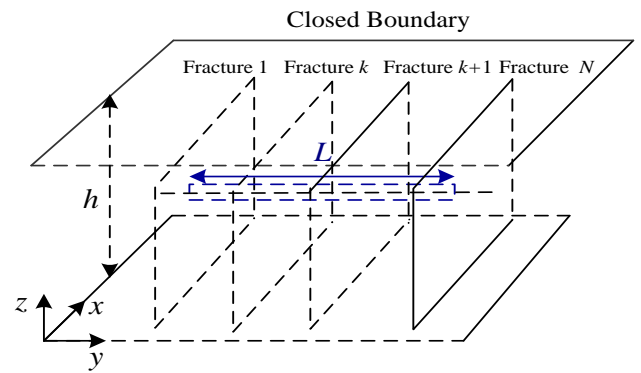


Figure 1. The physical model of fractured horizontal well in an infinite tight oil reservoir

3. MATHEMATICAL MODEL

3.1 Reservoir seepage model

Since the fractures fully penetrate the reservoir, the hydraulic horizontal well fractures' flow system can be simplified as a radial flow within the plane reservoir, and each fracture can be considered as being composed of microline sinks points [14,22-23]. For convenience, the two monoplanes of the fracture are divided into n_s equal segments and with a length of $\Delta x_{fk} = x_{fk} / n_s$, each portion is considered as one sink point as shown in Figure 2.

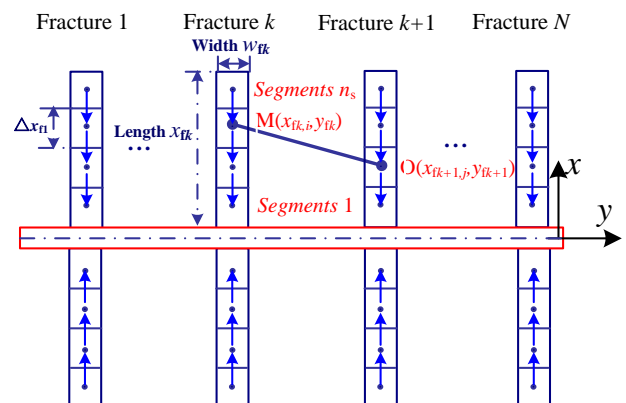


Figure 2. The sectional schematic of the fracture segments in the infinite conductivity model

The formation pressure rearranges because of the appearance of the artificial fractures. The production of the fractured horizontal wells changes and keeps declining over the production duration. However, if the time interval section is taken as small as possible, the flow can be treated as constant. Under the Cartesian coordinates plane, based on the pressure drawdown equation of the flow with constant rate of an infinite large sink point, the pressure drawdown of the point $O(x_{fk+1, \beta}, y_{fk+1})$ caused by sink points $M(x_{fk, j}, y_{fk})$ is as follows [24]:

$$p_i - p_{ik+1,j} = \frac{q_{fk,i} \mu B}{4\pi K h} \left\{ -Ei \left(-\frac{(x_{fk,i} - x_{fk+1,j})^2 + (y_{fk} - y_{fk+1})^2}{4\eta \Delta t} \right) \right\} \quad (1)$$

Where: p_i is the initial pressure of the oil reservoir, MPa; $p_{ik+1,j}$ is the pressure of j th fracture segment in the $k+1$ th fracture, MPa; $q_{fk,i}$ is the oil flow rate of the i th fracture segment in the k th fracture at $t=0+$; B is the fluid volume factor; $(x_{fk,i}, y_{fk})$ are the center coordinates of i th fracture segment in the k th fracture; $(x_{fk+1,j}, y_{fk+1})$ are the center coordinates of j th fracture segment in the $k+1$ th fracture; K is the permeability, D; h is the reservoir thickness, m; η is transmissibility to diffusivity, m^2/ks ; $\eta = K/\mu c \phi$; μ is the viscosity, $mPa \cdot s$; c is the total compressibility, MPa^{-1} ; and ϕ is the porosity, decimal number; Δt is the production duration time, ks .

When there are ns equal segments on the i th fracture, the total pressure drops from the i th fracture at time t and location $(x_{fk+1,j}, y_{fk+1})$ is given as:

$$p_i - p_{ik+1,j} = \sum_{i=1}^{2ns} \frac{q_{fk,i} \mu B}{4\pi K h} \left\{ -Ei \left(-\frac{(x_{fk,i} - x_{fk+1,j})^2 + (y_{fk} - y_{fk+1})^2}{4\eta \Delta t} \right) \right\} \quad (2)$$

Based on the superposition principle of the potential, the interaction between segments can be taken into account by superposition of pressures in space.

$$p_i - p_{ik+1,j} = \sum_{k=1}^N \sum_{i=1}^{2ns} \frac{q_{fk,i} \mu B}{4\pi K h} \left\{ -Ei \left(-\frac{(x_{fk,i} - x_{fk+1,j})^2 + (y_{fk} - y_{fk+1})^2}{4\eta \Delta t} \right) \right\} \quad (3)$$

3.2 Fracture flow model

Assuming a one-dimensional linear inflow along the fracture into the wellbore, we can compute the friction caused by the fluid when flowing within the fracture based on the planar Darcy flow (Figure 3). For example, to compute the pressure drop caused by the fluid flow within the fracture from the j th segment (point $O_{fk+1,j}$) of $k+1$ th fracture to the well bore (point O_0) the calculation is as shown on the following page [25].

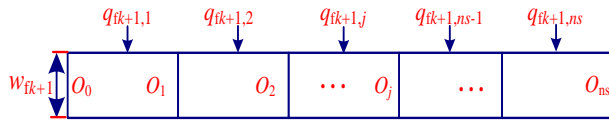


Figure 3. Schematic representation of flow units within a fracture

$$\begin{aligned} \Delta p_{f,j-0} &= \frac{\mu B}{2k_f w_{fk+1} h} \Delta x_{fk+1,1} q_{fk+1,1} + \frac{\mu B}{2k_f w_{fk+1} h} (\Delta x_{fk+1,1} + \Delta x_{fk+1,2}) q_{fk+1,2} + \dots \\ &+ \frac{\mu B}{2k_f w_{fk+1} h} (\Delta x_{fk+1,1} + \Delta x_{fk+1,2} + \dots + \Delta x_{fk+1,j}) q_{fk+1,j} \\ &+ \frac{\mu B}{2k_f w_{fk+1} h} (\Delta x_{fk+1,1} + \Delta x_{fk+1,2} + \dots + \Delta x_{fk+1,j}) q_{fk+1,j+1} + \dots \\ &+ \frac{\mu B}{2k_f w_{fk+1} h} (\Delta x_{fk+1,1} + \Delta x_{fk+1,2} + \dots + \Delta x_{fk+1,j}) q_{fk+1,ns} \\ &= \frac{\mu B}{2k_f w_{fk+1} h} \left\{ \sum_{i=1}^j \left(q_{fk+1,i} \sum_{j=1}^i \Delta x_{fk+1,j} \right) + \sum_{n=j+1}^{ns} \left[q_{fk+1,n} \left(\sum_{i=1}^j \Delta x_{fk+1,i} \right) \right] \right\} \quad (4) \end{aligned}$$

In the formula, K_{fk+1} is the permeability of the $k+1$ th fracture, D; w_{fk+1} is the width of the $k+1$ th fracture, m.

3.3 Transient reservoir-fracture coupled flow model

Due to the way in which the oil flow from the reservoir into the well bore can be separated into two different parts, Equation (3) and (4) have set up the formula correspondingly. The pressure node for each fracture segment is placed at the center of that segment, so the nodal pressure represents the reservoir pressure on the surface of the fracture that is in contact with the reservoir, the pressure continuity equation can then be established on the basis of Eq.(3) and (4). Since it has been assumed that the horizontal wellbore is infinitely conductive, the pressure is homogenous throughout the wellbore at any given time. In order to keep the pressure continuity in the oil reservoir and wellbore, Eq.(5) is established:

$$P_{fk+1,wf} = P_{wf} \quad (5)$$

Where: $p_{fk+1,wf}$ is the flow pressure of the well bottom, MPa;

Combining Eq.(3), (4) and (5) creates the reservoir-fracture coupled flow model of j th segment of the $k+1$ th fracture as follows:

$$\begin{aligned} p_i - p_{wf} &= \sum_{k=1}^N \sum_{i=1}^{2ns} \frac{q_{fk,i} \mu B}{4\pi K h} \left\{ -Ei \left(-\frac{(x_{fk,i} - x_{fk+1,j})^2 + (y_{fk} - y_{fk+1})^2}{4\eta \Delta t} \right) \right\} \\ &+ \frac{\mu B}{2k_f w_{fk+1} h} \left\{ \sum_{i=1}^j \left(q_{fk+1,i} \sum_{j=1}^i \Delta x_{fk+1,j} \right) + \sum_{n=j+1}^{ns} \left[q_{fk+1,n} \left(\sum_{i=1}^j \Delta x_{fk+1,i} \right) \right] \right\} \quad (6) \end{aligned}$$

There is no fluid flowing from other parts of the well bore except the fracture section, so the total production of the fractured horizontal well can be calculated as:

$$Q = \sum_{k=1}^N \sum_{i=1}^{2ns} q_{fk,i} \quad (7)$$

With a certain p_{wf} , the model with Eq.(6) and (7) is able to calculate the flow rate of every fracture segment and fracture d horizontal well.

At the time Δt , we can write:

$$\Delta p_{f1,1} = q_{f1,1} F_{11,11} + q_{f1,2} F_{12,11} + q_{f1,3} F_{13,11} + \dots + q_{fN,2ns} F_{N2ns,11} \quad (8)$$

Where $\Delta p_{f1,1} = (p_i - p_{f1,1}(x, y))$ and gives the pressure drop at the pressure node of the 1st segment in the 1st fracture due to the flow from itself and all the other fracture segments. The location (x, y) is a point on the fracture circumference. The term $F_{N \times 2ns, 11}$ in the above equation stands for the effect of 1st fracture segment on itself, where $N, 2ns$ is the segment under consideration. Similar equations can be written for all other segments.

$$\left\{ \begin{array}{l} q_{f1,1} F_{11,11} + q_{f1,2} F_{12,11} + q_{f1,3} F_{13,11} + \dots + q_{fN,2ns} F_{N \times 2ns, 11} = \Delta p_{f1,1} \\ q_{f1,1} F_{11,12} + q_{f1,2} F_{12,12} + q_{f1,3} F_{13,12} + \dots + q_{fN,2ns} F_{N \times 2ns, 12} = \Delta p_{f1,2} \\ q_{f1,1} F_{11,13} + q_{f1,2} F_{12,13} + q_{f1,3} F_{13,13} + \dots + q_{fN,2ns} F_{N \times 2ns, 13} = \Delta p_{f1,3} \\ \dots \\ q_{fN,2ns} F_{11, N \times 2ns} + q_{f1,2} F_{12, N \times 2ns} + q_{f1,3} F_{13, N \times 2ns} + \dots + q_{fN,2ns} F_{N \times 2ns, N \times 2ns} = \Delta p_{fN, 2ns} \end{array} \right. \quad (9)$$

Where:

$$F_{ki, k+1j}(\Delta t) = \frac{\mu B}{4\pi K h} \left\{ -Ei \left(-\frac{(x_{fk,i} - x_{fk+1,j})^2 + (y_{fk} - y_{fk+1})^2}{4\eta \Delta t} \right) \right\}$$

The unknowns in this problem are $N \times 2ns$ number of q 's at the nodes of the $N \times 2ns$ segments. A total of $N \times 2ns$ equations are needed to obtain a solution to the system of equations. By taking the pressure difference between wellbore and every other node, we can form $N \times 2ns$

equations. Because of the wellbore infinite conductivity assumption, pressure is constant in the well bore.

Solving the system of $N \times 2ns$ equations given above, the q 's from each node can be calculated for the first time step. By applying superposition in time, these solutions can be marched through time. It is assumed that all time steps are of equal length and are equal to Δt . Therefore, for the j th segment of the $k+1$ th fracture at $t = m\Delta t$ is:

$$p_i - p_{fk+1,j}(m\Delta t) = \sum_{k=1}^N \sum_{i=1}^{2ns} \left\{ q_{fk,i}(\Delta t) F_{ki, k+1j}(m\Delta t) + \sum_{g=2}^m [q_{fk,i}(g\Delta t) - q_{fk,i}((g-1)\Delta t)] F_{ki, k+1j}[(m-g+1)\Delta t] \right\} \quad (10)$$

Solving the above set of equations, as was done for the first time step, can yield the flow rate distribution along all the fracture divisions at any time step. This procedure can be repeated for all the time steps.

4. CASE STUDY AND SENSITIVITY ANALYSIS

A computer program was designed to test this model and compare with uniform flux and the infinite-conductivity fractured horizontal well mode. The basic parameter values of this case study are shown in Table 1.

Table 1. Basic parameters of a real example

Parameter	Data
horizontal well length, L_f	400 m
Reservoir Height, h	12m
Permeability, K	0.0035 D
Porosity, ϕ	10%
Total Compressibility, ct	0.00035 MPa-1
Reservoir Initial pressure, p_i	30 MPa
Formation Volume Factor, B	1.084
Oil Viscosity, μ	8 mPa·s
Oil Density at Reservoir Conditions, ρ	870 kg/m ³
Bottom-hole pressure, p_{wf}	25 MPa
Well Diameter, r_w	0.0889 m
Fracture permeability, K_f	30 D
Fracture width, w	5.0 mm
Fracture length, x_f	75 m
Fracture numbers, N	4

The case study was run with the well bottom flow pressure constraint. Table 2 presents the fracture and daily production comparison with different models and the actual production. Model 1 is based on non-uniform flow distribution and

infinite conductivity within the fracture, Model 2 is the proposed model, and Model 3 is based on uniform flow distribution and finite conductivity within the fracture[14,22].

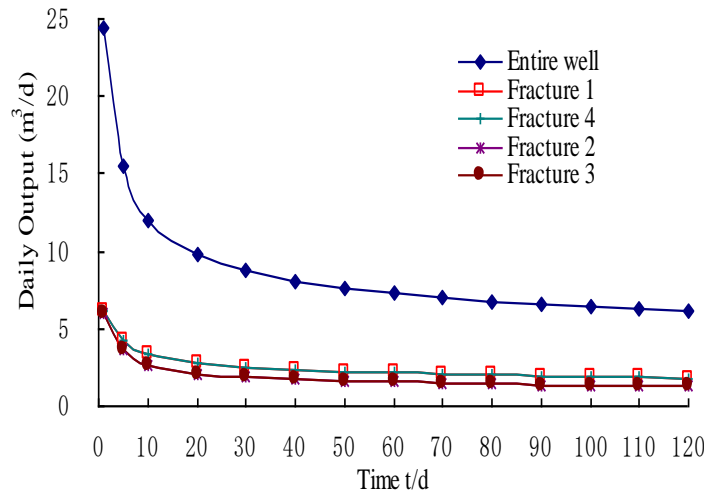
Table 2. Comparison of Simulated solution and the actual productivity

Parameters	Productivity (m ³ /d)											
	Model 1			Model 2			Model 3			Actual output		
	1 d	10 d	120 d	1 d	10 d	120 d	1 d	10 d	120 d	1 d	10 d	120 d
Fracture 1	14.83	5.74	2.63	6.15	3.35	1.88	5.65	3.24	1.87	/	/	/
Fracture 2	14.39	3.85	1.35	6.05	2.67	1.32	5.60	2.64	1.36	/	/	/
Fracture 3	14.39	3.85	1.35	6.05	2.67	1.32	5.60	2.64	1.36	/	/	/
Fracture 4	14.83	5.74	2.63	6.15	3.35	1.88	5.65	3.24	1.87	/	/	/
Total	58.44	19.19	7.97	24.41	12.04	6.41	22.49	11.75	6.45	24.22	11.85	6.32

This result shows that the computational results with this proposed model which with non-uniform flux and finite conductivity is closer to the actual productivity. While Model 1 calculates the 1st day production is 58.44 m³/d, which far exceeded the actual value, this indicated that the impact of pressure loss within the fracture cannot be omitted. The results also show that the uniform flux case predicted less productivity than the non-uniform flux case. The reason for this is that in order to obtain the same flux at the center of the

fracture as at its ends, for the uniform flux case, the fracture needs extra pressure drop to force some of the fluid to come to the center which would otherwise go to its ends. The ends of the fracture, being exposed to a larger portion of the reservoir than the center, gain access to reservoir fluids more easily.

4.1 Daily output of fracture and well with time

**Figure 4.** Daily production over time

As shown as Figure 4, the daily output of fractured horizontal wells decreases rapidly from a high value at the beginning of production and then remained steady at a constraint of bottom hole pressure. This is because, in the early stage when a fractured horizontal well starts to produce, the pressure waves have not spread to most of the flow regions, and the fluid is merely flowing linearly from the bedrock around the fracture towards the fracture. When the pressure wave reaches the outer boundaries of the fractures, the flow enters the quasi-steady state with the production gradually tending toward steady output. Compared to the output of fractures in different positions, the flow rate is

approximately equal in each fracture at the beginning, and the gap between fractures is growing in the unsteady stage. The fracture output of the two ends (Fracture 1 and Fracture 4) is higher than the center (Fracture 2 and Fracture 3). That is, the outermost fractures have a larger drainage area and the inner fractures' drainage areas exist in the interface between fractures. It also demonstrates that the fractures of the two ends have a protective screening effect on the middle fractures. So, an effective method of increasing production is to increase the fracture length of the two ends.

4.2 Flow rate distribution of different models

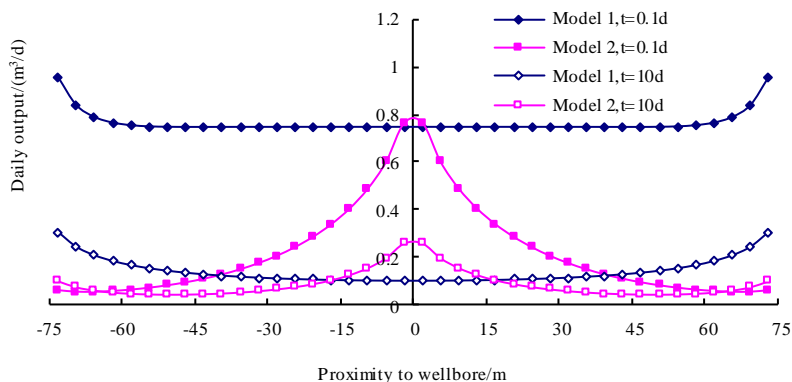


Figure 5. Flow rate distribution

The flux distribution along the discrete elements of Fracture 1 at different times ($t = 0.1$ d, $t = 10$ d) with Model 1 and Model 2 are shown in Figure 5. As Model 1 did not take into consideration the pressure drop within the fracture, the flux distribution at $t = 0.1$ d was a “U-shape”, with the flow at the two ends being relatively high. At $t = 10$ d, due to interference within the fractured segments there was an increase in strength, further strengthening the non-uniform flow distribution within the fracture. Model 2 considered the non-uniform flow rate distribution and finite conductivity along the fracture. The distribution of flow rate was wave-like in shape due to the influence of fractures. Therefore, the closer the fracture segment is to the wellbore, the lower the flow rate in the fracture segment. The flow rate of fractures is symmetrical around the wellbore.

In the early stage $t=0.1$ d, the pressure was uniform throughout the oil reservoir and was basically the original reservoir pressure. The pressure along the fracture dropped as the distance to the wellbore decreased, leading to a higher output of the fracture segment that was closer to the wellbore. As time increased ($t = 10$ d), the mutual interference within the fractured segments caused the flow distribution within the fracture to tend towards uniformity. However, the pressure was lowest at the junction of fracture with the wellbore, resulting in the flow distribution within the fracture displaying a “double U-shape”.

4.3 Flow rate distribution with time

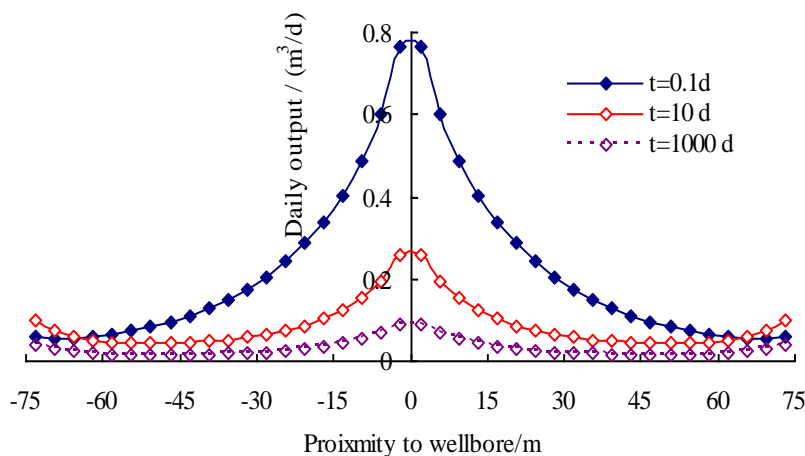


Figure 6. Flow rate distribution with time

The flow distribution of Fracture 1 at different times is shown in Figure 6. Assuming the fracture has finite conductivity, there is pressure drop along the fracture. With the pressure dropping as the distance to the wellbore was reduced, the flow rate of these fracture segments increased. Over time ($t = 10$ d), the reservoir pressure wave gradually diffused outwards, which caused the flux of the intermediate

segments to gradually decrease, while that at the two ends of the fracture the flux gradually increased. During the stable production stage ($t = 1000$ d), the characteristics of uniform fluid production were exhibited along the entire length of the fracture.

4.4 Flow rate distribution with fracture conductivity

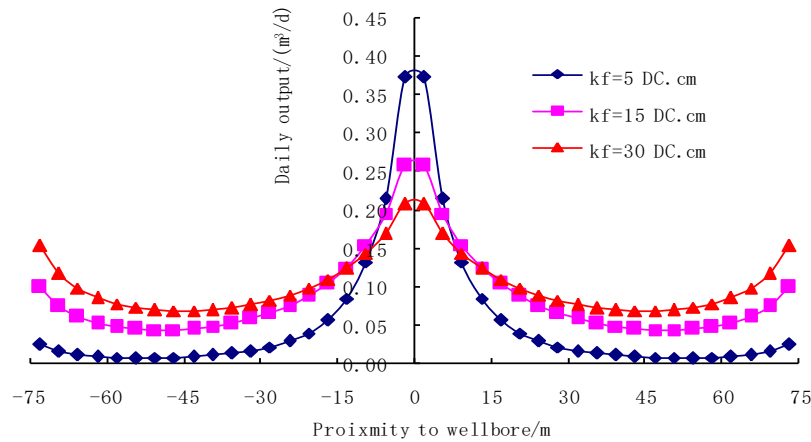


Figure 7. Flow rate distribution with fracture conductivity

Figure 7 illustrates the relationship between the flux distribution with the conductivity of Fracture 1 at time $t=10$ d. It can be seen that the in-flow of fracture segments increased closer to the well bore. The lower the conductivity, the more non-uniform the flux distribution along the fracture. At $t=10$ d, the daily outputs of the 1st fracture were 2.15 m³/d, 3.44 m³/d, 4.09 m³/d with different fracture conductivity of 5 DC.cm, 15 DC.cm and 30 DC.cm respectively. This shows that the daily output increased rapidly at the beginning under lower fracture conductivity, and when the conductivity increased to a certain value, the change of fracture conductivity has little influence on the flow rate. So, it is necessary to optimize the fracture conductivity consistently with the reservoir supply capability.

5. CONCLUSIONS

- (1) A reservoir/fractured horizontal well coupling model was established for finite conductivity considering the mutual interferences of fractures and segments under unsteady state conditions. The computational solution of the model was closer to the real output than previous models. Being a semi-analytical model, it does not suffer from numerical dispersion and grid sensitivities that result from numerical simulations.
- (2) The analysis shows that the flow rate is approximately equal in each fracture at the beginning and the gap between fractures grew in the unsteady stage. The fracture output of the two ends was higher than that of the center because of interference. It is therefore an effective method of increasing production to increase the fracture length of the two ends.
- (3) During the early non-steady state stage, the flux along the fracture exhibited a non-uniform characteristic: the flux increased as the fracture segment position moved closer to the well bore. As time increased, the mutual interference within the fractured segments caused the flow distribution within the fracture to tend towards uniformity.
- (4) The daily output increased rapidly with the conductivity under lower fracture conductivity, and once the conductivity had increased to a certain value, the change of fracture conductivity had little influence on the flow rate, providing an optimal value for a certain formation.

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