

Technological Trends in DL-Based 3D Digitization of Infrastructures by Using Point Clouds

Cuba Lizbeth^{1*} , Rodriguez Ciro² 

¹ Faculty of System Engineering, Universidad Nacional Mayor de San Marcos (UNMSM), Lima 15081, Peru

² Department of Software Engineering, Universidad Nacional Mayor de San Marcos (UNMSM), Lima 15081, Peru

Corresponding Author Email: lizabeth.cuba@unmsm.edu.pe

Copyright: ©2025 The authors. This article is published by IETA and is licensed under the CC BY 4.0 license (<http://creativecommons.org/licenses/by/4.0/>).

<https://doi.org/10.18280/isi.300323>

ABSTRACT

Received: 6 December 2024

Revised: 10 January 2025

Accepted: 20 January 2025

Available online: 31 March 2025

Keywords:

3D digitization, point cloud, deep learning, 3D object detection, semantic segmentation

This article addresses the challenge of 3D digitization using point clouds, an essential process for technological trends such as Building Information Modeling (BIM) and digital twins. The process of capturing three-dimensional geometries from point clouds generated by laser scanning is a costly and time-consuming task. The purpose of the study is to analyze how deep learning (DL) models can optimize this process in different types of infrastructures (industrial, transportation, construction, and public and social services). To this end, a methodology based on a systematic review and a bibliometric analysis of the scientific literature indexed in Scopus was employed, examining advanced models such as PointNet, PointNet++, ResPointNet++, and datasets like CLOI, PSNet5, and Pipework. The results highlight the effectiveness of AI in the automated handling of point clouds, although limited documentation was identified in its application to mining infrastructures. In conclusion, a DL model and specific datasets for the efficient processing of point clouds in the mining sector are identified and recommended, thus contributing to the advancement of 3D digitization in this sector.

1. INTRODUCTION

Scientific research on new digital technology trends in the architecture, engineering, and construction (AEC) sector has intensified, with Building Information Modeling (BIM) and Artificial Intelligence (AI) as leaders [1]. These trends can be employed as an essential pillar to drive the development of other digital technological trends that have advanced at a slower pace, such as digital twins and blockchain.

Despite the growing demand for digital twin technology in the industrial sector, its implementation faces significant challenges. One of the main challenges is the efficient management of the vast and critical engineering knowledge accumulated over decades, which is essential to ensure its proper integration and functioning.

The integration and effective use of this knowledge are fundamental to maximizing the potential of digital twins, enabling precise simulations and improving timely decision-making based on historical and real-time data [2].

In summary, this article highlights the importance of BIM technology, digital twins, and artificial intelligence (AI) as key pillars in 3D digitalization. It is crucial to highlight the close interdependence between BIM technologies, digital twins, and 3D digitization. To process BIM or capture existing infrastructures in 3D (which may differ from the original design), it is essential to use technologies such as point clouds or equivalents. However, the processing of point clouds requires handling large volumes of data, which demands the integration of advanced digital technologies, such as Big Data (BD). Likewise, to optimize processing times, it is essential to

resort to AI. Together, these technologies form an interdependent and complex ecosystem. In this context, the present article analyzes the advances in 3D digitalization driven by AI and proposes recommendations for the implementation of optimal models in the mining industry sector.

Currently, numerous industrial projects are still being carried out using 2D computer-aided design (CAD) tools, which is causing a delay in the migration towards 3D digitization for many types of infrastructures. According to [3], this shortcoming poses significant challenges in terms of design, maintenance, and optimization of infrastructures. The use of laser scanning technology for point cloud generation is fundamental in the design, repair, and expansion of infrastructures. 3D digitization significantly reduces the time required to collect data, decreases reliance on personnel, and lowers costs, as mentioned in [4].

Laser scanning technology is also used to measure and document the current conditions of infrastructures. However, the files containing these 3D point clouds are large and their handling is not straightforward, which highlights the importance of point cloud management, as noted in [5]. Fortunately, the most viable way to reduce costs and associated times is through the automation of the 3D modeling process using deep learning models, such as PointNet [6], PointNet++ [7], ResPointNet++ [8], or SE-PseudoGrid [9].

This is, to our knowledge, the first study on AI-based 3D digitization through point cloud processing that incorporates infrastructure types and key datasets. Moreover, considering the Peruvian context, no scientific works indexed in journals

like Scopus have been developed that address the industrial infrastructures of the mining sector. Therefore, this work provides relevant information, highlighting the models with the best performance and the most suitable datasets for mining industrial infrastructure.

The primary aim of this systematic review is to assess the technological implications of AI-driven 3D digitization through point cloud processing in the infrastructure sector, with a particular emphasis on the Peruvian mining context. To fulfill this aim, three specific objectives are addressed: (1) To evaluate the efficacy of AI models in the processes of point cloud segmentation and classification, concentrating on diverse categories of infrastructures, including industrial, transportation, construction, and utility sectors; (2) To identify and assess the most pertinent and accessible data sets related to each category of infrastructure, in order to ascertain the most appropriate options for the implementation of AI models; (3) To investigate and discuss both current and prospective applications of 3D digitization, along with the integration of deep learning (DL), in enhancing data collection, improving model precision, and mitigating costs within the mining sector. This research seeks to establish a robust foundation for the development of DL-based 3D digitization models that are tailored to the unique characteristics of mining infrastructure, thereby providing an unprecedented and significant contribution to the advancement of this technology within the local context.

2. METHODOLOGY

To achieve our objective, a systematic literature review was conducted using the guidelines and principles defined by Kitchenham [10], ensuring the rigor and reproducibility of the process. Figure 1 shows the Kitchenham approach, which comprises three steps: planning, execution, and reporting.

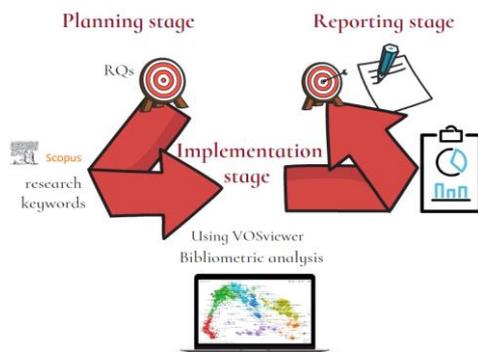


Figure 1. Kitchenham methodology

2.1 Planning stage

The objective of the systematic review is to evaluate the impact of technological advancement on 3D digitalization with AI according to the type of infrastructure. For this, the review of works published between the years 2020 and 2024 was considered. The reason we chose the year 2000 as the starting point for our review is the rise in the use of AI.

This research focuses on the analysis of identification machine learning techniques used for the segmentation and classification of point clouds according to the type of infrastructure, and to achieve this, the questions presented in Table 1 must be answered.

Table 1. Research questions

RQ	Questions
1	What are the most relevant applications of integrating 3D digitization with point clouds and AI for different types of infrastructures?
2	What available datasets are related to structural components of industrial infrastructure?
3	What AI models use point clouds for the recognition of structural components in industrial infrastructures?

2.2 The implementation stage

Table 2 details the organization of the keywords into four blocks. In the first block, words related to technologies such as "3D scanning," "laser scanning," and "point cloud" were established. In the second block, the keywords related to AI and the geometric recognition of objects in point clouds were defined as: "object recognition", "object detection", "classification", "segmentation", "instance segmentation", "semantic segmentation", "part segmentation", "segmented point cloud". In the third block, keywords related to AI techniques were selected using keywords such as: "Artificial intelligence", "machine learning", "deep learning", "convolutional neural network". Finally, in the fourth block, articles related to the field of application were selected using keywords such as: "construction", "structural components", "engineering", "infrastructure", "structural elements", "industrial plants", "processing plants", "structural parts", "infrastructure elements", "infrastructure components", "industrial process plant", "pipework components", "industrial facilities". This search resulted in the identification of 552 articles, which underwent a selection process considering the inclusion and exclusion criteria, see Table 2 and Section 2.3.

Table 2. Inclusion and exclusion criteria

Criteria	Description
Databases	Scopus
Searching Key	
Technology	("3D scanning" OR "laser scanning" OR "point cloud") AND ("object recognition" OR "object detection" OR "classification" OR "segmentation" OR "instance segmentation" OR "semantic segmentation" OR "part segmentation" OR "segmented point cloud")
IA	OR "instance segmentation" OR "semantic segmentation" OR "part segmentation" OR "segmented point cloud") AND ("artificial intelligence" OR "machine learning" OR "deep learning" OR "convolutional neural network") AND ("construction" OR "structural components" OR "engineering" OR "infrastructure" OR "structural elements" OR "industrial plants" OR "processing plants" OR "structural parts" OR "infrastructure elements" OR "infrastructure components" OR "industrial process plant" OR "pipework components" OR "industrial Facilities")
Technique	The study elaborates on the use of DL for geometric recognition of industrial structural components.
Application	Articles published in English.
Inclusion Criteria	Not Journal- Review or proceeding
Exclusion Criteria	Items over 5 years old

In this systematic review, models and datasets are classified

4. DISCUSSION

Despite the classification of the scientific contribution of 3D digitization with AI according to the type of infrastructure, as shown in Figure 4 and described in the responses to research questions RQ1a-RQ1d, this article extends its development in industrial infrastructure, as it is linked to the mining industry.

RQ1a: What are the most relevant applications of

integrating 3D digitization through point clouds and AI in industrial infrastructures?

With the aim of answering the question RQ1a, a comprehensive literature review was conducted. Table 3 summarizes the main findings: a) the datasets covering industrial infrastructures, among which Pipework, CLOI, and PSNet5 stand out; b) the DL models used for training, and c) the accuracy of these models.

Table 3. Precision of IA-based 3D digitization models of industrial infrastructures using point clouds

Ref	DataSet	Year	#	Semantic Classes	Model	mAcc
[13]	Pipework	2020	17	BlindFlange, Cross, Elbow90, Elbow non 90, Flange, Flange WN, Olet, OrificeFlange, Pipe, Reducer CONC, ReducerECC, Reducer Insert, Safety Valve, Strainer, Tee, Tee Red, Valve.	PointNet	73.3%
[14]	Semantic3D	2020	8	Terrain, Vegetation, and Building.	RDNet+PointNet	94.0%
[15]	CLOI	2020	10	Cylinders, Elbows, Channels, Beams, Angles, Flanges and Valves.	CLOI-NET	82.0%
[16]	Ind. building	2021	6	Beam, Ceiling, Column, Floor, Pipe, Wall.	CNN-RNN	86.1%
[17]	Pool and Sea	2021	-	Pipes and Valves.	PointNet	97.2%
[18]	Industrial plants	2021	6	Elbow, Flange, Straight, Tee, Valve and Manometer.	PointNet	71.5%
[19]	CLOI	2021	10	Cylinders, Elbows, Channels, I-beams, Angles, Flanges and Valves.	SFR-PointNet++	79.8%
[20]	Civil tunnelling	2021	-	Rock Bolt.	CFBolt	-
[8]	PSNet5	2021	5	Ibeam, Pipe, Pump, Rbeam, Tank.	ResPointNet++	95.0%
[21]	Ind. building	2021	6	Beam, Ceiling, Column, Floor, Pipe, Wall.	CRF-MRF	90.0%
[22]	Scaffolds	2022	-	Scaffolds.	RandLA-Net	90.8%
[23]	3DMatch	2022	40	Pipes and Valves.	KPConv	96.0%
[24]	Pipe and valve	2022	-	Pipes and Valves.	DGCNN	88.0%
[25]	Pipelines	2022	-	Pipelines.	DNN	99.7%
[9]	Pipework	2022	17	BlindFlange, Cross, Elbow90, Elbow non 90, Flange, Flange WN, Olet, OrificeFlange, Pipe, ReducerCONC, Reducer ECC, Reducer Insert, Safety Valve, Strainer, Tee, Tee RED, Valve.	SE-PseudoGrid	97.5%
[26]	BIMGeom IFCNetCore	2022	13	Wall, Slab, Column, Window, Door, Stair, Railing, FlowTerminal, FlowSegment, FlowFitting, DistributionControlElement, FlowController, and Interior furniture.	DGCNN	85.0%
[27]	Synthetic scaffold	2023	-	Scaffolds.	RandLA-Net	95.0%
[28]	Transmission Corridor	2023	4	Tower, Transmission Line, Ground Wire, Ground.	CA-PointNet++	93.7%
[29]	MFCAD	2024	-	CAD models.	Mod.PointNet++	97.7%
[30]	SoftGroup	2024	27	Ground, Support structure, Piping and Scaffolding, etc.	DBSCAN	78.1%
[31]	Mock-up plant	2024	9	Handrail, Pipe, Grating, Equipment, Fire suppression, Light fitting, Support, Tank, and Frame.	Hybrid	92.8%

The advances in the classification and segmentation of industrial infrastructures using advanced 3D digitization techniques and DL models stand out for their high accuracy in identifying structural components. DL models such as PointNet and its variants, like PointNet++ and SE-PseudoGrid, have proven to be very effective, achieving accuracies ranging from 71.5% to 99.7%, depending on the complexity of the dataset and the number of classes involved.

For the Pipework dataset (2020), which includes 17 classes achieved an accuracy of 73.3% using the PointNet model. In the case of the Semantic 3D dataset (2020) and the PointNet-RDNet model, which was applied in mining terrains, classifying 8 classes achieved an accuracy of 94.0%. Another significant example is the CLOI dataset (2020), which classifies 10 classes of industrial components, achieving 82% accuracy with the CLOI-NET model. The PSNet5 dataset (2021) excels in the classification of 5 classes of components, using the ResPointNet++ model, achieving an accuracy of 95%. This demonstrates the model's ability to handle the identification of industrial elements with high precision.

On the other hand, the model that combines CNN and RNN achieved an accuracy of 86.1%, performance reached in the recognition and classification of 6 classes of components.

Similarly, the DNN model achieved an accuracy of 99.7% in the recognition and classification of pipes, standing out over the other models. Figure 6 shows the models with an accuracy above 95% are shown, a notable example is the SE-PseudoGrid model, which achieved an outstanding accuracy of 97.5%.

PointNet-based models stand out for their ability to directly process cluttered point clouds without the need for preprocessing. This approach has proven effective in industrial contexts, achieving high accuracy in specific tasks such as pipe classification (97.5% with SE-PseudoGrid in [9]). Furthermore, its lightweight architecture makes it suitable for real-time applications. However, it has limitations when semantically segmenting complex geometries and lacks contextual awareness in large-scale environments, which is reflected in lower performances, such as in the studies [13, 18], where accuracies were 73.3% and 71.5%, respectively.

These results show the potential of AI models, such as DNN, SE-PseudoGrid, and ResPointNet++ to enhance automation in the identification of critical components in industrial infrastructures. Clearly, Industrial component identification is being increasingly investigated as can be seen in Table 3. Pipes and valves are the main structures researched

because they are key components in many industrial sectors, such as energy, petrochemicals, water management and industrial processes, so their research is justified by the critical need to monitor, maintain and optimize these systems. The high frequency of research on pipelines reflects the importance of automating their inspection and management in order to prevent failures, leaks or accidents, reducing downtime and operating costs.

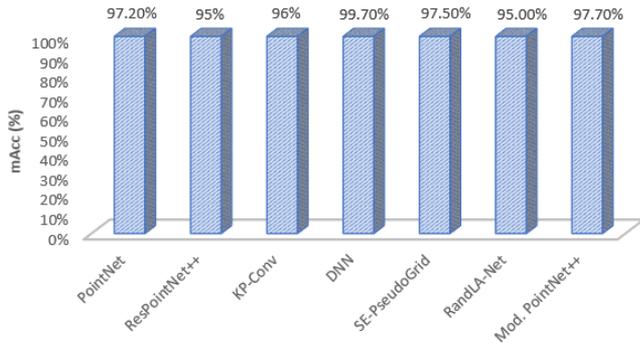


Figure 6. IA-based 3D digitization through point cloud processing for industrial infrastructure with over 95% accuracy

RQ1b: What are the most relevant applications of integrating 3D digitization through point clouds and AI in transportation infrastructure?

In the analysis of transportation infrastructures, the results of the models in various studies demonstrate remarkable effectiveness in the classification and recognition of critical components. Figure 7 shows the models that exceed 95% accuracy. The SP-Network model achieved an impressive accuracy of 99.7%, using the Road infrastructure dataset which covers a variety of classes including road surfaces, buildings, and traffic signs. Another relevant model is EffNet, which achieved an accuracy of 97.7% using the Railway dataset that includes: poles, catenaries, and cables.

In 2024, the KPConv model achieved an accuracy of 99% using the Rail3D dataset, demonstrating the ability of current models to classify a wide range of elements, from vegetation to signals and support structures. This is confirmed by looking at the Figure 7 that reports the BrIM model, which achieves an accuracy of 97.26% using the Highway bridges dataset, excels in identifying essential components such as beams and slabs. These results demonstrate notable progress in automating and enhancing transportation infrastructure management, which optimizes safety and operational efficiency.

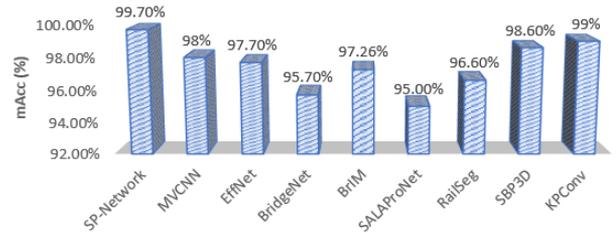


Figure 7. IA-based 3D digitization through point cloud processing for transportation infrastructure with over 95% accuracy

Automation through the use of IA models can significantly improve the efficiency and accuracy of inspections. Table 4 shows that the high frequency of research into bridges, railways, roads and tunnels reflects their critical importance in the transportation system and the urgent need to keep these infrastructures in good condition. The practical applications of this research in predictive maintenance, autonomous monitoring, asset management and road safety are marking a step towards smarter, safer and more efficient transportation systems. Moreover, advancements in technologies for the automatic identification of components within transportation infrastructure are expected to continue, thereby contributing to enhanced quality of life and promoting greater sustainability within both public and private transportation sectors.

Table 4. Precision of IA-based 3D digitization models of transportation infrastructures using point clouds

Ref	Year	DataSet	#	Semantic Classes	Model	mAcc
[32]	2020	Bridge	4	Background, Pier, Pier Cap, Slab.	PointNet++	94.0%
[33]	2020	KITTI	3	Car, Pedestrian, Cyclist.	RobNet	66.0%
[34]	2020	Stanford 3D	6	Road surfaces, Buildings, Walls, Traffic Signs, Trees, Streetlights.	SP-Network	99.7%
[35]	2021	Railroad Bridges	10	Pole, Building, Girder, Pier, Ground, Grass, Water, Sky, Car, Road.	SfM	80.8%
[36]	2021	Infrastructure building	10	Columns, Culvert1, Culvert2, Culvert3, Sump, Lshaped, Semi-gravity, Cantilever, Gravity, Wing wall.	MVCNN	98.0%
[37]	2021	Girder bridge	6	Abutment, Girder, Pipe, Cross Girder, Deck, Background.	PCIS	82.8%
[38]	2021	Railway	8	Pole, Catenary wire, Contact wire, Insulator, Dropper, Steady arm, Registration Arm, Cantilever.	EffNet	97.7%
[39]	2022	Railway infr.	8	Background, Traffic signs, Informative signs, Traffic lights, Masts, Cables, Droppers, Rails.	C-PointNet++	88.8%
[40]	2022	Railway Bridge	5	Spandrel Wall, Pier, Abutment, Arch, Hole.	BridgeNet	95.7%
[41]	2022	OCS	9	Catenary Wire, Steady Arm, Oblique Cantilever, Straight, Cantilever, Elastic Catenary Wire, Registration Arm, Dropper, Contact Wire.	PMFR-Net	93.0%
[42]	2022	Road surface	3	Drivable lane, Driving line, Hatched area.	MaskR-CNN	77.8%
[43]	2022	Railway system	16	Ground, Rail-bed, Sleeper, Rail, Platform-structural, Vegetation, Tree, Building, Catenary-wire, Catenary-pole, Noise-barrier, Platform-asset, Cantilever, Contact-wire, Dropper.	Mod. KPConv	82.1%
[44]	2022	Highway bridges	5	Slab, Girder, Pier cap, Pier, Background.	BrIM	97.3%
[45]	2022	PWMMS-UHA	9	Bridge Deck, Bridge Abutment, Bridge Pier, Man made terrain, Natural terrain, Vegetation, Building, Remaining hardscape, Scanning artifact.	PointNet-GV	80.3%
[46]	2023	Railway Catenary	14	Unlabelled, Top bar, Pole, Drop post, Top tie, Bracket, Pole	Mod.PointNet++	71%

		Arches		foundation, Steady arm, Contact wire, Stitch wire, Wheel tension device, Dropper, Messenger wire support, Insulator.		
[47]	2023	Railway infr.	7	Informative signs, Masts, Traffic lights, Traffic signs, Cables, Droppers, Rails.	Hybrid	68.7%
[48]	2023	Road maintenance	5	Asphalt, Road markings, Road signs, Barriers, other.	Hybrid	87%
[49]	2023	Semantic3D SemanticKITTI	8	Contact wires, Catenary wires, Current return wires, Tracks, OCS masts, Line foundation, Fences, Others.	SALAProNet,	95%
[50]	2023	Railway LIM	7	Natural greenery, farmland, Bare land, Railway, Road, River, Building.	DBSCAN	-
[51]	2023	Bridge and Tunnel	2	Cement Wall, Bridge. Crack detection.	CNN	79.8%
[52]	2023	Stanford 3D	13	Beam, Board, Book, Ceil, Chair, Clut, Col. Door, Floor, Sofa, Table, Wall, Wind.	Rnn-PointNet++	86.7%
[53]	2023	Toronto-3D	8	Road surface, Road Mrk, Natural, Building, Util. line, Pole, Car, Fence.	SCF-Net	-
[54]	2023	A metro tunnel	6	Cable, Segment, Pipe, Power track, Support, Track.	DAPCNet	91.0%
[55]	2023	PARIS-LILLE-3D	10	Ground, Road, Building, Pole, Bollard, Tree, Dustbin, Pedestrian, Car, Barrier.	RailSeg	96.6%
[56]	2023	COCO:Bridge	3	Railing, Abutment, Deck.	MaskR-CNN	60.5%
[57]	2023	STTED	7	Clutter, Bolt hole, Grouting hole, Longitudinal Joint, Cable, Weak-current cable, Circumferential joint.	GL-Net.	73.0%
[58]	2023	KITT	2	Car, Person.	MY3Net	84.2%
[59]	2024	Highway Bridges	6	Vegetation, Road, Railing, Noise, Barrier, Signs.	HSVM	92.0%
[60]	2024	Tunnel	8	Left wall, Right wall, Roof, Floor, Wires, Belts transport, Air tube.	SAM	88.9%
[61]	2024	Seg2Tunnel	5	Segment, Pipe, Cable, Rail, Walkway.	SBP3D	98.6%
[62]	2024	Rail3D	8	Ground, Vegetation, Rail, Poles, Wires, Signaling, Fences, Installation.	KPConv	99.0%
[63]	2024	Bridge-TLS	17	Assembly abutment, Assembly signbridge, Barrier flexible, Barrier railing, Barrier rigid, Beam_girder, Beam piercap, Column pier, Footing, Natural ground, Pipe, Slab deck, Slab paving, Sab sidewalk, Stair, Traffic sign, Wall noise barrier.	VI-Head	89.4%
[64]	2024	ROADSENSE	-	Transport, Forest.	PointNet++	82%

RQ1c: What are the most relevant applications of integrating 3D digitization through point clouds and AI in construction infrastructure?

In the analysis of construction infrastructures, the results from datasets of various studies demonstrate remarkable effectiveness in the classification and recognition of critical components. Figure 8 shows the models that exceed 90% accuracy. For example, a notable result comes from the BIM models, where the Hybrid model achieved 90% accuracy in classifying essential elements such as beams, columns, walls, and doors. This approach is fundamental in the implementation of BIM, which facilitates the planning and management of construction projects.

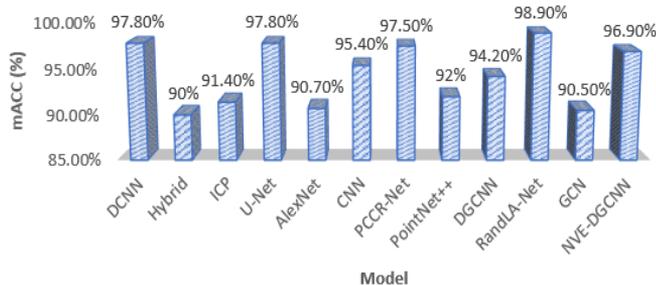


Figure 8. IA-based 3D digitization through point cloud processing for construction infrastructure with over 90% accuracy

In the case of the U-Net model that used the CrackSeg dataset, used for crack detection in pavements, it achieved an accuracy of 97.8%, highlighting the importance of computer vision techniques in infrastructure maintenance.

The NVE-DGCNN model showed an accuracy of 96.9% with the Bridges dataset, highlighting the effectiveness of

models in identifying critical structures such as bridges. Moreover, in the analysis of metro stations in Beijing, the use of PointNet++ achieved an accuracy of 60%, which demonstrates that classification in complex environments remains an area with significant opportunities for improvement.

Finally, the DGCNN model reported an accuracy of 94.2% on the S3DIS dataset, demonstrating a robust ability to identify elements within buildings, which is essential for interior space management. These results reflect the continuous development and application of advanced models in the classification of components in the construction sector, improving the efficiency in the design and maintenance of infrastructures.

It is well known for the use of BIM models for the digitalisation of infrastructures, facilitating project planning, resource optimisation and management during construction. Then, by integrating machine learning models, it enables the detection of possible errors in the design phase and improves the accuracy in the execution of works. Table 5 shows that the most investigated classes are: pillars, columns and beams, which are fundamental components in almost all construction infrastructures, since they support structural loads. Therefore, automatic inspections of these elements are essential to identify cracks, corrosion and other defects that could compromise the stability of a building or infrastructure.

RQ1d: What are the most relevant applications of integrating 3D digitization through point clouds and AI in ISPS?

The information presented in Table 6 reflects the performance of various models in the classification of components within the ISPS category. Over the years, remarkable results in terms of accuracy have been observed. In 2022, the GFSAE model achieved an accuracy of 95.4%, operating on the Semantic 3D dataset which includes 8 classes

such as terrain, vehicles, among others. This highlights the effectiveness of DL techniques in segmenting complex data in urban environments.

Likewise, in 2022, the U-Net 3D model achieved an impressive accuracy of 96.9% with the dataset City center of Stuttgart, Germany, demonstrating its ability to distinguish between various urban elements such as buildings and vegetation. In 2023, the D-Net model achieved an accuracy of 97.6% with the US Highway dataset, correctly identifying various objects, including buildings and electrical cables.

Figure 9 shows the IA-based 3D digitization through point cloud processing for ISPS with over 90% accuracy, as it can be seen the model MIF-PointNet++ offer a 98% of mAcc. These results underscore the progress in the use of advanced models for the identification and classification of components in ISPS, which could have a significant impact on the planning and management of these vital resources. The continuous improvement in the accuracy of these models suggests progress towards automation and optimization in urban infrastructure.

Evidently, urban buildings are the basic element in any city, and therefore 3D modelling of buildings is essential for urban

planning, asset management and land use determination. The sector classes urban buildings, vegetation and natural elements are the most frequent in Table 6. The use of 3D models in public infrastructure allows urban planners to create accurate digital maps of urban areas, facilitating decision making on land use, construction areas, green areas and road infrastructure.

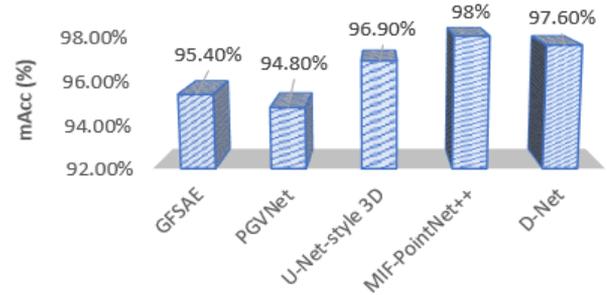


Figure 9. IA-based 3D digitization through point cloud processing for ISPS with over 90% accuracy

Table 5. Precision of IA-based 3D digitization models of construction infrastructures using point clouds

Ref	Year	DataSet	#	Semantic Classes	Model	mAcc
[65]	2020	Motorway Monorail	6	Piers, Roads, Vegetation, Terrain, Vehicles, Background.	DCNN	97.8%
[66]	2020	BIM models.	7	Beams, Columns, Walls, Pipes, Doors, Windows, Railings.	Hybrid	90.0%
[67]	2020	Annunziata viaduct	11	Bridges, Viaducts.	Mask-RCNN	-
[68]	2020	BIM models.	-	BIM.	ICP	91.4%
[69]	2021	CrackSeg	-	Pavement.	U-Net	97.8%
[70]	2021	S3DIS	-	-	CorDet	80.5%
[71]	2022	TUMCMS S3DIS	5	Ceiling, Wall, Floor, Windows, Door.	Point Transformer	81.9%
[72]	2022	ShapeNet S3DIS	16	Airplane, Bag, Cap, Car, Chair, Earphone, Guitar, Knife, Lamp, Laptop, Motor, Mug, Pistol, Rocket, Skateboard, Table.	PointNet++	88.0%
[73]	2022	5 Datasets	3	Cranes, Scaffolds, Formwork.	AlexNet	90.7%
[74]	2022	Digimap	5	Flat, Hip, Gable, Cross-hip, Mansard roofs.	CNN	95.4%
[26]	2022	Industrial	13	Wall, Slab, Column, Window, Door, Stair, Railing, FlowTerminal, FlowSegment, FlowFitting, DistributionControlElement, FlowController, FurnishingElement.	GCNs	83.0%
[75]	2023	Synthetic	4	Columns, Beams, Slabs, Walls.	PCCR-Net	97.5%
[76]	2023	Interior trades	4	Tiling, Waterproofing, Boarding, Background.	PointNet++	92.0%
[77]	2023	Subway stations	-	Non-paying Areas, Paying Areas, Entrances and exits, Platform Levels, Tracks, Accessible Elevators, and Escalators, Stairs.	PointNet++	60.0%
[78]	2023	S3DIS	5	Columns, Beams, Walls, Floors, Ceilings.	DGCNN	94.2%
[79]	2023	Sungkyunkwan University	9	Wall, Window, Curtain, Duct, Vent, Coping, Door, Colon, Balcony.	RandLA-Net,	98.9%
[80]	2024	ScanNetv2	5	Apartment, Bathroom, Bedroom, Living room, Classroom, Conference room, Comp. cluster.	GCN	90.5%
[81]	2024	Bridges	5	Bridges.	NVE-DGCNN	96.9%
[82]	2024	ScanNet- S3DIS	6	Beam, Ceiling, Column, Door, Floor, Wall, Window.	ConPro-NET	81.0%
[83]	2024	2 Datasets	6	Concrete, Formwork, Reinforcement Steel, Steel Structure, Wall Tiles, and Floor Tiles.	Mask-RCNN	-
[84]	2024	S3DIS	12	Ceiling, Floor, Wall, Beam, Column, Windows, Door, Table, Chair, Sofa, Book case, Board, Clutter.	PointNet++	60.0%

Table 6. Precision of IA-based 3D digitization models of ISPS using point clouds

Ref	Year	DataSet	#	Semantic Classes	Model	mAcc
[85]	2020	ISPRS 3D	9	Powerline, Low vegetation, Impervious surface, Car, Fence/Hedge, Roof, Facade, Shrub, and Tree.	DANCE-Net	71.2%
[86]	2021	Urban outdoor	6	Car, Bush, Tree, Ground, Streetlight, and Building.	KBA	75.0%
[87]	2021	Suburban European city	11	Natural ground, Low vegetation, High vegetation, Buildings, Traffic roads, Wire-Structure, Connectors, Vehicles, Poles,	RandLA-Net	81.9%

[88]	2021	Jujube orchard	2	Hardscape, Barriers, Pavements Branches, Trunks.	SPGNet	89.0%
[89]	2021	Buildings of the city of Shenzhen	3	Building, Tree canopy, Terrain.	DeepLabv3-PointNet++	83.3%
[90]	2021	Highway in Shenzhen, China	7	Transversal slow belt (TSB), VSB, Meshline, Zebra crossing, Arrow, Solid line, and Dotted line.	DFPN	69.1%
[91]	2022	Semantic3D	8	Man-made terrain, Natural terrain, High vegetation, Low vegetation, Building, Hardscape, Scanning artifacts, Cars.	GFSAE	95.4%
[92]	2022	Paris-Lille-3D	7	Cars, Trees, Traffic poles, and Small objects (Pedestrians, Bicycles, and E-bicycles).	PGVNet	94.8%
[93]	2022	City center of Stuttgart, Germany	5	Ground, Building, Low Points, Bridges, Vegetation.	U-Net-style 3D	96.9%
[94]	2022	LASDU,US3D, ISPRS 3D,GML	24	Ground, Building, Tree, Low veg, Artifact ground, High veg, Building, Water, Bridge Power, Low, Imper, Car, Fence, Roof, Facade, Shrub, Tree	VD-LAB	76.0%
[95]	2023	USGS ISPRS	7	Ground, Building, Car, Tree, Low veg Steeply sloping terrain, Dense vegetation, Buildings with vegetation, Train stations, Multistory buildings with courtyards, Quarries (with fracture lines).	MIF-PointNet++	98.0%
[96]	2023	DALES	4	Buildings, Vegetation, Ground, Background.	Hybrid	77.3%
[97]	2023	US Highway	8	Buildings, Cars, Powerlines, Vegetation, Asphalt Road, Poles, Billboards, and Sidewalk.	D-Net	97.6%
[98]	2023	Two complex Chinese urban Scenes	10	Ground, Building, Tree, Light, Parterre, Pedestrian, Fence, Pole, Car, others.	Hybrid	88.1%
[99]	2023	SensatUrban	11	Ground, Vegetation, Building, Wall, Bridge, Parking, Traffic, Street, Car, Footpath and Water.	TSANet	83.4%
[100]	2024	Hong Kong China. Lille, France.	5	Others, Ground, Building, Vegetation, Pole-like.	GeoBIM	86.9%
[101]	2024	SensatUrban	9	Ground, High vegetation, Buildings, Walls, Parking, Traffic Roads, Street furniture, Cars, Footpath.	RandLA-Net	62.0%

Table 7. Most used dataset for 3D digitization with AI for industrial infrastructure

Dataset	Year	Application	Type	Points	Class
CLOI [15]	2020	Five industrial	Indoor scene	14 M	10
Pipework [13]	2020	Industrial process plant	Object-based	110 M	17
PSNet5 [8]	2021	Four different industrial scenes	Indoor scene	80 M	5

In the case of digitalisation of vegetation and natural spaces in cities, it can be used to manage urban biodiversity, plan the renewal of green areas and ensure that cities are more sustainable. It also allows us to assess the environmental impact of infrastructure and develop mitigation strategies for the changing effects of climate.

RQ2: What available datasets are related to structural components of industrial infrastructure?

Currently, the availability of public datasets, which encompass structural components in industrial infrastructure, is significantly limited due to the high costs associated with the acquisition and labeling of these data [15]. The datasets presented in Table 7 are the most relevant resources available for industrial infrastructure.

Pipework [13]: It is a repository specifically designed for semantic segmentation tasks of 3D point clouds in the context of industrial components, particularly focused on the segmentation and classification of pipes and their associated elements within industrial facilities, such as factories or processing plants. For the creation of this dataset, a terrestrial laser scanning (TLS) was conducted at a petroleum refinery plant. Pipework comprises a total of 4647 shapes grouped into 17 classes, which together encompass 110 million points addressing various industrial components.

CLOI [15]: It is a dataset designed for semantic

segmentation and large-scale object classification, with a specific focus on industrial components and large structures in manufacturing environments or industrial plants. It is one of the most extensive TLS collections of industrial plants, this dataset was carried out in five industrial facilities, three were warehouses, one was a petrochemical plant, and the fifth was an oil refinery. CLOI consists of 12125 shapes grouped into 10 classes, covering 140 million points that address industrial, indoor, and outdoor situations. These classes include electrical conduits, straight pipes, circular hollow sections, elbows, channels, solid bars, beams, angles, flanges, and valves. This dataset provides a detailed and comprehensive representation of industrial infrastructure, making it a valuable tool for applications that require precise analysis of industrial environments.

PSNet5 [8]: It is a well-known public dataset that presents a collection of 3D point clouds of industrial components. PSNet5 was built using a TLS, selecting four industrial scenarios from water treatment plants in Hong Kong, which include Chiller House (CH), On-Site Chlorine Generation (OSCG), Sludge Press House (SPH), and Wash-water Recovery Tank. (WRT2). The four scenes used are mainly composed of elements such as pipes, pumps, beams, and other industrial categories. This dataset consists of 5 classes with a total of 80 million points. The large amount of training data is sufficient to train DL models and fully leverage their capability in perceiving three-dimensional data of industrial structural components.

The most representative datasets for this case study are CLOI, Pipework, and PSNet5. These datasets were generated using TLS, which includes RGB features. To classify the classes, a 3D semantic segmentation was performed, with classes related to structural components.

RQ3: What AI models use point clouds for the recognition of structural components in industrial infrastructures?

To address this research question, a thorough review of DL-based models intended for semantic segmentation of point clouds was conducted, considering publications from recent years. Attention has been given to the approaches developed and applied in the context of structural components in infrastructures.

Figure 10 shows the taxonomy of DL models with an emphasis on applications with 3D point clouds. In this figure, three main categories can be observed: 3D shape classification, 3D point cloud segmentation, and 3D object detection-tracking.

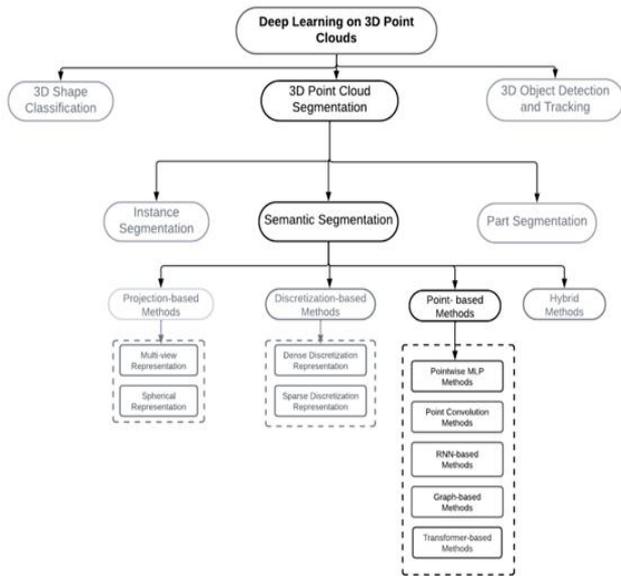


Figure 10. Taxonomy of DL methods for 3D point cloud segmentation [102]

3D point cloud segmentation requires comprehension of global geometric structures and the specific details of individual points. Based on the level of granularity, 3D point cloud segmentation methods can be categorized into three subtypes: semantic segmentation (scene level), instance segmentation (object level), and part segmentation (part level) [102]. The approach to semantic segmentation of point clouds is to separate them into several subsets based on the semantic meaning of the points, where four specific methods stand out: the projection-based method, the discretization-based method, the point-based method, and the hybrid-based method.

This research focuses on the point-based method, which is subdivided into several approaches. One of the main ones is the so-called Pointwise MLP; these point-based methods perform learning directly on the irregular point cloud. These clouds lack a defined order and structure, which makes difficult the direct application of standard Convolutional Neural Networks (CNNs), originally designed for data organized in regular grids. This limitation was overcome in 2017 with the introduction of the PointNet model [6], which was designed to process unstructured 3D point clouds without requiring conversion to a structured grid or voxel representation, then this contribution has served as a reference for various segmentation methods.

In general, most existing DL-based point cloud segmentation applications, especially those implemented in the field of industrial structural components, have opted for point-based methods. In what follows, a brief description of the most commonly used and most accurate models, according

to the literature review is described.

PointNet [6]: Pointnet is a novel type of neural network that directly consumes unordered point clouds, which also takes care of the permutation invariance of points in the point cloud. Pointnet can do object classification, part segmentation, and semantic parsing. The main feature of Pointnet is the network is robust with respect to input perturbation and corruption. Also, the network can learn to summarize a shape by a sparse set of key points.

PointNet++ [7]: is a hierarchical network that applies Pointnet recursively on a nested partitioning of the input point cloud. It proposes novel set learning layers to adaptively combine features from multiple scales from varying densities. Similar to CNNs, Pointnet++ extracts local features from a small neighborhood and further grouping into larger units and processes to produce higher level features. This process is recursive until we obtain the feature of the whole point set.

ResPointNet++ [8]: ResPointNet++ is a model for industrial point clouds, which significantly improves the performance of DL-based methods for industrial point cloud segmentation. Through the implementation of the ResPointNet++, it is feasible to effectively segment large-scale industrial LiDAR point clouds by using a neural architecture with deep residual settings.

SE-PseudoGrid [9]: The SE-PseudoGrid architecture enhances the network's ability to differentiate and classify 3D objects, excelling in industrial and robotics applications. SE-PseudoGrid model, called SE-LAO, extracts descriptive features from the point cloud during the process of learning the representation of these clouds. The integration of the SE mechanism and the PseudoGrid model contributed to a more effective approach for classification. The model architecture is composed of two components, the encoder and the header. The encoder uses a shared fully connected (FC) layer, generating feature embeddings. Through SE layers and residual blocks (RB), the encoder learns significant local structures. Then, a series of SE-LAO and SE-RB layers are applied to extract local geometric structures from each point.

The precision of a model is also measured by metrics such as Mean Overall Accuracy (mOA) and Mean Intersection over Union (mIoU). These metrics are commonly expressed in percentage terms and are widely used to evaluate the performance of models in point cloud processing with AI in a 3D digitization process, see Table 8.

Table 8 presents the Pipework, CLOI, and PSNet5 datasets. These datasets are related to the case study and are available to the academic community. The Pipework dataset was first used in 2020. The study [14] proposed a DL-based method to retrieve pipe component catalogs to support the reconstruction of a 3D CAD model of a process plant with point clouds. The data retrieval system identifies the type of pipe components, searches for and extracts data from the catalog, and performs post-processing of the catalog data. The authors applied the PointNet model, obtaining the following metrics: mOA of 79.9%, mAcc of 73.6%, and mIoU of 60.8%, with their respective mIoU per class presented in Table 5.

In the study [15], the CLOI dataset was used to evaluate DL classification models along with their new model CLOI-NET. They achieved superior results compared to other models, reaching the following metrics: mOA of 83%, mAcc of 59%, and mIoU of 45.1%, with the respective mIoU per class presented in Table 8.

In the study [19], the CLOI dataset was used to evaluate DL classification models along with their new model SFR-

PointNet++. The authors achieved superior results compared to other models, reaching the following metrics: mOA of 72%, mAcc of 50%, and mIoU of 38.1%, with the respective mIoU per class presented in Table 3.

The study [8] used the PSNet5 dataset to evaluate DL classification models along with their new model ResPointNet++. They obtained superior results compared to other models, achieving the following metrics: mOA of 94%

and mIoU of 87.3%, with the respective mIoU per class presented in Table 8.

The pipework dataset was used to evaluate DL classification models along with their new SE-PseudoGrid model [9], and it achieved superior results compared to other models, reaching the following metrics: mOA of 96.2%, mAcc of 97.5%, and mIoU of 96.5%, with the respective mIoU per class presented in Table 8.

Table 8. Most used models with corresponding precision for 3D digitization with AI for the industrial infrastructure

Ref	DataSet	Year	Model	mOA	mAcc	mIoU
[13]	Pipework	2020	PointNet	79.9%	73.6%	60.8%
			PointNet	50%	21%	12%
[15]	CLOI	2020	PointNet++	68%	46%	32%
			CLOI-NET	83.0%	59%	45.1%
			PointNet	50%	21%	12%
[19]	CLOI	2021	PointNet++	68%	46%	32%
			PointNET++ SFR	72%	50%	38%
			PointNet	53.0%	-	21.2%
[8]	PSNet 5	2021	PointNet++	70.5%	-	45.5%
			ResPointNet++	95.0%	-	87.3%
		2020	PointNet	84.2%	73.9%	-
[9]	Pipework	2022	PointNet++	86.8%	75.3%	-
		2022	SE-PseudoGrid	96.2%	97.5%	96.5%

Industrial structural components play a critical role in industrial plants, and the 3D digitization of these components from point clouds has gained significant attention. A major challenge has been the ineffectiveness of semantic segmentation. Accurate classification of structural components typically requires professional intervention, leading to inefficiencies. However, recent advancements in DL methods for classification, semantic segmentation, and object detection in point clouds have shown promise for industrial structural components, particularly with the development of pointwise MLP methods for segmentation, as illustrated in Figure 10.

After conducting a thorough analysis of the datasets, the datasets related to industrial structural components are as follows: Pipework, CLOI, and PSNet5, these datasets have played a fundamental role in the evaluation of DL models designed to address the interpretation of three-dimensional industrial scenes.

In particular, it is essential to highlight that 3D digitalization with AI is a growing trend in the mining industry, as it allows for better understanding and planning of infrastructures. The aforementioned DL models, such as PointNet, PointNet++, ResPointNet++, and SE-PseudoGrid, have proven to be highly effective in analyzing and processing large datasets of point clouds in environments other than industrial mining infrastructures. However, they have been successfully used to identify and classify different types of rocks and minerals in three-dimensional images using the PointNet model, in a type of infrastructure that could be considered similar to transportation infrastructure or construction infrastructure, according to the classification described in this paper.

Therefore, by combining 3D digitization with AI and using appropriate models and datasets, greater efficiency and accuracy can be achieved in the characterization of mining infrastructure. This can lead to better planning and management of mining projects, as well as a reduction in costs and risks associated with resource exploration and extraction.

A global analysis of the industries related to the 92 articles investigated in this article confirms that: a) the industry where this technology is most used is the oil or natural gas industry,

where it is employed for the inspection and maintenance of metal structures in difficult and hazardous environments, b) there are no articles of the industrial infrastructure type that are related to the mining industry. There are some articles that could be related to rocks or mining areas, but not those related to industrial processes. Consequently, it can be stated that 3D digitization with AI in mining infrastructure is in full development and requires deep attention.

Paradoxically, the main industrial activity in Peru is mining; however, this study demonstrates that there has been no advancement in 3D digitization with AI in journals indexed in Scopus. Therefore, it is recommended to consider the present research topic in the strategic funding areas of the competent entities, such as Prociencia in Peru.

As a final result of this article, to accelerate the adoption of 3D digitalization tools with AI in industrial mining infrastructures, it is recommended to consider articles [8, 9], [13-31] as a starting point. Additionally, it is suggested to use the models (PointNet++, ResPointNet++, and SE-PseudoGrid) and the dataset (Pipework, CLOI, and PSNet5) for the digitalization of industrial mining infrastructures with AI.

In consideration of future research activities, a number of potential pathways are suggested subsequent to the completion of this comprehensive review. Several of these are detailed in what follows:

1) The generation of synthetic data with enhanced geometric accuracy and a broader variety of materials, including concrete, wood, steel, and glass, aims to augment the capabilities of DL models.

2) Exploration of datasets pertinent to particular industrial sectors, incorporating data from infrastructure situated in diverse geographical regions while taking into account distinct cultural and construction elements.

3) Given that the findings associated with ISPS exhibit the lowest degree of accuracy, subsequent research endeavors may aim to enhance the precision of the following categories: Soil, Tall Vegetation, Buildings, Walls, Parking, Circulation Paths, Street Furniture, Automobiles, and Path. This improvement is intended to strengthen the DL models.

5. CONCLUSIONS

The present systematic literature review has facilitated the generation of knowledge on 3D digitization with AI, recognized trends in the application of deep learning (DL) models, and identified unexplored research areas, particularly in the mining industry.

Models such as PointNet and its variants (PointNet++, SE-PseudoGrid, among others), MaskR-CNN, KPConv, U-Net, DGCNN ConPro-NET, NVE-DGCNN and D-Net used in point cloud classification, focusing on overall infrastructures, achieved representative levels of accuracy in specific datasets as described in detail in the article.

Among these, models with high potential for use in industrial infrastructures, specially mining industry the PointNet++ spurred the development of improved models, such as ResPointNet++ and SE-PseudoGrid which stand out with accuracy higher than 97.5%. Furthermore, a thorough analysis of datasets revealed that key industrial structural components include Pipework, CLOI, and PSNet5. These datasets play a critical role in evaluating DL models tailored to interpreting 3D industrial infrastructures.

Overall, the application of DL models has resulted in quantifiable improvements, demonstrating their exceptional performance in semantic segmentation and classification tasks. However, there are still some areas such as the mining sector where there is no evidence in Scopus where the use of such DL models has been used in industrial infrastructures.

This study is distinguished not only by its thorough examination of DL models utilized in the 3D digitalization of industrial, construction, transport, and ISPS sectors, but also by its exploration of the models' competencies in performing specific tasks. These tasks range from the semantic segmentation of industrial components to the identification of architectural structures within construction and urban settings. The analysis encompasses the classification of the elements under consideration, as well as a synthesis of relevant metrics, including mAcc. This investigation promotes the integration of AI-driven technologies within infrastructures. Furthermore, it underscores critical gaps in the existing literature, thereby motivating future inquiries to overcome these identified limitations.

ACKNOWLEDGMENT

This work was supported by ProInnovate (Grant number: PIEC1-6-F-236-20) from the Ministry of Production of Peru, which backed the project titled: "Desarrollo de un software inteligente de reconocimiento de elementos geométricos (tuberías, vigas, muros, y otros) de plantas mineras para la generación de maquetas 3D usando Machine Learning".

REFERENCES

- [1] Agapaki, E., Miatt, G., Brilakis, I. (2018). Prioritizing object types for modelling existing industrial facilities. *Automation in Construction*, 96: 211-223. <https://doi.org/10.1016/j.autcon.2018.09.011>
- [2] Dou, Y., Li, T., Li, L., Zhang, Y., Li, Z. (2023). Tracking the research on ten emerging digital technologies in the AECO industry. *Journal of Construction Engineering and Management*, 149(3): 03123003. <https://doi.org/10.1061/JCEMD4.COENG-12290>
- [3] Agapaki E., Brilakis I. (2018). State-of-practice on as-is modelling of industrial facilities. In *Advanced Computing Strategies for Engineering*, Springer, Cham, pp. 103-124.
- [4] Bejan, A. (2015). *Constructal thermodynamics*. In *Constructal Law & Second Law Conference*, Parma, pp. S1-S8.
- [5] Malinverni, E., Pierdicca, R., Paolanti, M., Martini, M., Morbidoni, C., Matrone, F., Lingua, A. (2019). Deep learning for semantic segmentation of 3D point clouds. *International Archives of the Photogrammetry, Remote Sensing & Spatial Information Sciences*, 42: 735-742. <https://doi.10.5194/isprs-archives-XLII-2-W15-735-2019>
- [6] Qi, C.R., Su, H., Mo, K., Guibas, L.J. (2017). Pointnet: Deep learning on point sets for 3D classification and segmentation. In *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*, pp. 652-660. <https://doi.org/10.1109/CVPR.2017.16>
- [7] Qi, C.R., Yi, L., Su, H., Guibas, L.J. (2017). Pointnet++: Deep hierarchical feature learning on point sets in a metric space. *Advances in Neural Information Processing Systems*, 30: 5105-5114. <https://doi.org/10.48550/arXiv.1706.02413>
- [8] Yin, C., Wang, B., Gan, V., Wang, M., Cheng, J. (2021). Automated semantic segmentation of industrial point clouds using ResPointNet++. *Automation in Construction*, 130: 103874. <https://doi.org/10.1016/j.autcon.2021.103874>
- [9] Yin, C., Cheng, J.C., Wang, B., Gan, V.J. (2022). Automated classification of piping components from 3D LiDAR point clouds using SE-PseudoGrid. *Automation in Construction*, 139: 104300. <https://doi.org/10.1016/j.autcon.2022.104300>
- [10] Kitchenham, B., Brereton, O.P., Budgen, D., Turner, M., Bailey, J., Linkman, S. (2009). Systematic literature reviews in software engineering—A systematic literature review. *Information and Software Technology*, 51(1): 7-15. <https://doi.org/10.1016/j.infsof.2008.09.009>
- [11] Garg, K.C., Singh, R.K. (2022). Library and Information Science Research (LISR): A bibliometric study of papers published during 1994–2020. *DESIDOC Journal of Library and Information Technology*, 42(1): 57-63. <https://doi.org/10.14429/djlit.42.2.17480>
- [12] Van Eck, N.J., Waltman, L. (2022). VOSviewer Manual. https://www.vosviewer.com/documentation/Manual_VOSviewer_1.6.18.pdf
- [13] Yeo, C., Kim, S., Kim, H., Kim, S., Mun, D. (2020). Deep learning applications in an industrial process plant: Repository of segmented point clouds for pipework components. *JMST Advances*, 2(1): 15-24. <https://doi.org/10.1007/s42791-019-00027-y>
- [14] Yan, Y., Yan, H., Guo, J., Dai, H. (2020). Classification and segmentation of mining area objects in large-scale spares lidar point cloud using a novel rotated density network. *ISPRS International Journal of Geo-Information*, 9(3): 182. <https://doi.org/10.3390/ijgi9030182>
- [15] Agapaki, E., Brilakis, I. (2020). CLOI-NET: Class segmentation of industrial facilities' point cloud datasets. *Advanced Engineering Informatics*, 45: 101121. <https://doi.org/10.1016/j.aei.2020.101121>
- [16] Perez-Perez, Y., Golparvar-Fard, M., El-Rayes, K.

- (2021). Scan2BIM-NET: Deep learning method for segmentation of point clouds for scan-to-BIM. *Journal of Construction Engineering and Management*, 147(9): 04021107. [https://doi.org/10.1061/\(ASCE\)CO.1943-7862.0002132](https://doi.org/10.1061/(ASCE)CO.1943-7862.0002132)
- [17] Martin-Abadal, M., Piñar-Molina, M., Martorell-Torres, A., Oliver-Codina, G., Gonzalez-Cid, Y. (2020). Underwater pipe and valve 3D recognition using deep learning segmentation. *Journal of Marine Science and Engineering*, 9(1): 5. <https://doi.org/10.3390/jmse9010005>
- [18] Shigeta, K., Masuda, H. (2021). Extraction and recognition of components from point clouds of industrial plants. *Computer-Aided Design & Applications*, 18(5): 890-899. <https://doi.org/10.14733/cadaps.2021.890-899>
- [19] Agapaki, E., Brilakis, I. (2021). CLOI: An automated benchmark framework for generating geometric digital twins of industrial facilities. *Journal of Construction Engineering and Management*, 147(11): 04021145. [https://doi.org/10.1061/\(ASCE\)CO.1943-7862.00021](https://doi.org/10.1061/(ASCE)CO.1943-7862.00021)
- [20] Saydam, S., Liu, B., Li, B., Zhang, W., Singh, S.K., Raval, S. (2021). A coarse-to-fine approach for rock bolt detection from 3D point clouds. *IEEE Access*, 9: 148873-148883. <https://doi.org/10.1109/ACCESS.2021.3120207>
- [21] Perez-Perez, Y., Golparvar-Fard, M., El-Rayes, K. (2021). Segmentation of point clouds via joint semantic and geometric features for 3D modeling of the built environment. *Automation in Construction*, 125: 103584. <https://doi.org/10.1016/j.autcon.2021.103584>
- [22] Kim, J., Chung, D., Kim, Y., Kim, H. (2022). Deep learning-based 3D reconstruction of scaffolds using a robot dog. *Automation in Construction*, 134: 104092. <https://doi.org/10.1016/j.autcon.2021.104092>
- [23] Wang, B., Wang, Q., Cheng, J.C., Yin, C. (2022). Object verification based on deep learning point feature comparison for scan-to-BIM. *Automation in Construction*, 142: 104515. <https://doi.org/10.1016/j.autcon.2022.104515>
- [24] Martin-Abadal, M., Oliver-Codina, G., Gonzalez-Cid, Y. (2022). Real-time pipe and valve characterisation and mapping for autonomous underwater intervention tasks. *Sensors*, 22(21): 8141. <https://doi.org/10.3390/s22218141>
- [25] Xu, Z., Kang, R., Li, H. (2022). Feature-based deep learning classification for pipeline component extraction from 3D point clouds. *Buildings*, 12(7): 968. <https://doi.org/10.3390/buildings12070968>
- [26] Collins, F.C., Ringsquandl, M., Braun, A., Hall, D.M., Borrmann, A. (2022). Shape encoding for semantic healing of design models and knowledge transfer to scan-to-BIM. *Proceedings of the Institution of Civil Engineers-Smart Infrastructure and Construction*, 175(4): 160-180. <https://doi.org/10.1680/jsmic.21.00032>
- [27] Kim, J., Kim, J., Kim, Y., Kim, H. (2023). 3D reconstruction of large-scale scaffolds with synthetic data generation and an upsampling adversarial network. *Automation in Construction*, 156: 105108. <https://doi.org/10.1016/j.autcon.2023.105108>
- [28] Wang, G., Wang, L., Wu, S., Zu, S., Song, B. (2023). Semantic segmentation of transmission corridor 3D point clouds based on CA-PointNet++. *Electronics*, 12(13): 2829. <https://doi.org/10.3390/electronics12132829>
- [29] Vidanes, G., Toal, D., Zhang, X., Keane, A., Gregory, J., Nunez, M. (2024). Extending point-based deep learning approaches for better semantic segmentation in CAD. *Computer-Aided Design*, 166: 103629. <https://doi.org/10.1016/j.cad.2023.103629>
- [30] Birkeland, A.A., Udnæs, M. (2024). Semi-automated dataset creation for semantic and instance segmentation of industrial point clouds. *Computers in Industry*, 155: 104064. <https://doi.org/10.1016/j.compind.2023.104064>
- [31] Imabuchi, T., Kawabata, K. (2024). Discrimination of plant structures in 3D point cloud through back-projection of labels derived from 2D semantic segmentation. *Journal of Robotics and Mechatronics*, 36(1): 63-70. <https://doi.org/10.20965/jrm.2024.p0063>
- [32] Kim, H., Yoon, J., Sim, S.H. (2020). Automated bridge component recognition from point clouds using deep learning. *Structural Control and Health Monitoring*, 27(9): e2591. <https://doi.org/10.1002/stc.2591>
- [33] Sun, W., Zhang, Z., Huang, J. (2020). RobNet: Real-time road-object 3D point cloud segmentation based on SqueezeNet and cyclic CRF. *Soft Computing*, 24(8): 5805-5818. <https://doi.org/10.1007/s00500-019-04355-y>
- [34] Wang, D., Wang, J., Scaioni, M., Si, Q. (2019). Coarse-to-fine classification of road infrastructure elements from mobile point clouds using symmetric ensemble point network and Euclidean cluster extraction. *Sensors*, 20(1): 225. <https://doi.org/10.3390/s20010225>
- [35] Park, G., Lee, J.H., Yoon, H. (2021). Semantic structure from motion for railroad bridges using deep learning. *Applied Sciences*, 11(10): 4332. <https://doi.org/10.3390/app11104332>
- [36] Koo, B., Jung, R., Yu, Y., Kim, I. (2021). A geometric deep learning approach for checking element-to-entity mappings in infrastructure building information models. *Journal of Computational Design and Engineering*, 8(1): 239-250. <https://doi.org/10.1093/jcde/qwaa075>
- [37] Saovana, N., Yabuki, N., Fukuda, T. (2021). Automated point cloud classification using an image-based instance segmentation for structure from motion. *Automation in Construction*, 129: 103804. <https://doi.org/10.1016/j.autcon.2021.103804>
- [38] Liu, S., Tu, X., Xu, C., Chen, L., Lin, S., Li, R. (2021). An optimized deep neural network for overhead contact system recognition from LiDAR point clouds. *Remote Sensing*, 13(20): 4110. <https://doi.org/10.3390/rs13204110>
- [39] Grandio, J., Riveiro, B., Soilán, M., Arias, P. (2022). Point cloud semantic segmentation of complex railway environments using deep learning. *Automation in Construction*, 141: 104425. <https://doi.org/10.1016/j.autcon.2022.104425>
- [40] Jing, Y., Sheil, B., Acikgoz, S. (2022). Segmentation of large-scale masonry arch bridge point clouds with a synthetic simulator and the BridgeNet neural network. *Automation in Construction*, 142: 104459. <https://doi.org/10.1016/j.autcon.2022.104459>
- [41] Xu, T., Gao, X., Yang, Y., Xu, L., Xu, J., Wang, Y. (2022). Construction of a semantic segmentation network for the overhead catenary system point cloud based on multi-scale feature fusion. *Remote Sensing*, 14(12): 2768. <https://doi.org/10.3390/rs14122768>
- [42] Li, H.T., Todd, Z., Bielski, N., Carroll, F. (2022). 3D lidar point-cloud projection operator and transfer machine learning for effective road surface features

- detection and segmentation. *The Visual Computer*, 38(5): 1759-1774. <https://doi.org/10.1007/s00371-021-02103-8>
- [43] Eickeler, F., Borrmann, A. (2022). Enhancing railway detection by priming neural networks with project exaptations. *Remote Sensing*, 14(21): 5482. <https://doi.org/10.3390/rs14215482>
- [44] Xia, T., Yang, J., Chen, L. (2022). Automated semantic segmentation of bridge point cloud based on local descriptor and machine learning. *Automation in Construction*, 133: 103992. <https://doi.org/10.1016/j.autcon.2021.103992>
- [45] Lin, Y.C., Habib, A. (2022). Semantic segmentation of bridge components and road infrastructure from mobile LiDAR data. *ISPRS Open Journal of Photogrammetry and Remote Sensing*, 6: 100023. <https://doi.org/10.1016/j.ophoto.2022.100023>
- [46] Ton, B., Ahmed, F., Linssen, J. (2022). Semantic segmentation of terrestrial laser scans of railway catenary arches: A use case perspective. *Sensors*, 23(1): 222. <https://doi.org/10.3390/s23010222>
- [47] Grandio, J., Riveiro, B., Lamas, D., Arias, P. (2023). Multimodal deep learning for point cloud panoptic segmentation of railway environments. *Automation in Construction*, 150: 104854. <https://doi.org/10.1016/j.autcon.2023.104854>
- [48] Tardy, H., Soilán, M., Martín-Jiménez, J.A., González-Aguilera, D. (2023). Automatic road inventory using a low-cost mobile mapping system and based on a semantic segmentation deep learning model. *Remote Sensing*, 15(5): 1351. <https://doi.org/10.3390/rs15051351>
- [49] Wang, Z., Geng, Y., Jia, L., Qin, Y., Chai, Y., Tong, L., Liu, K. (2023). Self-attentive local aggregation learning with prototype guided regularization for point cloud semantic segmentation of high-speed railways. *IEEE Transactions on Intelligent Transportation Systems*, 24(10): 11157-11170. <https://doi.org/10.1109/TITS.2023.3281352>
- [50] Kim, M.K., Park, D., Yun, S., Park, W.H., Lee, D., Chung, J.D., Chung, K.J. (2023). Establishment of a landscape information model (LIM) and AI convergence plan through the 3D digital transformation of railway surroundings. *Drones*, 7(3): 167. <https://doi.org/10.3390/drones7030167>
- [51] Mirzazade, A., Popescu, C., Gonzalez-Libreros, J., Blanksvärd, T., Täljsten, B., Sas, G. (2023). Semi-autonomous inspection for concrete structures using digital models and a hybrid approach based on deep learning and photogrammetry. *Journal of Civil Structural Health Monitoring*, 13(8): 1633-1652. <https://doi.org/10.1007/s13349-023-00680-x>
- [52] Huo, S., Liu, Y., Wang, J., Li, R., Liu, X., Shi, J. (2023). A pre-processing module for point-based deep learning in dense point clouds in the ship engineering field. *Journal of Marine Science and Engineering*, 11(12): 2248. <https://doi.org/10.3390/jmse11122248>
- [53] Wang, Y., Wang, W., Liu, J., Chen, T., Wang, S., Yu, B., Qin, X. (2023). Framework for geometric information extraction and digital modeling from LiDAR data of road scenarios. *Remote Sensing*, 15(3): 576. <https://doi.org/10.3390/rs15030576>
- [54] Ji, A., Zhang, L., Fan, H., Xue, X., Dou, Y. (2023). Dual attention-based deep learning network for multi-class object semantic segmentation of tunnel point clouds. *Automation in Construction*, 156: 105131. <https://doi.org/10.1016/j.autcon.2023.105131>
- [55] Jiang, T., Yang, B., Wang, Y., Dai, L., Qiu, B., Liu, S., Li, S., Zhang, Q., Jin, X., Zeng, W. (2023). RailSeg: Learning local-global feature aggregation with contextual information for railway point cloud semantic segmentation. *IEEE Transactions on Geoscience and Remote Sensing*, 61: 1-29. <https://doi.org/10.1109/TGRS.2023.3319950>
- [56] Martens, J., Blut, T., Blankenbach, J. (2023). Cross domain matching for semantic point cloud segmentation based on image segmentation and geometric reasoning. *Advanced Engineering Informatics*, 57: 102076. <https://doi.org/10.1016/j.aei.2023.102076>
- [57] Li, J., Zhang, Z., Sun, H., Xie, S., Zou, J., Ji, C., Lu, Y., Ren, X., Wang, L. (2023). GL-Net: Semantic segmentation for point clouds of shield tunnel via global feature learning and local feature discriminative aggregation. *ISPRS Journal of Photogrammetry and Remote Sensing*, 199: 335-349. <https://doi.org/10.1016/j.isprsjprs.2023.04.011>
- [58] Wang, Y., Liu, X., Zhao, Q., He, H., Yao, Z. (2023). Target detection for construction machinery based on deep learning and multisource data fusion. *IEEE Sensors Journal*, 23(10): 11070-11081. <https://doi.org/10.1109/JSEN.2023.3264526>
- [59] Mansour, M., Martens, J., Blankenbach, J. (2024). Hierarchical SVM for semantic segmentation of 3D point clouds for infrastructure scenes. *Infrastructures*, 9(5): 83. <https://doi.org/10.3390/infrastructures9050083>
- [60] Kang, J., Chen, N., Li, M., Mao, S., Zhang, H., Fan, Y., Liu, H. (2023). A point cloud segmentation method for dim and cluttered underground tunnel scenes based on the segment anything model. *Remote Sensing*, 16(1): 97. <https://doi.org/10.3390/rs16010097>
- [61] Lin, W., Sheil, B., Zhang, P., Zhou, B., Wang, C., Xie, X. (2024). Seg2Tunnel: A hierarchical point cloud dataset and benchmarks for segmentation of segmental tunnel linings. *Tunnelling and Underground Space Technology*, 147: 105735. <https://doi.org/10.1016/j.tust.2024.105735>
- [62] Kharroubi, A., Ballouch, Z., Hajji, R., Yarroudh, A., Billen, R. (2024). Multi-context point cloud dataset and machine learning for railway semantic segmentation. *Infrastructures*, 9(4): 71. <https://doi.org/10.3390/infrastructures9040071>
- [63] Vassilev, H., Laska, M., Blankenbach, J. (2024). Uncertainty-aware point cloud segmentation for infrastructure projects using Bayesian deep learning. *Automation in Construction*, 164: 105419. <https://doi.org/10.1016/j.autcon.2024.105419>
- [64] Comesaña-Cebral, L., Martínez-Sánchez, J., Seoane, A. N., Arias, P. (2024). Transport infrastructure management based on LiDAR synthetic data: A deep learning approach with a ROADSENSE simulator. *Infrastructures*, 9(3): 58. <https://doi.org/10.3390/infrastructures9030058>
- [65] Saovana, N., Yabuki, N., Fukuda, T. (2020). Development of an unwanted-feature removal system for Structure from Motion of repetitive infrastructure piers using deep learning. *Advanced Engineering Informatics*, 46: 101169. <https://doi.org/10.1016/j.aei.2020.101169>
- [66] Zeng, S., Chen, J., Cho, Y.K. (2020). User exemplar-based building element retrieval from raw point clouds

- using deep point-level features. *Automation in Construction*, 114: 103159. <https://doi.org/10.1016/j.autcon.2020.103159>
- [67] Barrile, V., Bernardo, E., Candela, G., Bilotta, G., Modafferi, A., Fotia, A. (2020). Road infrastructure heritage: From scan to infrabim. *Wseas Transactions on Environment and Development*, 16: 633-642.
- [68] Braun, A., Tuttas, S., Borrmann, A., Stilla, U. (2020). Improving progress monitoring by fusing point clouds, semantic data and computer vision. *Automation in Construction*, 116: 103210. <https://doi.org/10.1016/j.autcon.2020.103210>
- [69] Jiang, Y., Han, S., Bai, Y. (2021). Building and infrastructure defect detection and visualization using drone and deep learning technologies. *Journal of Performance of Constructed Facilities*, 35(6): 04021092. [https://doi.org/10.1061/\(ASCE\)CF.1943-5509.0001652](https://doi.org/10.1061/(ASCE)CF.1943-5509.0001652)
- [70] Xu, Y., Shen, X., Lim, S. (2021). Cordet: Corner-aware 3D object detection networks for automated scan-to-BIM. *Journal of Computing in Civil Engineering*, 35(3): 04021002. [https://doi.org/10.1061/\(ASCE\)CP.1943-5487.0000962](https://doi.org/10.1061/(ASCE)CP.1943-5487.0000962)
- [71] Pan, Y., Braun, A., Borrmann, A., Brilakis, I. (2022). 3D deep-learning-enhanced void-growing approach in creating geometric digital twins of buildings. *Proceedings of the Institution of Civil Engineers-Smart Infrastructure and Construction*, 176(1): 24-40. <https://doi.org/10.1680/jsmic.21.00035>
- [72] Zoumpikas, T., Salamó, M., Puig, A. (2022). Rethinking design and evaluation of 3D point cloud segmentation models. *Remote Sensing*, 14(23): 6049. <https://doi.org/10.3390/rs14236049>
- [73] Vega Torres, M.A., Braun, A., Noichl, F., Borrmann, A., Bauer, H., Wohlfeld, D. (2022). Recognition of temporary vertical objects in large point clouds of construction sites. *Proceedings of the Institution of Civil Engineers-Smart Infrastructure and Construction*, 174(4): 134-149. <https://doi.org/10.1680/jsmic.21.00033>
- [74] Muftah, H., Rowan, T.S.L., Butler, A.P. (2022). Towards open-source LOD2 modelling using convolutional neural networks. *Modeling Earth Systems and Environment*, 8(2): 1693-1709. <https://doi.org/10.1007/s40808-021-01159-8>
- [75] Shu, J., Li, W., Zhang, C., Gao, Y., Xiang, Y., Ma, L. (2023). Point cloud-based dimensional quality assessment of precast concrete components using deep learning. *Journal of Building Engineering*, 70: 106391. <https://doi.org/10.1016/j.jobe.2023.106391>
- [76] Fang, X., Li, H., Wu, H., Fan, L., Kong, T., Wu, Y. (2023). A fast end-to-end method for automatic interior progress evaluation using panoramic images. *Engineering Applications of Artificial Intelligence*, 126: 106733. <https://doi.org/10.1016/j.engappai.2023.106733>
- [77] An, J., Zhang, J., Ma, M. (2023). Research on the intelligent auxiliary design of subway station building space based on deep learning. *Applied Sciences*, 13(16): 9242. <https://doi.org/10.3390/app13169242>
- [78] Hsieh, C.S., Ruan, X.J. (2023). Automated semantic segmentation of indoor point clouds from close-range images with three-dimensional deep learning. *Buildings*, 13(2): 468. <https://doi.org/10.3390/buildings13020468>
- [79] Maru, M.B., Wang, Y., Kim, H., Yoon, H., Park, S. (2023). Improved building facade segmentation through digital twin-enabled RandLA-Net with empirical intensity correction model. *Journal of Building Engineering*, 78: 107520. <https://doi.org/10.1016/j.jobe.2023.107520>
- [80] Yue, H., Lehtola, V., Wu, H., Vosselman, G., Li, J., Liu, C. (2024). Recognition of indoor scenes using 3D scene graphs. *IEEE Transactions on Geoscience and Remote Sensing*, 62: 5703216. <https://doi.org/10.1109/TGRS.2024.3387556>
- [81] Bahreini, F., Hammad, A. (2024). Dynamic graph CNN based semantic segmentation of concrete defects and as-inspected modeling. *Automation in Construction*, 159: 105282. <https://doi.org/10.1016/j.autcon.2024.105282>
- [82] Reja, V.K., Goyal, S., Varghese, K., Ravindran, B., Ha, Q.P. (2024). Hybrid self-supervised learning-based architecture for construction progress monitoring. *Automation in Construction*, 158: 105225. <https://doi.org/10.1016/j.autcon.2023.105225>
- [83] Pal, A., Lin, J.J., Hsieh, S.H., Golparvar-Fard, M. (2024). Activity-level construction progress monitoring through semantic segmentation of 3D-informed orthographic images. *Automation in Construction*, 157: 105157. <https://doi.org/10.1016/j.autcon.2023.105157>
- [84] Liang, H., Yeoh, J.K., Chua, D.K. (2024). Material augmented semantic segmentation of point clouds for building elements. *Computer-Aided Civil and Infrastructure Engineering*, 39(15): 2312-2329. <https://doi.org/10.1111/mice.13198>
- [85] Li, X., Wang, L., Wang, M., Wen, C., Fang, Y. (2020). DANCE-NET: Density-aware convolution networks with context encoding for airborne LiDAR point cloud classification. *ISPRS Journal of Photogrammetry and Remote Sensing*, 166: 128-139. <https://doi.org/10.1016/j.isprsjprs.2020.05.023>
- [86] Ponciano, J.J., Roetner, M., Reiterer, A., Boochs, F. (2021). Object semantic segmentation in point clouds—Comparison of a deep learning and a knowledge-based method. *ISPRS International Journal of Geo-Information*, 10(4): 256. <https://doi.org/10.3390/ijgi10040256>
- [87] Zou, Y., Weinacker, H., Koch, B. (2021). Towards urban scene semantic segmentation with deep learning from LiDAR point clouds: A case study in Baden-Württemberg, Germany. *Remote Sensing*, 13(16): 3220. <https://doi.org/10.3390/rs13163220>
- [88] Ma, B., Du, J., Wang, L., Jiang, H., Zhou, M. (2021). Automatic branch detection of jujube trees based on 3D reconstruction for dormant pruning using the deep learning-based method. *Computers and Electronics in Agriculture*, 190: 106484. <https://doi.org/10.1016/j.compag.2021.106484>
- [89] Sun, C., Zhang, F., Zhao, P., Zhao, X., Huang, Y., Lu, X. (2021). Automated simulation framework for urban wind environments based on aerial point clouds and deep learning. *Remote Sensing*, 13(12): 2383. <https://doi.org/10.3390/rs13122383>
- [90] Chen, S., Zhang, Z., Zhong, R., Zhang, L., Ma, H., Liu, L. (2020). A dense feature pyramid network-based deep learning model for road marking instance segmentation using MLS point clouds. *IEEE Transactions on Geoscience and Remote Sensing*, 59(1): 784-800. <https://doi.org/10.1109/TGRS.2020.2996617>
- [91] Chen, Q., Zhang, Z., Chen, S., Wen, S., Ma, H., Xu, Z. (2022). A self-attention based global feature enhancing network for semantic segmentation of large-scale urban street-level point clouds. *International Journal of Applied*

- Earth Observation and Geoinformation, 113: 102974. <https://doi.org/10.1016/j.jag.2022.102974>
- [92] Fang, L., You, Z., Shen, G., Chen, Y., Li, J. (2022). A joint deep learning network of point clouds and multiple views for roadside object classification from lidar point clouds. *ISPRS Journal of Photogrammetry and Remote Sensing*, 193: 115-136. <https://doi.org/10.1016/j.isprsjprs.2022.08.022>
- [93] Schmohl, S., Narváez Vallejo, A., Soergel, U. (2022). Individual tree detection in urban ALS point clouds with 3D convolutional networks. *Remote Sensing*, 14(6): 1317. <https://doi.org/10.3390/rs14061317>
- [94] Li, J., Weinmann, M., Sun, X., Diao, W., Feng, Y., Hinz, S., Fu, K. (2022). VD-LAB: A view-decoupled network with local-global aggregation bridge for airborne laser scanning point cloud classification. *ISPRS Journal of Photogrammetry and Remote Sensing*, 186: 19-33. <https://doi.org/10.1016/j.isprsjprs.2022.01.012>
- [95] Hu, H., Zhang, G., Ao, J., Wang, C., Kang, R., Wu, Y. (2023). Multi-information PointNet++ fusion method for DEM construction from airborne LiDAR data. *Geocarto International*, 38(1): 2153929. <https://doi.org/10.1080/10106049.2022.2153929>
- [96] Zhao, D., Ji, L., Yang, F. (2023). Land cover classification based on airborne lidar point cloud with possibility method and multi-classifier. *Sensors*, 23(21): 8841. <https://doi.org/10.3390/s23218841>
- [97] Zabolli, M., Rastiveis, H., Hosseiny, B., Shokri, D., Sarasua, W.A., Homayouni, S. (2023). D-Net: A density-based convolutional neural network for mobile LiDAR point clouds classification in urban areas. *Remote Sensing*, 15(9): 2317. <https://doi.org/10.3390/rs15092317>
- [98] Wang, P., Tang, Y., Liao, Z., Yan, Y., Dai, L., Liu, S., Jiang, T. (2023). Road-side individual tree segmentation from urban MLS point clouds using metric learning. *Remote Sensing*, 15(8): 1992. <https://doi.org/10.3390/rs15081992>
- [99] Zhou, Y., Ji, A., Zhang, L., Xue, X. (2023). Sampling-attention deep learning network with transfer learning for large-scale urban point cloud semantic segmentation. *Engineering Applications of Artificial Intelligence*, 117: 105554. <https://doi.org/10.1016/j.engappai.2022.105554>
- [100] Shao, J., Yao, W., Wang, P., He, Z., Luo, L. (2024). Urban GeoBIM construction by integrating semantic LiDAR point clouds with as-designed BIM models. *IEEE Transactions on Geoscience and Remote Sensing*, 62: 1-12. <https://doi.org/10.1109/TGRS.2024.3358370>
- [101] Ballouch, Z., Hajji, R., Kharroubi, A., Poux, F., Billen, R. (2024). Investigating prior-level fusion approaches for enriched semantic segmentation of urban LiDAR point clouds. *Remote Sensing*, 16(2): 329. <https://doi.org/10.3390/rs16020329>
- [102] Guo, Y., Wang, H., Hu, Q., Liu, H., Liu, L., Bennamoun, M. (2020). Deep learning for 3D point clouds: A survey. *IEEE Transactions on Pattern Analysis and Machine Intelligence*, 43(12): 4338-4364. <https://doi.org/10.1109/TPAMI.2020.3005434>