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Enhancing Energy Efficiency in Sensor Cloud Through Time Series Forecasting of Sensor Data



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ABSTRACT

In today's interconnected world, diverse sensor types are critical for powering various applications and services. The limited energy resources of these sensors present a significant challenge in managing sensor networks efficiently. To address this, we propose an energy-saving sensor cloud that utilizes a data prediction technique. Typically, a sensor node in a Wireless Sensor Network (WSN) gathers and transmits data to the cloud every 10 minutes, consuming substantial energy. In contrast, our proposed method requires sensor nodes to communicate with the cloud every 110 minutes, as the cloud system's forecasting method is capable of predicting ten steps ahead, thus reducing transmission frequency. We have applied Wavelet-based Forecasting (WBF), Auto-Regressive Integrated Moving Average (ARIMA), and a hybrid ARIMA-WBF for these predictions. The ARIMA model demonstrates superior performance compared to the other techniques when dealing with linear sensor data. Our method results in a power consumption that is approximately 90.9% lower than that of traditional methods within the sensor cloud, owing to reduced data transmission frequency. Additionally, our approach yields notably lower Root Mean Square Error (RMSE) and Mean Absolute Error (MAE) in predictions.

1. INTRODUCTION

Wireless Sensor Network (WSN) techniques have gained significant traction in recent applications. Cloud computing, known for providing on-demand resources such as infrastructure and storage, has been seamlessly integrated with sensor networks to create what is known as a sensor cloud [1]. This sensor cloud [2-4] offers sensing services to end-users, enabling them to access sensor data through the cloud system. Given the limited battery life of sensors and the substantial energy required to operate data centers, the creation of an energy-efficient sensor cloud is imperative [5-7]. The energy efficiency of such a network is crucial not only because of the finite lifetime of sensor batteries but also due to the high energy demands of running cloud data centers.

The energy E_j required by a sensor S' to transmit data to a node S'' at a data rate D_r can be calculated using the following equation [8]:

$$E_i = E_1 + E' D_r P_{rec} d^{\sigma} \tag{1}$$

where, E_1 = the ideal energy consumption of the node S'. E' = Constant

 P_{rec} = Minimum energy requirement for successful decoding at the node S"

 $D_r = \text{data rate of sensor } S'$

d = distance between the node S' and S''.

σ values are between 2 and 6.

The energy consumption of WSNs is a function of data transmission rate and distance. A higher rate and longer distances of data transmission can rapidly deplete a sensor's battery.

The implementation of a forecasting system in the cloud, which predicts future sensor data, can address this energy consumption issue. With accurate forecasts, end-users can retrieve predicted data directly from the cloud, reducing the frequency of data transmissions from sensors and, thereby, conserving energy within the sensor network. Anjali et al. [9] developed a machine learning method for temperature prediction. Chu et al. [10] achieved more accurate temperature estimates by applying neural network techniques to image data. Kisi and Shiri [11] utilized ANNs and Fuzzy systems for advanced air temperature forecasting at Iranian weather stations. Afroz et al. [12] introduced a method for forecasting indoor temperatures using various parameters and training algorithms. Park et al. [13] developed a deep learning model to predict temperatures using real weather datasets. Krishnaveni and Padma [14] presented a highly efficient and accurate weather prediction method using decision tree techniques. Yang et al. [15] formulated an advanced Markov Model for indoor temperature forecasts.

In addition, Panigrahi and Behera [16] discussed a hybrid ETS-ANN model that improved time series forecasting results. They also proposed a non-linear TLBO-MFLANN model, which yielded favorable outcomes across various datasets [17]. Pattanayak et al. [18] introduced a fuzzy time series forecasting method incorporating SVM and membership values. Panigrahi and Behera [19] developed an ANN-based forecasting method enhanced by differential evolution. Izonin et al. [20] created an ensemble method using GRNN-SGTM to tackle missing data challenges in datasets. Valente and Maldonado [21] applied SVM regression with feature selection for high-frequency time series forecasting. Dantas and Oliveira [22] demonstrated how combining Exponential Smoothing, Clustering, and bootstrap aggregation could improve time series forecasting. Deng et al. [23] crafted an ensemble of SVRs for time series prediction. Jaseena and Kovoor [24] surveyed various weather forecasting techniques and predictors. Baydilli and Atila [25] analyzed the impact of hyperparameters in deep learning. Fay and Ringwood [26], as well as Aminghafari and Poggi [27], proposed Wavelet transfer models for time series forecasting. Lastly, Nury et al. [28] conducted a comparative study on the effectiveness of wavelet-ANN and wavelet-ARIMA techniques in predicting Bangladesh's temperature data.

By adopting such forecasting systems, sensor clouds can enhance their energy efficiency, extending the operational lifespan of sensor nodes and reducing the energy footprint of cloud data centers.

2. PROPOSED MODEL

In traditional models, sensor nodes gather data and transmit it to the cloud system so that the users get the information. As the sensor node of the WSN collects data every 10 minutes, and in the traditional approach, the node must send data every 10 minutes to the cloud, which will consume more energy. In our proposed method, the sensor nodes transmit with the cloud every 110 minutes as the prediction technique within the cloud system forecasts ten steps ahead forecasted value. We have used ARIMA, WBF, and ARIMA-WBF as the forecasting techniques. The accuracy of the ARIMA model is better compare to others. Due to less transmission of data from the sensors to the cloud, the proposed method is energy efficient.

The proposed model for the energy-efficient sensor cloud using the data prediction approach is shown in Figure 1.

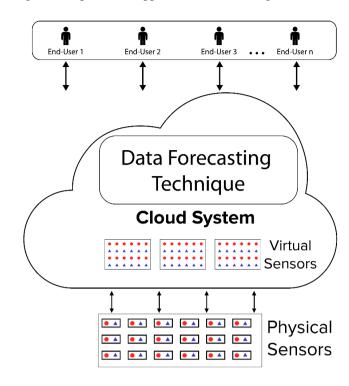


Figure 1. Data prediction-based energy-efficient sensor cloud

2.1 Data and preliminary analysis

2.1.1 Sensor datasets

Nine sensors' datasets [29] deployed at Library at the Dock and Fitzroy Gardens, Sidney, are used for the simulation. The environmental sensor measuring humidity, light levels, and temperature are analyzed. The data is collected every 10 min from 15/12/2014 to 20/05/2015 for all the nine sensors having three measurements, respectively.

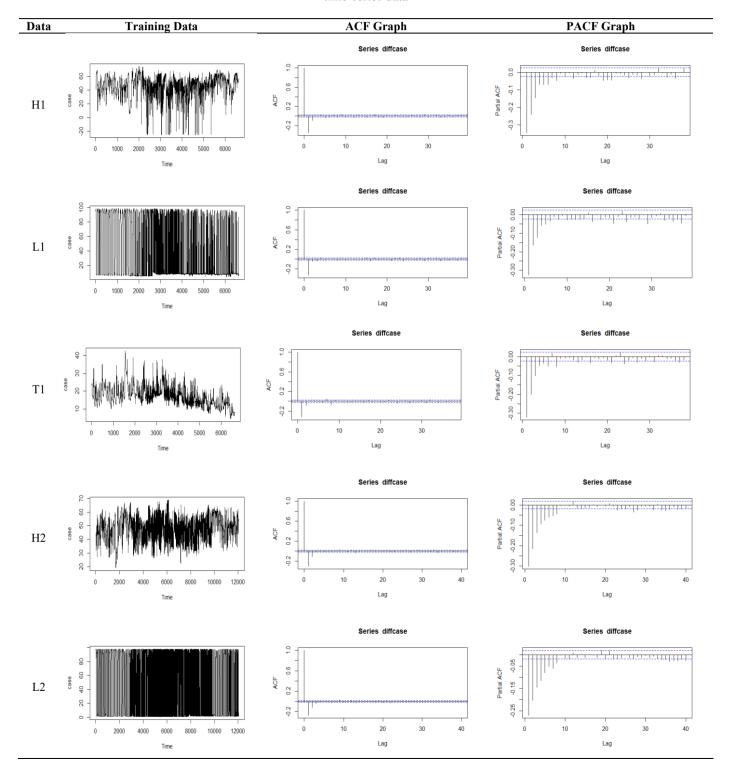
In total twenty-seven environmental sensor datasets are collected for measuring humidity, light levels, and temperature, respectively. Table 1 shows the nine environmental sensor data sets' descriptions for measuring humidity, light levels, and temperature, respectively.

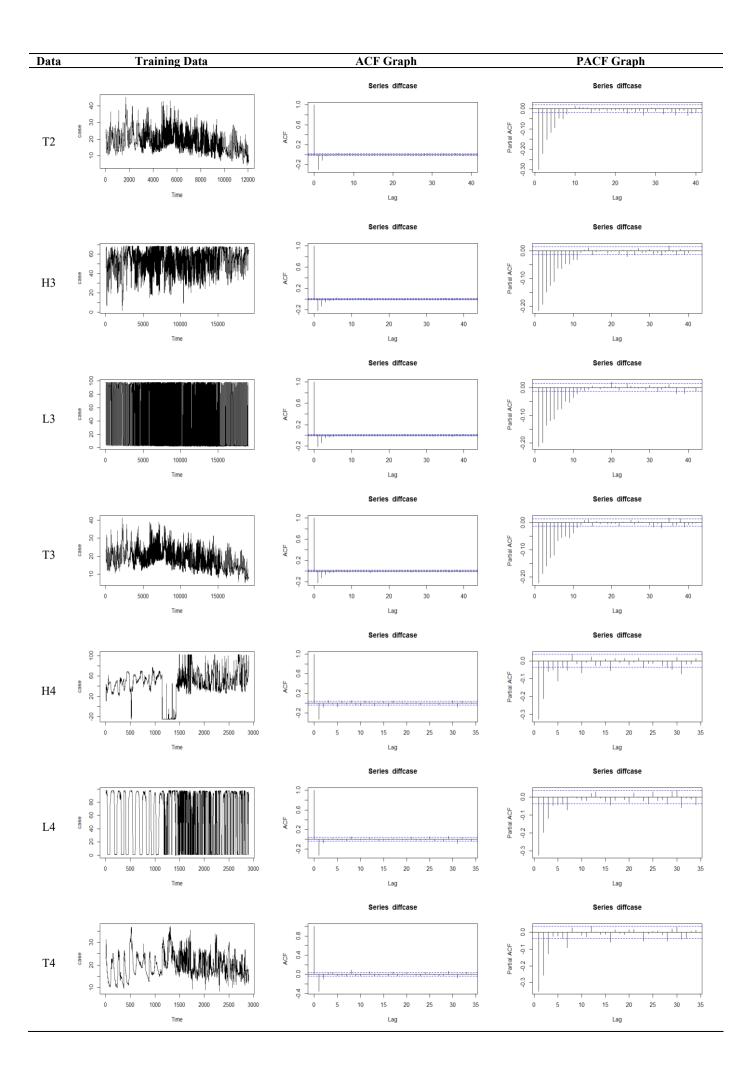
Table 1.	Descripti	ons of se	nsor data	sets of	humidity.	light, an	d temperature

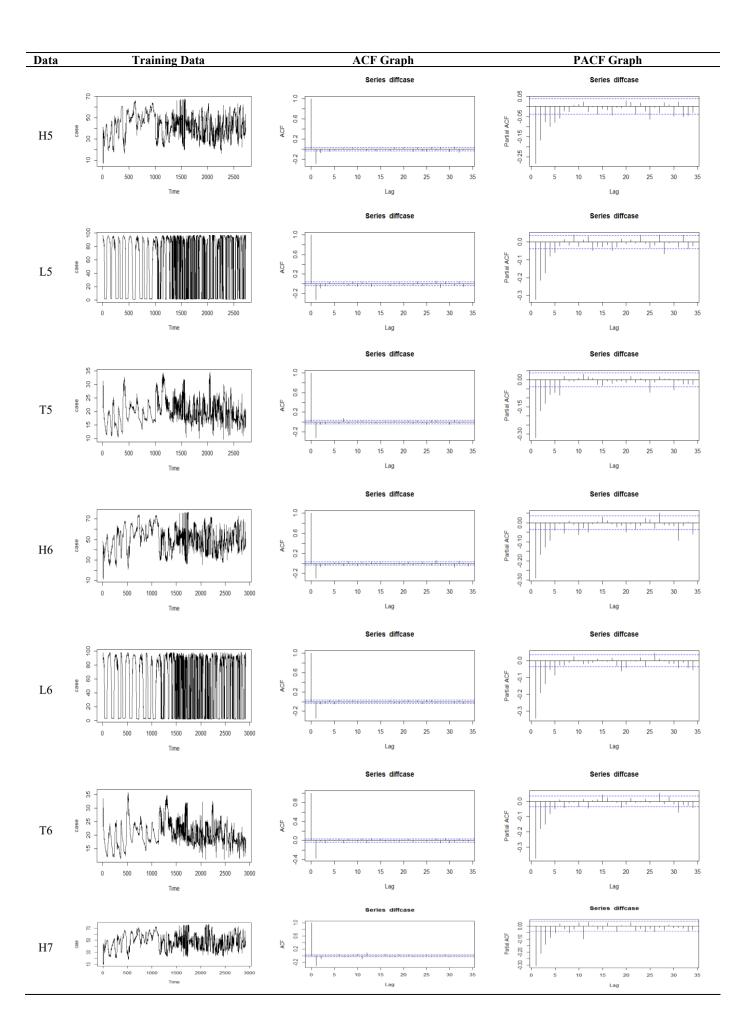
Sensor	Data	No. of Data	Min Value	Max Value	Mean	1st Quartile	Median	3 rd Quartile
1	Humidity (H1)	6626	7.00	74.30	46.12	38.50	48.60	56.30
	Light (L1)	6626	4.50	98.20	36.56	7.80	8.50	89.00
	Temperature (T1)	6626	4.50	42.60	16.88	13.20	16.50	19.40
2	Humidity (H2)	12038	19.10	69.10	48.39	42.50	49.20	54.90
	Light (L2)	12038	0.60	98.40	50.30	1.50	73.75	95.90
	Temperature (T2)	12038	4.20	45.20	18.09	13.90	17.10	21.90
3	Humidity (H3)	19119	1.50	68.60	53.53	46.10	56.20	63.00
	Light (L3)	19119	1.50	98.40	47.44	2.90	29.10	95.70
	Temperature (T3)	19119	5.20	41.30	18.18	14.20	17.40	21.30
4	Humidity (H4)	2902	1.90	102.5	44.31	35.10	47.30	60.40
	Light (L4)	2902	0.00	98.00	55.60	1.10	88.20	96.00
	Temperature (T4)	2902	8.40	37.10	19.86	16.10	19.00	23.50
5	Humidity (H5)	2727	7.00	67.70	42.27	33.50	43.30	50.80
	Light (L5)	2727	0.80	97.30	54.48	1.90	83.25	93.40
	Temperature (T5)	2727	9.70	34.50	19.91	16.80	19.00	22.30
6	Humidity (H6)	2914	11.40	76.50	50.38	42.10	51.00	59.00
	Light (L6)	2914	1.90	98.00	52.08	2.90	78.30	91.10

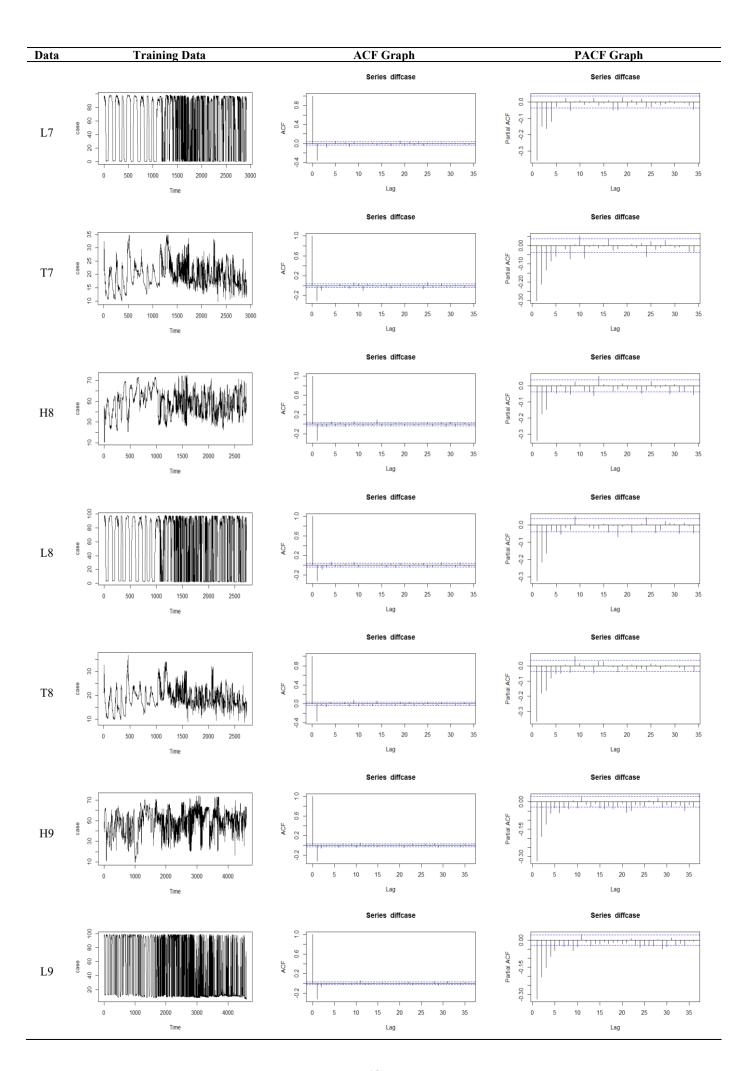
	Temperature (T6)	2914	11.00	35.80	20.42	17.70	20.00	22.90
7	Humidity (H7)	2917	10.00	76.50	47.53	37.40	48.30	57.40
	Light (L7)	2917	0.40	98.30	55.15	0.90	86.80	95.50
	Temperature (T7)	2917	9.70	34.80	19.73	16.50	19.00	22.60
8	Humidity (H8)	2724	10.90	74.90	48.68	39.30	49.90	57.60
	Light (L8)	2724	1.90	97.80	54.33	3.10	84.60	94.00
	Temperature (T8)	2724	8.70	36.8	19.03	16.10	18.10	21.90
9	Humidity (H9)	4597	9.80	74.3	48.43	41.42	50.20	56.70
	Light (L9)	4597	6.50	98.7	49.59	10.90	13.55	96.00
	Temperature (T9)	4597	5.80	43.9	19.51	16.10	18.70	21.90

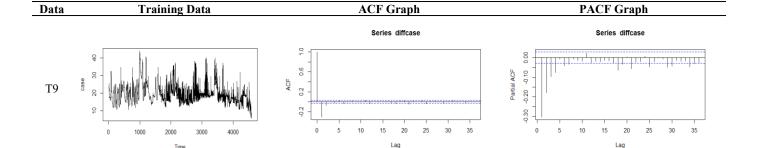
Table 2. Training sensor data sets of humidity, light, and temperature and the ACF, PACF graphs for twenty-seven univariate time-series data











2.1.2 Basic data analysis

A summary of the environmental sensor data sets for measuring humidity, light levels, and temperature are shown in Table 1.

Table 2 shows these twenty-seven sensor datasets for measuring humidity, light levels, and the temperature started with different 10 min, and these environmental curves not showing non-linear nature. We bound our attention to trend and linear models. To fit the individual conventional ARIMA model and ARIMA-WBF model, the parameters, namely p and q, are specified by plotting PACF and ACF plots (see Table 2).

2.1.3 Performance evaluation metrics

The mean absolute error (MAE) and root mean square error (RMSE) are used to evaluate [30] the performance of different forecasting models for the sensor data sets. The mathematical expressions are explained as follows:

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{y}_i)^2}$$
 (2)

$$MAE = \frac{1}{n} \sum_{i=1}^{n} |y_i - \hat{y}_i|$$
 (3)

where, \hat{y}_i is the predicted output and y_i is the actual output.

2.2 Methodology

We have used ARIMA, WBF, and ARIMA-WBF as the forecasting techniques. We have used the combination of ARIMA and WBF methods to forecast the environmental sensor for measuring humidity, light levels, and temperature.

2.2.1 ARIMA model

The ARIMA model [31] is a linear regression model. The ARIMA (p, d, q), where the model structure is decided by p, d, and q integer parameter values. The ARIMA model [32] is mathematically expressed as follows:

$$y_{t} = \theta_{0} + \varphi_{1}y_{t-1} + \varphi_{2}y_{t-2} + \dots + \varphi_{p}y_{t-p} + \varepsilon_{t} - \theta_{1}\varepsilon_{t-1} + \theta_{2}\varepsilon_{t-2} + \dots + \theta_{q}\varepsilon_{t-q}$$

$$(4)$$

where, the random error at time t is ε_t , the actual value is y_t , φ_i and θ_j are the model's coefficients. It is assumed that ε_{t-1} ($\varepsilon_{t-1} = y_{t-1} - \hat{y}_{t-1}$) has constant variance and zero mean. The methods consist of the following three iterative steps: (1) The model Identification, (2) estimation of the parameters, (3) using the residual analysis for checking the model to get the best fitted. In the first step differencing is applied to make the data stationary. Once the data is stationary, the partial autocorrelation function (PACF) and the autocorrelation function (ACF) graph are analyzed to select the MA and AR

model types. The Akaike Information Criterion (AIC) is used for the estimation of parameters. At last, residual analysis is carried out to check the model to get the best-fitted model. ARIMA model generally does not perform well in non-linear data sets, so in the next session, we have discussed the WBF model

2.2.2 WBF model

Generally, the wavelet models are used in nonstationary datasets, unlike ARIMA [33]. Most climatic and epidemic time-series analysis of datasets are nonstationary; thus, the wavelet model [34, 35] is mostly used to forecast. The selection of the optimal number of decomposition level in the WBF model is as follows:

$$W_L = int[log(m)] (5)$$

where, m is the time-series length. The working principle of a wavelet-based forecasting model is explained by Messina et al. [34]. Daubechies wavelets can generate events in so many fashions across the observed time series that most other time series forecasting models cannot recognize [36].

2.2.3 ARIMA-WBF model

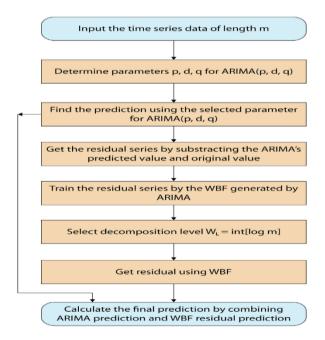


Figure 2. Flow chart for the hybrid ARIMA-WBF model

For the environmental sensor datasets, a combination of the stationary ARIMA and WBF model, which is nonstationary in nature, reduces the component models' individual biases. The present sensor datasets for twenty-seven univariate time series

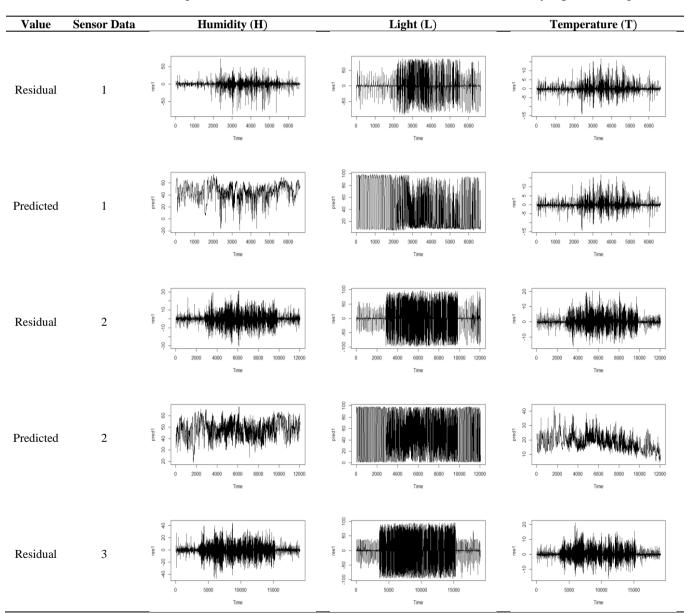
are linear. If it is non-linear, then the ARIMA model fails to produce random errors. The current sensor datasets are linear. We have used a hybrid model for proving this practically, which is a combination of WBF and ARIMA. The wavelet function is chosen to model the residual series generated from the ARIMA model. Several hybrids [37, 38] models using ARIMA and neural networks. The algorithm of the hybrid ARIMA-WBF model is described in Figure 2.

3. RESULTS AND DISCUSSION

It is challenging to study the limited environmental sensor nine datasets' characteristics and nature of measuring humidity, light, and temperature. So, we consider one significant problem relevant to the environmental sensor datasets for a total of twenty-seven sensor datasets. This paper deals with the data-driven forecasts of the ten-minute sensor datasets of measuring humidity, light, and temperature. We have used a novel parsimonious ARIMA model of the twenty-seven sensor

datasets. Hundred minutes ahead (short-term) out of sample forecasts is predicted for these twenty-seven datasets. Twentyseven univariate time series sensor datasets of humidity, light, and temperature are used to train the hybrid model and the traditional constituent models. The datasets are linear, nonstationary, and statistical tests confirmed this. We experimentally evaluate ARIMA. WBF, and hybrid ARIMA-WBF models for all these twenty-seven sensor datasets. We have used MAE and RMSE for the evaluation of the predictive performance [39] of the models. We start evaluating our experiment for the twenty-seven univariate ten min time series datasets with the ARIMA model using the 'forecast' [40] package in R. We fit the wavelet model using the ARIMA function. Once the ARIMA is fitted, predictions are generated ten steps ahead for short-term forecasts for all the twentyseven sensor datasets measuring humidity, light, and temperature. We compute the predicted values of training data and analyze the residual errors using traditional and advanced individual models, namely ARIMA and the hybrid ARIMA-WBF model. Plots of the residual series are given in Table 3.

Table 3. Plots of residuals and predicted values of sensor data sets for ARIMA model for humidity, light, and temperature



Value	Sensor Data	Humidity (H)	Light (L)	Temperature (T)
Predicted	3	8 -	8 0 0 10000 15000 Time	95 - 10 95 - 1
Residual	4	8 - 0 500 1000 1500 2000 2500 3000 Time	8 0 500 1000 1500 2000 2500 3000 Time	90 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Predicted	4	8 8 0 500 1000 1500 2000 2500 3000 Time	8	88 8 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9
Residual	5	R O 500 1000 1500 2000 2500	\$ - 0 500 1000 1500 2000 2500 Time	20 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Predicted	5	8 8 9 0 1000 1500 2000 2500 Time	8	8 - 2 - 4 - 4 - 4 - 4 - 4 - 4 - 4 - 4 - 4
Residual	6	R 0 500 1000 1500 2000 2500 3000	8	© 0 0 1000 1500 2000 2500 3000 Time
Predicted	6	8 - 0 500 1000 1500 2000 2500 3000 Time	8	\$8 \$9 \$9 \$9 \$9 \$9 \$9 \$9 \$9 \$9 \$9 \$9 \$9 \$9
Residual	7	Q Q Q Q Q Q Q Q Q Q Q Q Q Q Q Q Q Q Q	8 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	9 0 0 0 1000 1500 2000 2500 3000 Time

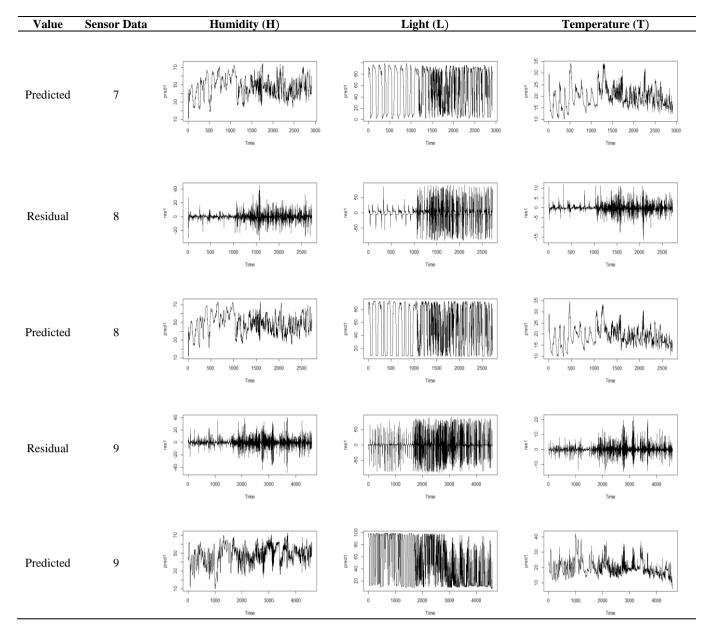


Table 4. ARIMA models of sensor data sets of humidity, light and temperature

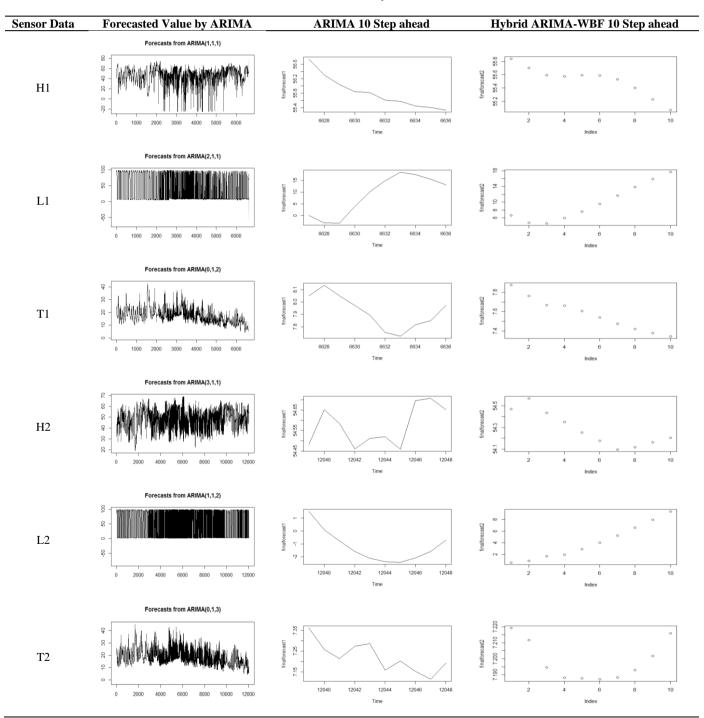
Sensor Data	ARIMA (p,d,q)	ARIMA Model
H1	(1,1,1)	$\widehat{\Delta y_t} = 0.2295 \widehat{\Delta y_{t-1}} - 0.7168 \hat{\varepsilon}_{t-1}$
L1	(2,1,1)	$\widehat{\Delta y}_{t} = 0.3037 \widehat{\Delta y}_{t-1} + 0.0615 \widehat{\Delta y}_{t-2} - 0.7158 \hat{\varepsilon}_{t-1}$
T1	(0,1,2)	$\widehat{\Delta y}_t = -0.4163\hat{\varepsilon}_{t-1} - 0.0897\hat{\varepsilon}_{t-2}$
H2	(3,1,1)	$\widehat{\Delta y}_{t} = 0.3232 \widehat{\Delta y}_{t-1} - 0.0026 \widehat{\Delta y}_{t-2} + 0.0195 \widehat{\Delta y}_{t-3} - 0.7486 \hat{\varepsilon}_{t-1}$
L2	(1,1,2)	$\widehat{\Delta y}_t = 0.3036 \widehat{\Delta y}_{t-1} - 0.6928 \hat{\varepsilon}_{t-1} - 0.0423 \hat{\varepsilon}_{t-2}$
T2	(0,1,3)	$\widehat{\Delta y}_t = -0.4364\hat{\varepsilon}_{t-1} - 0.1527\hat{\varepsilon}_{t-2} - 0.0329\hat{\varepsilon}_{t-3}$
Н3	(2,1,2)	$\widehat{\Delta y}_t = 0.0009 + 0.9188 \widehat{\Delta y}_{t-1} - 0.2583 \widehat{\Delta y}_{t-2} - 1.2571 \hat{\varepsilon}_{t-1} + 0.3738 \hat{\varepsilon}_{t-2}$
L3	(1,1,2)	$\widehat{\Delta y}_t = 0.3940 \widehat{\Delta y}_{t-1} - 0.7289 \hat{\varepsilon}_{t-1} - 0.0727 \hat{\varepsilon}_{t-2}$
T3	(2,1,2)	$\widehat{\Delta y}_t = 1.1458\widehat{\Delta y}_{t-1} - 0.3685\widehat{\Delta y}_{t-2} - 1.4940\hat{\varepsilon}_{t-1} + 0.5721\hat{\varepsilon}_{t-2}$
H4	(1,1,2)	$\widehat{\Delta y}_t = 0.9150 \widehat{\Delta y}_{t-1} - 1.3709 \hat{\varepsilon}_{t-1} + 0.3877 \hat{\varepsilon}_{t-2}$
L4	(1,0,2)	$\widehat{\Delta y}_t = 55.5964 + 0.9448 \widehat{\Delta y}_{t-1} - 0.3933 \hat{\varepsilon}_{t-1} - 0.0683 \hat{\varepsilon}_{t-2}$
T4	(2,1,1)	$\widehat{\Delta y}_{t} = 0.0040 \widehat{\Delta y}_{t-1} - 0.0987 \widehat{\Delta y}_{t-2} - 0.4868 \hat{\varepsilon}_{t-1}$
H5	(1,1,2)	$\widehat{\Delta y}_t = 0.5239 \widehat{\Delta y}_{t-1} - 0.8898 \hat{\varepsilon}_{t-1} + 0.0981 \hat{\varepsilon}_{t-2}$
L5	(1,0,2)	$\widehat{\Delta y}_t = 54.4748 + 0.9494 \widehat{\Delta y}_{t-1} - 0.4222 \hat{\varepsilon}_{t-1} - 0.0952 \hat{\varepsilon}_{t-2}$
T5	(1,1,1)	$\widehat{\Delta y}_t = 0.2480 \widehat{\Delta y}_{t-1} - 0.6649 \hat{\varepsilon}_{t-1}$
Н6	(2,1,2)	$\widehat{\Delta y}_t = -0.0075 \widehat{\Delta y}_{t-1} + 0.1346 \widehat{\Delta y}_{t-2} - 0.3735 \hat{\varepsilon}_{t-1} - 0.2404 \hat{\varepsilon}_{t-2}$
L6	(1,0,2)	$\widehat{\Delta y}_t = 52.0821 + 0.9490 \widehat{\Delta y}_{t-1} - 0.4210 \hat{\varepsilon}_{t-1} - 0.0643 \hat{\varepsilon}_{t-2}$
T6	(3,1,1)	$\widehat{\Delta y}_{t} = 0.0593 \widehat{\Delta y}_{t-1} - 0.0173 \widehat{\Delta y}_{t-2} - 0.0561 \widehat{\Delta y}_{t-3} - 0.5477 \hat{\varepsilon}_{t-1}$
H7	(2,1,1)	$\widehat{\Delta y}_{t} = 0.2243 \widehat{\Delta y}_{t-1} - 0.0337 \widehat{\Delta y}_{t-2} - 0.6424 \hat{\varepsilon}_{t-1}$
L7	(2,0,4)	$\widehat{\Delta y}_t = 55.1164 + 1.9534 \widehat{\Delta y}_{t-1} - 0.9565 \widehat{\Delta y}_{t-2} - 1.4398 \hat{\varepsilon}_{t-1} + 0.4138 \hat{\varepsilon}_{t-2} - 0.0.0419 \hat{\varepsilon}_{t-3} + 0.0822 \hat{\varepsilon}_{t-4}$
T7	(2,1,2)	$\widehat{\Delta y}_t = -0.0042 \widehat{\Delta y}_{t-1} + 0.0324 \widehat{\Delta y}_{t-2} - 0.4084 \hat{\varepsilon}_{t-1} - 0.1645 \hat{\varepsilon}_{t-2}$

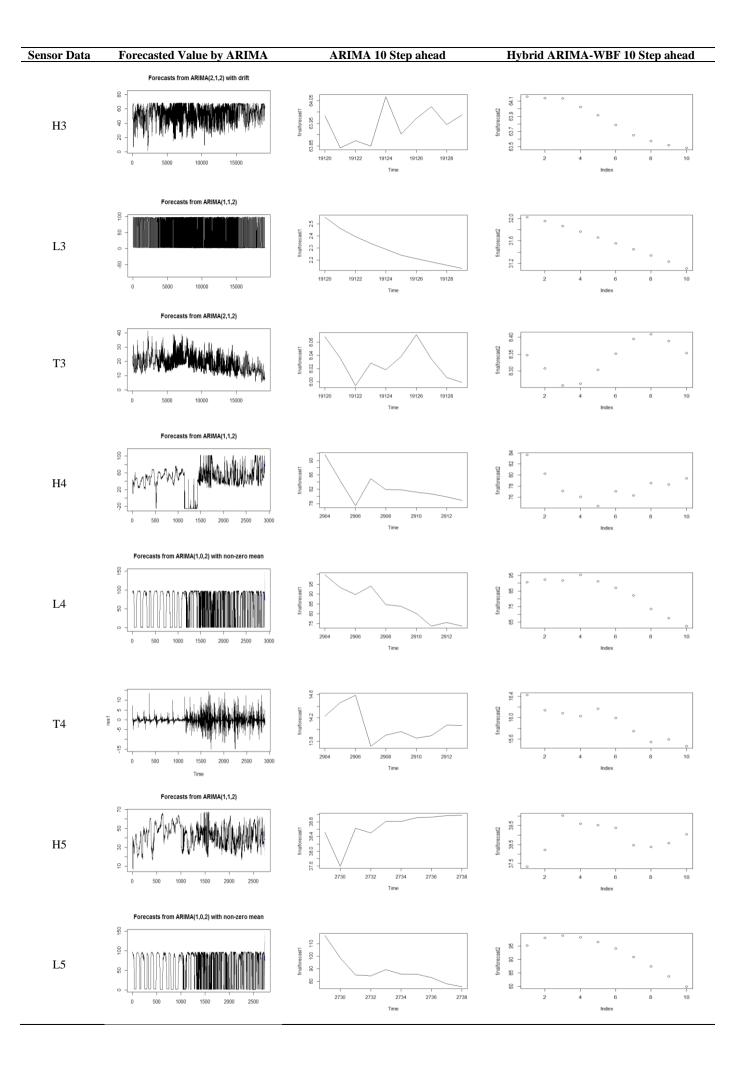
Sensor Data	ARIMA (p,d,q)	ARIMA Model
Н8	(3,1,2)	$\widehat{\Delta y}_t = -0.5797 \widehat{\Delta y}_{t-1} + 0.0948 \widehat{\Delta y}_{t-2} - 0.0442 \widehat{\Delta y}_{t-3} + 0.1462 \hat{\varepsilon}_{t-1} - 0.4148 \hat{\varepsilon}_{t-2}$
L8	(1,0,2)	$\widehat{\Delta y}_t = 54.3273 + 0.9464 \widehat{\Delta y}_{t-1} - 0.4072 \hat{\varepsilon}_{t-1} - 0.0815 \hat{\varepsilon}_{t-2}$
T8	(3,1,1)	$\widehat{\Delta y}_t = 0.0714 \widehat{\Delta y}_{t-1} - 0.0261 \widehat{\Delta y}_{t-2} - 0.0679 \widehat{\Delta y}_{t-3} - 0.5506 \hat{\varepsilon}_{t-1}$
H9	(1,1,1)	$\widehat{\Delta y}_t = 0.2360 \widehat{\Delta y}_{t-1} - 0.6570 \widehat{\varepsilon}_{t-1}$
L9	(1,1,1)	$\widehat{\Delta y}_t = 0.2705 \widehat{\Delta y}_{t-1} - 0.7163 \hat{\varepsilon}_{t-1}$
T9	(1,1,1)	$\widehat{\Delta y}_t = 0.2326 \widehat{\Delta y}_{t-1} - 0.6177 \hat{\varepsilon}_{t-1}$

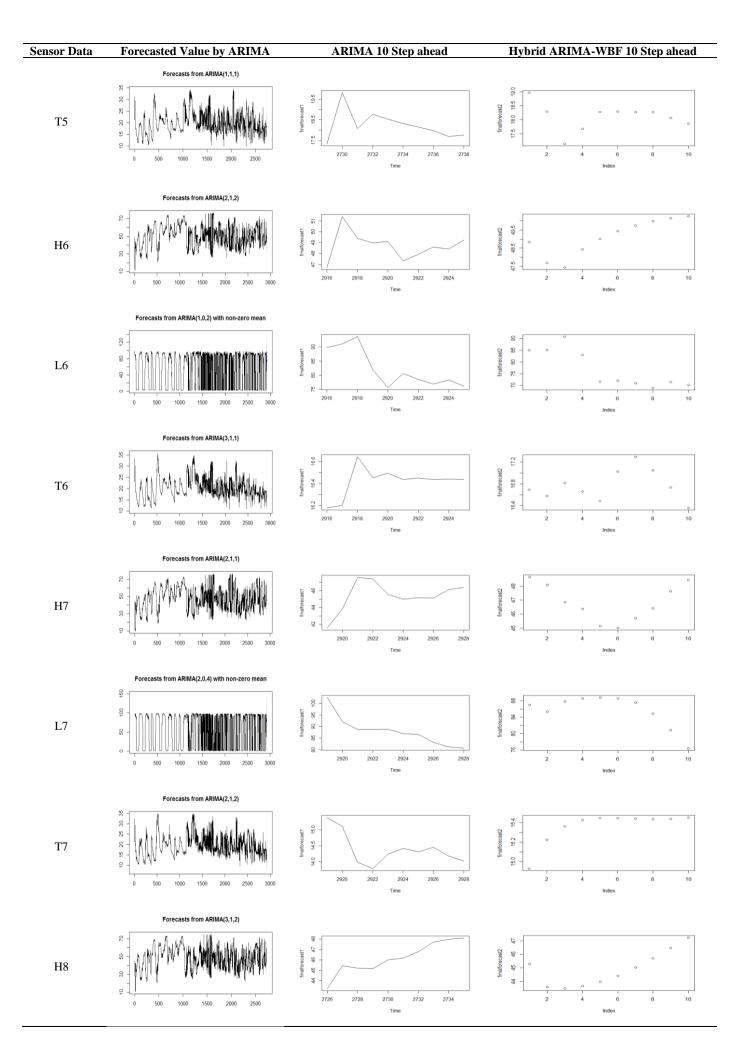
The ARIMA residual forecasts and WBF forecasts are added to find the out-of-sample forecasts using the hybrid ARIMA-WBF model for the next ten steps ahead. The best fitted parsimonious ARIMA models of twenty-seven environmental sensor datasets measuring humidity, light, and temperature are presented in Table 4.

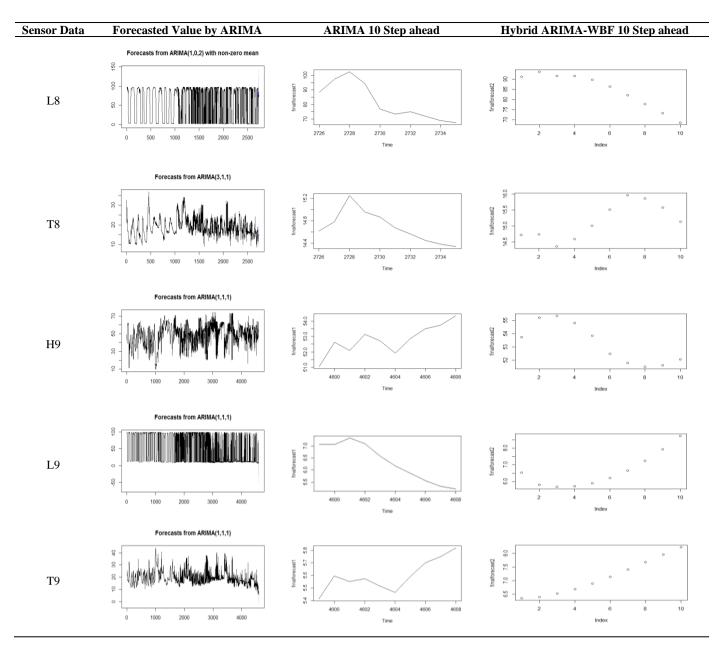
The real-time forecasted values of sensor data sets for the ARIMA model, out of sample Real-time (short-term) forecasts (hundred ten minutes ahead) of sensor data sets for both ARIMA and hybrid ARIMA-WBF models are displayed in Table 5.

Table 5. Forecasted values of sensor data sets for the ARIMA model, out of real-time sample forecasts (10 ten steps ahead) of sensor data sets for both ARIMA and hybrid ARIMA-WBF models









We applied an advanced hybrid ARIMA-WBF model for the nonlinearity, nonstationarity, and non-Gaussian environmental sensor datasets of measuring humidity, light, and temperature for comparison purposes. The results of the simulations are displayed in Table 6. Our proposed individual ARIMA model performance is better than the hybrid model in twenty-one out of twenty-seven datasets of sensor datasets. The RMSE and MAE values are lower in ARIMA compared to the other two models in 78 percent of datasets which signifies the forecasting accuracy of ARIMA is better in most of the cases

In the simulation, 100 nodes are distributed uniformly in a square of side 100 meters. The rate of the data flow of all the nodes is 40Kbps. And the sink is at the left corner of the square. We have calculated the energy consumption by forwarding the network traffic using the shortest path algorithm to reach the sink. list of parameters used in the simulation is explained in Table 7.

Table 6. The performance in terms of quantitative measures for various prediction models on twenty-seven sensor datasets for humidity, light, and temperature

				I	Perforn	nance				
		H1	L1	T1	H2	L2	T2	Н3	L3	Т3
Model	RMSE									
ARIMA		8.8	23.7	2.1	4.63	28.39	2.93	5.9	27.04	2.33
WBF		9.4	24.6	2.2	4.72	33.94	3.19	7.2	37.59	3.29
ARIMA-WBF		9.5	25.7	2.8	5.01	30.72	3.16	6.4	29.17	2.52
		H1	L1	T1	H2	L2	T2	Н3	L3	Т3
Model	MAE									
ARIMA		4.77	12.25	1.16	2.84	15.1	1.74	3.54	15.04	1.35
WBF		5.32	13.39	1.24	3.01	26.7	1.96	5.10	31.15	2.42
ARIMA-WBF		5.18	14.13	1.27	3.04	17.9	1.85	3.78	16.26	1.43

				I	Perforn	nance				
		H4	L4	T4	Н5	L5	T5	Н6	L6	Т6
Model	RMSE									
ARIMA		10.65	25.01	2.58	5.52	25.04	2.1	5.65	23.32	1.94
WBF		10.83	27.07	3.30	5.64	27.28	2.2	5.80	24.58	2.58
ARIMA-WBF		11.43	26.96	2.87	6.23	27.11	2.4	6.30	25.63	2.19
		H4	L4	T4	Н5	L5	T5	Н6	L6	T6
Model	MAE									
ARIMA		5.77	14.53	1.53	3.24	15.0	1.2	3.20	13.54	1.12
WBF		5.89	14.10	2.45	3.44	14.6	1.3	3.43	13.36	1.91
ARIMA-WBF		5.74	13.93	1.64	3.58	14.9	1.4	3.55	13.59	1.12
				I	Perforn	nance				
Model		H7	L7	T7	Н8	L8	T8	Н9	L9	Т9
	RMSE									
ARIMA		6.67	24.61	2.29	5.94	24.8	2.2	6.08	25.13	2.55
WBF		7.25	25.39	3.01	6.11	25.6	2.7	6.21	27.09	2.61
ARIMA-WBF		7.34	26.89	2.51	6.58	27.0	2.5	6.61	27.21	2.76
		H7	L7	T7	Н8	L8	T8	Н9	L9	Т9
Model	MAE									
ARIMA		3.83	14.16	1.36	3.54	14.7	1.35	3.63	13.77	1.43
WBF		4.35	13.41	2.23	3.80	13.7	2.02	3.87	15.29	1.54
ARIMA-WBF		4.36	14.72	1.51	4.01	13.7	1.48	4.00	15.62	1.59

Table 7. List of parameters

Parameters	Values/Unit
No of Sensor Nodes	100
Area of Simulation	100 * 100 square meter
Types of Communication	Multi-hop
Nodes Distribution	Uniform
Simulation Time	100 Hours
Data Rate	40Kbps
Transmission Range	20 Meter
σ	4
Gateway Position	Corner of the square

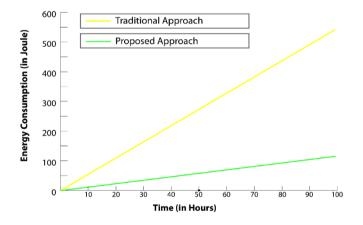


Figure 3. The energy consumption in the proposed and traditional method

In the conventional approach, sensor nodes send data every 10 minutes to cloud systems as data is collected every 10 minutes. In the proposed approach, ten steps ahead forecasting is used in the cloud system, so sensors send data every 110 minutes to the cloud. The power consumption in the proposed and traditional approach is explained in Figure 3. In the traditional method, sensor nodes send data every 10 minutes to cloud systems as data is collected every 10 minutes. In the proposed approach, ten steps ahead forecasting is used in the cloud system, so sensors send data every 110 minutes to the cloud.

It is observed that the proposed methods consume less energy as compared to the traditional method for the sensor cloud system.

This paper used the ARIMA-WBF model using residual modelling for humidity, light, and temperature forecasting for the sensor data 1 to 9. The ARIMA-WBF model explains the non-linear, linear, and nonstationary tendencies present in the humidity, light, and temperature data sets of nine different sensors. Since all the data sets are linearity and nonstationarity, the proposed ARIMA model can perform better than the other two models. It also provides better accuracy in forecasting than other advanced models like WBF and ARIMA-WBF for twenty-seven out of twenty-seven data sets under RMSE and twenty-one out of twenty-seven data sets under MAE of humidity, light, and temperature, respectively considered in this study. The present model can forecast with better accuracy if the linearity of the ARIMA model is satisfied. Ten minutes for ten steps ahead of sample forecasts are provided separately for twenty-seven environmental sensor datasets measuring humidity, light, and temperature. As the sensor node of the WSN collects data every 10 minutes, and in the traditional approach node and sends data every 10 minutes to the cloud, which will consume more energy. In our proposed approach, the sensor nodes communicate with the cloud every 110 minutes as the forecasting technique within the cloud system forecasts the ten steps ahead forecasted value. We have used ARIMA, WBF, and ARIMA-WBF as the forecasting techniques. Our results show the accuracy of the ARIMA model is better compare to others.

4. CONCLUSIONS

A Sensor-Cloud using the data forecasting technique is proposed, which is energy efficient. We have used ARIMA, WBF, and ARIMA-WBF as the forecasting techniques. Our results show the accuracy of the ARIMA model is better compare to others. The sensor nodes gather data and send it to the cloud system. The end users get the sensor information from the cloud. As the sensor node of the WSN collects data every 10 minutes, and in the traditional approach, the node must send data every 10 minutes to the cloud, which will consume more energy. In our proposed approach, the sensor nodes transmit data to the cloud every 110 minutes as the forecasting technique within the cloud system forecasts the ten

steps ahead forecasted value. Due to less transmission of data to the cloud from the sensors, the proposed approach is energy efficient. Our proposed method consumes 0.090909 times lower power as compared to existing methods in the sensor cloud due to less data transmission, and the RMSE and MAE in the prediction are also significantly less.

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