Computational Analysis of Non-Newtonian Boundary Layer Flow of Nanofluid Past a Vertical Plate with Partial Slip

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Abstract

In the present study, the heat, momentum and mass (species) transfer in external boundary layer flow of Casson nanofluid over a vertical plate surface with multiple slip effect is studied theoretically. The effects of Brownian motion and thermophoresis are incorporated in the model in the presence of both heat and nanoparticle mass transfer convective conditions. The governing partial differential equations (PDEs) are transformed into highly nonlinear, coupled, multi-degree non-similar partial differential equations consisting of the momentum, energy and concentration equations via appropriate non-similarity transformations. These transformed conservation equations are solved subject to appropriate boundary conditions with a second order accurate finite difference method of the implicit type. The influences of the emerging parameters i.e. Casson fluid parameter (β), Brownian motion parameter (Nb), thermophoresis parameter (Nt), Buoyancy ratio parameter (N ), Lewis number (Le), Prandtl number (Pr), Velocity slip factor (Sf) and Thermal slip factor (ST) on velocity, temperature and nano-particle concentration distributions is illustrated graphically and interpreted at length. Validation of solutions with a Nakamura tridiagonal method has been included. The study is relevant to enrobing processes for electric-conductive nano-materials, of potential use in aerospace and other industries.

Keywords

Nanoparticles, Species diffusion, Casson viscoplastic model, Partial slip, Keller-box numerical method.
1. Introduction

The word “nanotechnology” was probably used for the first time by the Japanese scientist Norio Taniguchi in 1974. K. Eric Drexler is credited with initial theoretical work in the field of nanotechnology. The term nanotechnology was used by Drexler in his 1986 book “Engines of creation: The coming era of nanotechnology”. Drexler’s idea of nanotechnology is referred to as molecular nanotechnology [1]. Earlier the great theoretical physicist Richard Feynman predicted nanotechnology in 1959. In the 1980s and 1990s new nano-materials were discovered and nano fluids emerged as a result of the experiments intended to increase the thermal conductivity of liquids. The birth of nano fluids is attributed to the revolutionary idea of adding solid particles into fluids to increase the thermal conductivity. This innovative idea was put forth by the Scottish physicist J.C. Maxwell as early as 1873. Nano fluids have evolved into a very exciting and rich frontier in modern nano-technology. The excitement can be attributed to the robustness of the concept of nano fluids and the plethora of different applications of this technology [2]. The properties of nano fluids need a lot of fine tuning, many seemingly contradicting studies need clarity and validation. Nano fluids have potential applications in micro-electronics, fuel cells, rocket propulsion, environmental detoxification, spray coating of aircraft wings, pharmaceutical suspensions, medical sprays etc. These applications of nano fluids are largely attributable to the enhanced thermal conductivity and Brownian motion dynamics which can be exploited to immense benefit. Nanomaterials work efficiently as new energy materials since they incorporate suspended particles with size as the same as or smaller than the size of de Broglie wave [3]. The use of nanoparticles is now a subject of abundant studies, and aspects of particular interest are Brownian motion and thermophoretic transport. Nano fluids constitute a new class of heat transfer fluids comprising a conventional base fluid and nano-particles. The nanoparticles are utilized to enhance the heat transfer performance of the base fluids [4]. The cooling rate requirements cannot be obtained by the ordinary heat transfer fluids because their thermal conductivity is not adequate. Brownian motion of the nanoparticles enhances the thermal conductivity of base fluids, although there may be many more mechanisms at work which exert a contribution. The concept of nano fluids was introduced by Choi [5] wherein he proposed the suspension of nanoparticles in a base fluid such as water, oil, and ethylene glycol. Buongiorno’s [6] attempted to explain the increase in the thermal conductivity of such fluids and developed a model that emphasized the key mechanisms in laminar flow as being particle Brownian motion and thermophoresis.

In recent years with the development of hydrophobic surfaces, slip flows have garnered some attention in nanofluid dynamics. Furthermore the non-Newtonian properties of different nanofluid suspensions have also attracted interest in simulating rheological behavior with different models. Noghrehabadi et al. [7] investigated the effects of the slip boundary condition on the heat transfer characteristics for a stretching sheet subjected to convective heat transfer in the presence of nanoparticles. They found that the flow velocity and the surface shear stress on the stretching sheet are strongly influenced by the slip parameter with a decrease in the momentum boundary layer thickness and increase in thermal boundary layer thickness. Khan and Pop [8] studied the problem of laminar fluid flow which results from a stretching of a flat surface in a nanofluid.
They analyzed the development of the steady boundary layer flow, heat transfer and nanoparticle volume fraction, observing that the reduced Nusselt number decreased while the reduced Sherwood number increased with greater volume fraction. Subba Rao and Nagendra [9] investigated thermal radiation effects on Oldroyd-B viscoelastic nanofluid flow from a stretching sheet in a non-Darcy porous medium. They analyzed the behavior of nano particles on temperature and concentration distributions in detail. Uddin et al. [10] analyzed anisotropic slip effects on nanofluid bio-convection boundary layers from a translating sheet using MAPLE symbolic quadrature and Lie group methods. Rana et al. [11] used a high-penalty finite element method to simulate two-dimensional flow dissipative viscoelastic nanofluid polymeric boundary layer stretching sheet flow, employing the Reiner-Rivlin second grade non-Newtonian model. They showed that greater polymer fluid viscoelasticity accelerates the flow and increasing Brownian motion and thermophoresis enhances temperatures and reduces heat transfer rates (local Nusselt numbers. Malik et al. [12] used the Runge–Kutta Fehlberg method to obtain numerical solutions for steady thermal boundary layer flow of a Casson nanofluid flowing over a vertical radially exponentially-stretching cylinder. Many such studies have been communicated and have usually adopted the so-called “active control” boundary condition, based on the Kuznetsov-Nield formulation [13] for natural convective boundary layer flow of a nanofluid over a vertical surface featuring Brownian motion and thermophoresis. However Kuznetsov and Nield [14] re-visited their original model, refining this formulation with passive control of nanofluid particle fraction at the boundary rather than active control to be more physically realistic. This recent boundary condition provides one of the motivations for the present research. Uddin and Bég [15] obtained extensive solutions for the influence of multiple slip and radiative heat transfer on magnetized stretching sheet flow for a range of thermal and mass convective boundary conditions. Further studies of magnetic non-Newtonian and/or slip transport of nanofluids include Ahmed and Mahdy [16] (for bio-convection nano fluids over wavy surfaces), the above studies were generally confined to internal transport. However external boundary layer convection flows also find applications in many technological systems including enrobing polymer coating processes, heat exchanger design, solar collector architecture etc. Prasad et al. [17] studied two-dimensional nanofluid boundary layer flow from a spherical geometry embedded in porous media with a finite difference scheme. Sarojamma and Vendabai [18] investigated computationally the heat and mass transfer in magnetized Casson nanofluid boundary layer flow from a vertical exponentially stretching cylinder with heat source/sink effects.

The present work, motivated by applications in enrobing dynamics of nanomaterials, examines theoretically and computationally the steady-state transport phenomena in Casson nanofluid flow over a vertical plate with partial slip. Mathematical modelling is developed to derive the equations of continuity, momentum, energy and species conservation, based on the Buongiorno nano fluid model [6]. The partial differential boundary layer equations are then transformed into a system of dimensionless non-linear coupled differential boundary layer equations, which is solved with the robust second order accurate Keller box implicit finite difference method. The present work extends significantly earlier simulations of Hussain et al. [19] (who consider an exponentially stretching surface) to the case of a vertical plate with partial slip condition.
An extensive parametric analysis of the influence of a number of parameters (Brownian motion, thermophoresis, Casson non-Newtonian, Biot number, stream wise coordinate) on thermo-diffusive characteristics is conducted. The simulations are also relevant to calendaring in pseudo-plastic materials fabrication [20].

2. Mathematical Flow Model

We examine steady buoyancy-driven convection heat transfer flow of Casson nanofluid from a vertical plate. Figure 1 shows the flow model and associated coordinate system.

![Physical model and coordinate system](image)

Fig. 1. Physical model and coordinate system

The nanofluid fluid is taken to be incompressible and a homogenous dilute solution. The x-coordinate is measured along the vertical plate from the lowest point and the y-coordinate is measured normal to the surface. The gravitational acceleration, \( g \) acts downwards. Both the plate and the fluid are maintained initially at the same temperature. Instantaneously they are raised to a temperature \( T_T > T_x \) i.e. the ambient temperature of the fluid which remains unchanged. The appropriate constitutive equations for the Casson non-Newtonian model are:

\[
\tau_{ij} = \begin{cases} 
2 \left( \mu_B + \frac{p_y}{\sqrt{2\pi}} \right) \epsilon_{ij}, \pi \geq \pi_c \\
2 \left( \mu_B + \frac{p_y}{\sqrt{2\pi}} \right) \epsilon_{ij}, \pi < \pi_c 
\end{cases}
\]  

(1)

in which \( \pi = \epsilon_{ij} \epsilon_{ij} \) and \( \epsilon_{ij} \) is the \((i,j)\)th component of deformation rate, \( \pi \) denotes the product of the component of deformation rate with itself, \( \pi_c \) shows a critical value of this product based on the non-Newtonian model, \( \mu_B \) the plastic dynamic viscosity of non-Newtonian fluid and \( p_y \) the yield stress of fluid. The Casson model, although relatively simple, is a robust viscoplastic model and describes accurately the shear stress-strain behavior of certain industrial polymers in which flow is not possible prior to the attainment
of a critical shear stress. Unlike the Bingham viscoplastic model which has a linear shear rate, the Casson model has a non-linear shear rate. Casson fluid theory was originally propounded to simulate shear thinning (viscosity is reduced with greater shear rates) liquids containing rod-like solids and is equally popular in analysing inks, emulsions, food stuffs (chocolate melts), certain gels and paints [21]. More recently it has been embraced in advanced polymeric flow processing [22]. Incorporating the Casson terms and applying the Buongiorno nano fluid model, the governing conservation equations, in primitive form, for the regime under investigation i.e. mass continuity, momentum, energy and species, can be written as follows:

\[
\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \tag{2}
\]

\[
u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = \left(1 + \frac{1}{\beta} \right) \frac{\partial^2 u}{\partial y^2} + g \beta_f (T - T_w) + g \beta_c (C - C_w) \tag{3}
\]

\[
u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} = \alpha \frac{\partial^2 T}{\partial y^2} + \tau \left( D_B \frac{\partial C}{\partial y} + D_T \left( \frac{\partial T}{\partial y} \right)^2 \right) \tag{4}
\]

\[
u \frac{\partial C}{\partial x} + v \frac{\partial C}{\partial y} = D_B \frac{\partial^2 C}{\partial y^2} + D_T \frac{\partial^2 T}{\partial y^2} \tag{5}
\]

The boundary conditions imposed at the vertical plate surface and in the free stream are:

At \( y = 0, u = N_0 \frac{\partial u}{\partial y}, v = 0, T = T_w + K_0 \frac{\partial T}{\partial y} \) as \( y \to \infty, u \to 0, v \to 0, T \to T_w, C \to C_w \). \( \tag{6} \)

Here \( N_0 \) is the velocity slip factor \( K_0 \) is the thermal slip factor and \( T_w \) is the free stream temperature. For \( N_0 = 0 = K_0 \), one can recover the no-slip case. The \( u \) and \( v \) are the velocity components in the \( x \)- and \( y \)-directions respectively, \( v \) - the kinematic viscosity of the electrically-conducting nanofluid, \( \beta \) - is the non-Newtonian Casson parameter respectively, \( \rho_f \) is the density of fluid, \( \sigma \) is the electrical conductivity of the nanofluid, \( \alpha \) - the thermal diffusivity of the nanofluid, \( T \) - the temperature, respectively. Furthermore \( \tau = \left( \rho c\right)_p / \left( \rho c\right)_f \) is the ratio of nanoparticle heat capacity and the base fluid heat capacity, \( C_p \) is the specific heat capacity; \( D_B \) is the Brownian diffusion coefficient; \( D_T \) is the thermophoretic diffusion coefficient; \( k \) is the thermal conductivity of nanofluid; \( T_w \) and \( C_w \) are the ambient fluid temperature and concentration, respectively.

The stream function \( \psi \) is defined by the Cauchy-Riemann equations, \( u = \partial \psi / \partial y \) and \( v = -\partial \psi / \partial x \), and therefore, the continuity equation is automatically satisfied. In order to write the governing equations and the boundary conditions in dimensionless form, the following non-dimensional quantities are introduced.

\[
\xi = \frac{V_0 x}{\nu}, \eta = \frac{y}{x} \left( Gr_s \right)^{1/4}, \psi = 4\nu \left( Gr_s \right)^{1/4} f(\xi, \eta) + \frac{1}{4} \xi \tag{7}
\]

\[
\theta(\xi, \eta) = \frac{T - T_w}{T_w - T_\infty}, \phi(\xi, \eta) = \frac{C - C_\infty}{C_w - C_\infty}, Gr_s = \frac{g \beta_f (T_w - T_\infty)}{4\nu^2} \tag{8}
\]

The transformed boundary layer equations for momentum, energy and concentration emerge as:
\[
\left(1 + \frac{1}{\beta}\right) f'' + (3f + \xi) f'' - 2f'^2 + \theta + N\phi
\]
\[
= \xi \left( f' \frac{\partial f'}{\partial \xi} - f \frac{\partial f}{\partial \xi} \right)
\]  
\tag{8}

\[
\frac{\theta'}{Pr} + (3f + \xi) \theta' + N_b \phi' \theta' + N_t \theta' = \xi \left( f' \frac{\partial \theta'}{\partial \xi} - \theta' \frac{\partial f}{\partial \xi} \right)
\]  
\tag{9}

\[
\phi' \frac{Le}{Le} + (3f + \xi) \phi' + N_b \theta' \phi' \frac{Le}{N_t} \theta' = \xi \left( f' \frac{\partial \phi'}{\partial \xi} - \phi' \frac{\partial f}{\partial \xi} \right)
\]  
\tag{10}

The corresponding transformed dimensionless boundary conditions are:

At \( \eta = 0, f = 0, f' = \left(1 + \frac{1}{\beta}\right) S_f f''(0), \theta = 1 + S_T \theta'(0) \) As \( \eta \to \infty, f' \to 0, \theta \to 0, \phi \to 0 \)  
\tag{11}

where \( Pr = \gamma/\alpha \) is Prandtl number; \( Gr \) is a Grashof buoyancy number; \( S_f = N_b Gr^{1/4} / \gamma \) and \( S_T = K_0 Gr^{1/4} / \gamma \) the non-dimensional velocity slip and thermal jump parameters. \( Le = \gamma / D_H \) is the Lewis number; \( N_t = (\rho c)_p D_T (T_w - T_{ov}) / (\rho c)_f \gamma T_{ov} \) is the thermophoresis parameter; \( N_b = (\rho c)_p D_n (C_w - C_{ov}) / (\rho c)_f \gamma \) is the Brownian parameter; \( N = \beta_e (C_w - C_{ov}) / \beta_f (T_w - T_{ov}) \) is the concentration to thermal buoyancy ratio parameter.

All other parameters are defined in the nomenclature. The skin-friction coefficient (plate surface shear stress function), the local Nusselt number (heat transfer rate) and Sherwood number (mass transfer rate) can be defined using the transformations described above with the following expressions:

\[
\frac{1}{4} Gr_{\gamma/4} C_f = \left(1 + \frac{1}{\beta}\right) f''(\xi, 0)
\]  
\tag{12}

\[
Gr_{\gamma/4} Nu = -\theta'(\xi, 0)
\]  
\tag{13}

\[
Gr_{\gamma/4} Sh = -\phi'(\xi, 0)
\]  
\tag{14}

### 3. Numerical Solution with Keller Box Implicit Method

The strongly coupled, nonlinear conservation equations do not admit analytical (closed-form) solutions. An elegant, implicit difference finite difference numerical method developed by Keller [23] is therefore adopted to solve the general flow model defined by equations (8)-(10) with boundary conditions (11). This method is especially appropriate for boundary layer flow equations which are parabolic in nature. It remains one of the most widely applied computational methods in viscous fluid dynamics. Recent problems which have used Keller’s method include natural convection flow of a chemically-reacting Newtonian fluid along vertical and inclined plates [24], stretching sheet MHD flow of Casson fluid model [25], magnetohydrodynamic Falkner-Skan “wedge” flows [26], magneto-rheological flow from an extending cylinder [27], Hall magneto-gas dynamic generator slip flows [28] and radiative-convective Casson slip
boundary layer flows [29]. Keller’s method provides unconditional stability and rapid convergence for strongly non-linear flows. It involves four key stages, summarized below.

1) Reduction of the $N^{th}$ order partial differential equation system to $N$ first order equations

2) Finite difference discretization of reduced equations

3) Quasilinearization of non-linear Keller algebraic equations

4) Block-tridiagonal elimination of linearized Keller algebraic equations

Stage 1: Reduction of the Nth order partial differential equation system to N first order equations

Equations (8) – (10) subject to the boundary conditions (11) are first written as a system of first-order equations. For this purpose, we reset Equations (8) – (10) as a set of simultaneous equations by introducing the new variables.

\[ f' = u \]  
\[ u' = v \]  
\[ \theta = s \]  
\[ s' = t \]  
\[ g' = p \]  

\[ \left(1 + \frac{1}{\beta}\right)v' + (3f + \xi)v - 2u^2 + (s + Ng) = \xi \left( u \frac{\partial u}{\partial \xi} - v \frac{\partial f}{\partial \xi} \right) \]  
\[ \frac{t'}{Pr} + (3f + \xi)t + N_k \phi' t + N_i t^2 = \xi \left( u \frac{\partial s}{\partial \xi} - t \frac{\partial f}{\partial \xi} \right) \]  
\[ \frac{p'}{Le} + (3f + \xi)p + \frac{1}{Le \ N_i} t' = \xi \left( u \frac{\partial g}{\partial \xi} - p \frac{\partial f}{\partial \xi} \right) \]

where primes denote differentiation with respect to $\eta$.

In terms of the dependent variables, the boundary conditions become:

At $\eta = 0: u = 0, f = 0, s = 1, g = 1$
As $\eta \to \infty : u \to 0, v \to 0, s \to 0, g \to 0$  

Stage 2: Finite difference discretization of reduced boundary layer equations

A two-dimensional computational grid (mesh) is imposed on the $\xi-\eta$ plane as sketched in Fig.2. The stepping process is defined by:

\[ \eta_0 = 0, \eta_j = \eta_{j-1} + h_j, j = 1, 2, ..., J, \eta_J = \eta_e \]  
\[ \xi^0 = 0, \xi^n = \xi^{n-1} + k_n, n = 1, 2, ..., N \]

where $k_n$ and $h_j$ denote the step distances in the $\xi$ (streamwise) and $\eta$ (spanwise) directions respectively.
If \( g^n \) denotes the value of any variable at \((\eta, \xi^n)\), then the variables and derivatives of Eqns. (15) – (22) at \((\eta_{j-1/2}, \xi^n)\) are replaced by:

\[
g_{j-1/2}^{n} = \frac{1}{4} \left( g_j^n + g_{j-1}^{n-1} + g_j^{n-1} + g_{j-1}^n \right) \tag{26}
\]

\[
\left( \frac{\partial g}{\partial \eta} \right)_{j-1/2}^{n-1/2} = \frac{1}{2h_j} \left( g_j^n - g_{j-1}^{n-1} + g_j^{n-1} - g_{j-1}^n \right) \tag{27}
\]

\[
\left( \frac{\partial g}{\partial \xi} \right)_{j-1/2}^{n-1/2} = \frac{1}{2k^n} \left( g_j^n - g_{j-1}^{n-1} + g_j^{n-1} - g_{j-1}^n \right) \tag{28}
\]

The finite-difference approximation of equations (15) – (22) for the mid-point \((\eta_{j-1/2}, \xi^n)\), below:

\[
h_j^{-1} \left( f_j^n - f_{j-1}^n \right) = u_j^n \tag{29}
\]

\[
h_j^{-1} \left( u_j^n - u_{j-1}^n \right) = v_j^n \tag{30}
\]

\[
h_j^{-1} \left( g_j^n - g_{j-1}^n \right) = p_j^n \tag{31}
\]

\[
h_j^{-1} \left( \theta_j^n - \theta_{j-1}^n \right) = t_j^n \tag{32}
\]

\[
\left( 1 + \frac{1}{\beta} \right) \left( v_j + v_{j-1} \right) + \frac{(3 + \alpha)}{4h_j} \left[ \left( f_j + f_{j-1} \right) \left( v_j + v_{j-1} \right) \right] \\
+ \frac{h_j}{2} \left( s_j + s_{j-1} + N(g_j + g_{j-1}) \right) \\
- \frac{\alpha h_j}{2} f_{j-1/2}^{n-1} \left( s_j + s_{j-1} + N(g_j + g_{j-1}) \right) \\
+ \frac{\alpha h_j}{2} v_{j-1/2}^{n-1} \left( f_j + f_{j-1} \right) = \left[ R_{j-1/2}^{n-1} \right] \tag{33}
\]
\[
\frac{1}{Pr} \left( t_j - t_{j-1} \right) + \frac{(3+\alpha)h_j}{4} \left[ (f_j + f_{j-1}) \left( t_j + t_{j-1} \right) \right] \\
+ \frac{h_j}{4} \left( t_j + t_{j-1} \right)^2 - \frac{\alpha h_j}{4} \left[ (u_j + u_{j-1}) \left( s_j + s_{j-1} \right) \right] \\
+ Nb \frac{h_j}{4} \left[ (t_j + t_{j-1}) \left( p_j + p_{j-1} \right) \right] + \frac{ah_j}{2} s_j^{-1} (u_j + u_{j-1}) \\
- \frac{ah_j}{2} u_{j-1} \left( s_j + s_{j-1} \right) - \frac{ah_j}{2} f_{j-1}^{-1} \left( t_j + t_{j-1} \right) \\
+ \frac{ah_j}{2} f_{j-1}^{-1} \left( f_j + f_{j-1} \right) + \frac{h_j}{2} \xi \left( t_j + t_{j-1} \right) = [R_1]^{-1}_{j-1/2} 
\]

\[
\frac{1}{Le} \left( p_j - p_{j-1} \right) + \frac{(3+\alpha)h_j}{4} \left[ (f_j + f_{j-1}) \left( p_j + p_{j-1} \right) \right] \\
- \frac{ah_j}{4} \left[ (u_j + u_{j-1}) \left( g_j + g_{j-1} \right) \right] + \frac{ah_j}{2} s_j^{-1} (u_j + u_{j-1}) \\
+ \frac{B}{Le} \left( t_j - t_{j-1} \right) - \frac{ah_j}{2} u_{j-1} \left( g_j + g_{j-1} \right) + \xi \left( p_j + p_{j-1} \right) \\
- \frac{ah_j}{2} f_{j-1}^{-1} \left( p_j + p_{j-1} \right) + \frac{ah_j}{2} p_{j-1}^{-1} \left( f_j + f_{j-1} \right) = [R_3]^{-1}_{j-1/2} 
\]

Where the following notation applies:

\[
\alpha = \frac{\gamma^{n-1/2}}{k_n} , B = \frac{Nt}{Nb} 
\]

\[
[R_1]^{-1}_{j-1/2} = -h_j \left[ 1 + \frac{1}{\beta} \left( \frac{v_j - v_{j-1}}{h_j} \right) \right] + (2 - \alpha)(u_j^{-1/2})^2 \\
+ \left( s_j^{-1/2} + Ng_{j-1/2} \right) 
\]

\[
[R_3]^{-1}_{j-1/2} = -h_j \left[ \frac{t_j - t_{j-1}}{Pr} \left( t_j^{-1/2} \right) + \alpha \left( u_j^{-1/2} s_j^{-1/2} \right) - Nb \left( p_j^{-1/2} h_j^{-1/2} \right) \right] \\
+ \left( 3f_j^{-1/2} + \xi - \alpha \right) (t_j^{-1/2})^2 
\]

\[
[R_3]^{-1}_{j-1/2} = -h_j \left[ \frac{1}{Le} \left( \frac{p_j - p_{j-1}}{h_j} \right) + (3f_j^{-1/2} + \xi - \alpha) (p_j^{-1/2}) \right] \\
+ \frac{B}{Le} \left( \frac{t_j - t_{j-1}}{h_j} \right) + \alpha \left( u_j^{-1/2} g_j^{-1/2} \right) 
\]

The boundary conditions are

\[
f_0^n = u_0^n = 0, \theta_0^n = 1, u_0^* = 0, v_0^n = 0, \theta_0^* = 0, \varphi_0^n = 1, \varphi_0^* = 0 
\]

Stage 3: Quasilinearization of non-linear Keller algebraic equations
If we assume $f_{j-1}, u_{j-1}, v_{j-1}, p_{j-1}, s_{j-1}, t_{j-1}$, to be known for $0 \leq j \leq J$. Equations (29) – (35) comprise a system of $6J+6$ equations for the solution of $6J+6$ unknowns $f_{j}, u_{j}, v_{j}, p_{j}, s_{j}, t_{j}, j = 0, 1, 2 \ldots, J$. This non-linear system of algebraic equations is linearized by means of Newton’s method as elaborated by Keller [23] and explained in [36,37].

Stage 4: Block-tridiagonal elimination of linear Keller algebraic equations

The linearized version of eqns. (29) – (35) can now be solved by the block-elimination method, since they possess a block-tridiagonal structure since it consists of block matrices. The complete linearized system is formulated as a block matrix system, where each element in the coefficient matrix is a matrix itself. Then, this system is solved using the efficient Keller-box method. The numerical results are affected by the number of mesh points in both directions. After some trials in the $\eta$-direction (radial coordinate) a larger number of mesh points are selected whereas in the $\zeta$ direction (tangential coordinate) significantly less mesh points are utilized. $\eta_{\text{max}}$ has been set at 16 and this defines an adequately large value at which the prescribed boundary conditions are satisfied. $\zeta_{\text{max}}$ is set at 1.0 for this flow domain. Mesh independence testing is also performed to ensure that the converged solutions are correct. The computer program of the algorithm is executed in MATLAB running on a PC.

If we assume $f_{j}, u_{j}, v_{j}, p_{j}, s_{j}, t_{j}$, to be known for $0 \leq j \leq J$, Eqs. (29) - (35) are a system of $6J+6$ equations for the solution of $6J+6$ unknowns $f_{j}, u_{j}, v_{j}, p_{j}, s_{j}, t_{j}, j = 0, 1, 2 \ldots, J$. This non-linear system of algebraic equations is linearized by means of Newton’s method which then solved in a very efficient manner by using the Keller-box method, which has been used most efficiently by Cebeci and Bradshaw[38], taking the initial interaction with a given set of converged solutions at $\xi = \xi_{0}$. To initiate the process with $\xi = 0$, we first prescribe a set of guess profiles for the functions $f, u, v, \theta$ and $t$ which are unconditionally convergent. These profiles are then employed in the Keller-box scheme with second-order accuracy to compute the correct solution step by step along the boundary layer. For a given $\xi$ the iterative procedure is stopped to give the final velocity and temperature distribution when the difference in computing these functions in the next procedure become less than $10^{-5}$, i.e., $|\delta f| \leq 10^{-5}$, where the superscript $i$ denotes the number of iterations. For laminar flows the rate of convergence of the solutions of the equations (29)-(35) is quadratic provided the initial estimate to the desired solution is reasonably close to the final solution. Calculations are performed with four different $\Delta \eta$ spacings show that the rate of convergence of the solutions is quadratic in all cases for these initial profiles with typical iterations. The fact that Newton’s method is used to to linearize the non-linear algebraic equations and that with proper initial guess $\xi_{0}$ usually obtained from a solution at $\xi_{n-1}$, the rate of convergence of the solutions should be quadratic can be used to test the code for possible programming errors and to aid in the choice of $\Delta \xi$ spacings in the downstream direction. To study the effect of $\Delta \xi$ spacing on the rate of convergence of solutions, calculations were performed in the range $0 \leq \xi \leq 0.4$ with uniform $\Delta \xi$ spacings corresponding to 0.08, 0.04, 0.02 and 0.01. Except for the results obtained with $\Delta \xi = 0.08$, the
rate of convergence of the solutions was essentially quadratic at each \( \xi \) station. In most laminar boundary layer flows, a step size of \( \Delta y = 0.02 \) to 0.04 is sufficient to provide accurate and comparable results. In fact in the present problem, we can even go up to \( \Delta y = 0.1 \) and still get accurate and comparable results. This particular value of \( \Delta y = 0.1 \) has also been used successfully by Merkin [39]. A uniform grid across the boundary is quite satisfactory for most laminar flow calculations, especially in laminar boundary layer. However, the Keller-box method is unique in which various spacing in both \( \eta \) and \( \xi \) directions can be used (Aldoss et al., [40]).

4. Validation with Nakamura Difference Scheme

The present Keller box method (KBM) algorithm has been tested rigorously and benchmarked in numerous studies by the authors. However to further increase confidence in the present solutions, we have validated the general model with an alternative finite difference procedure due to Nakamura [30]. The Nakamura tridiagonal method (NTM) generally achieves fast convergence for nonlinear viscous flows which may be described by either parabolic (boundary layer) or elliptic (Navier-Stokes) equations. The coupled 7th order system of nonlinear, multi-degree, ordinary differential equations defined by (8)–(10) with boundary conditions (11) is solved using the NANONAK code in double precision arithmetic in Fortran 90, as elaborated by Bég [31]. Computations are performed on an SGI Octane Desk workstation with dual processors and take seconds for compilation. As with other difference schemes, a reduction in the higher order differential equations, is also fundamental to Nakamura’s method. The method has been employed successfully to simulate many sophisticated nonlinear transport phenomena problems e.g. magnetized biopolymer enrobing coating flows (Bég et al. [32]). Intrinsic to this method is the discretization of the flow regime using an equi-spaced finite difference mesh in the transformed coordinate (\( \eta \)) and the central difference scheme is applied on the \( \eta \)-variable. A backward difference scheme is applied on the \( \xi \)-variable. Two iteration loops are used and once the solution for \( \eta \) has converged, the code progresses to the next \( \xi \) station. The partial derivatives for \( f, \theta, \phi \) with respect to \( \eta \) are as explained evaluated by central difference approximations. An iteration loop based on the method of successive substitution is utilized to advance the solution i.e. march along. The finite difference discretized equations are solved in a step-by-step fashion on the \( \eta \)-domain in the inner loop and thereafter on the \( \xi \)-domain in the outer loop. For the energy and nanoparticle species conservation Eqns. (9)-(10) which are second order multi-degree ordinary differential equations, only a direct substitution is needed. However a reduction is required for the third order momentum (velocity) boundary layer eqn. (8). We apply the following substitutions:

\[
P = f' \tag{41}
\]

\[
Q = \theta \tag{42}
\]

\[
R = \phi \tag{43}
\]
The eqns. (8)-(10) then retract to:

**Nakamura momentum equation:**

\[ A_i P^{ii} + B_i P' + C_i P = T_i \]  

(44)

**Nakamura energy equation:**

\[ A_i Q^{ii} + B_i Q' + C_i Q = T_i \]  

(45)

**Nakamura nano-particle species equation:**

\[ A_i R^{ii} + B_i R' + C_i R = T_i \]  

(46)

Here \( A_i, B_i, C_i = 1, 2, 3 \) are the Nakamura matrix coefficients, \( T_i = 1, 2, 3 \) are the Nakamura source terms containing a mixture of variables and derivatives associated with the respective lead variable \((P, Q, R)\). The Nakamura Eqns. (27)–(30) are transformed to finite difference equations and these are orchestrated to form a tridiagonal system which due to the high nonlinearity of the numerous coupled, multi-degree terms in the momentum, energy, nano-particle species and motile micro-organism density conservation equations, is solved iteratively. Householder’s technique is ideal for this iteration. The boundary conditions (11) are also easily transformed. Further details of the **NTM** approach are provided in Nakamura [30]. Comparisons are documented in Table 1 for skin friction and very good correlation is attained. Table 1 further indicates that increase in Casson viscoplastic parameter \((\beta)\) induces a strong retardation in the flow i.e. suppresses skin friction magnitudes. In both cases however positive magnitudes indicate flow reversal is not generated.

<table>
<thead>
<tr>
<th>( \beta )</th>
<th>(1+1/( \beta )) ( f^*(0) ) (KBM)</th>
<th>(1+1/( \beta )) ( f^*(0) ) (NTM)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.7</td>
<td>0.8412</td>
<td>0.8411</td>
</tr>
<tr>
<td>1.2</td>
<td>0.7605</td>
<td>0.7607</td>
</tr>
<tr>
<td>1.6</td>
<td>0.7277</td>
<td>0.7261</td>
</tr>
<tr>
<td>2.0</td>
<td>0.7065</td>
<td>0.7061</td>
</tr>
<tr>
<td>1.0</td>
<td>0.9070</td>
<td>0.9073</td>
</tr>
</tbody>
</table>

Nakamura matrix coefficients, \( Ti=1,2,3 \), are the Nakamura source terms containing a mixture of variables and derivatives associated with the respective lead variable \((P, Q, R)\). The Nakamura Eqns. (27)–(30) are transformed to finite difference equations and these are orchestrated to form a tridiagonal system which due to the high nonlinearity of the numerous coupled, multi-degree terms in the momentum, energy, nano-particle species and motile micro-organism density conservation equations, is solved iteratively. Householder’s technique is ideal for this iteration. The boundary conditions (11) are also easily transformed. Further details of the **NTM** approach are provided in Nakamura [30]. Comparisons are documented in Table 1 for skin friction and very good correlation is attained. Table 1 further indicates that increase in Casson viscoplastic parameter \((\beta)\) induces a strong retardation in the flow i.e. suppresses skin friction magnitudes. In both cases however positive magnitudes indicate flow reversal is not generated.

**Table 1.** Numerical values of skin-friction coefficient \((1+1/\beta) f^*(0)\) of \( \beta \).

5. Keller Box Method (KBM) Numerical Results and Discussion

Comprehensive solutions have been obtained with KBM and are presented in Figures 3 to 11. The numerical problem comprises three dependent thermo-fluid dynamic variables \((f, \theta, \phi)\) and eight multi-physical control parameters, \( Pr, Le, \beta, N, Nb, Nt, Sf, Sr \). The influence of stream wise space variable \( \xi \) is also
investigated. In the present computations, the following default parameters are prescribed (unless otherwise stated): \( Pr=0.71, \ Le=0.6, \ \beta=1.0, \ N=0.1, \ Nb=0.4=Nt, \ Sr=0.5, \ St=1.0, \ \xi=1.0. \)

Figures 3(a)–3(c) illustrate the effect of the Casson viscoplastic parameter, \( \beta \) on velocity \( (f') \), temperature \( (\theta) \) and concentration \( (\phi) \) profiles. With increasing \( \beta \) values, initially close to the plate surface, fig. 3a shows that the flow is strongly decelerated. However, further from the surface, the converse response is induced in the flow. This may be related to the necessity for a yield stress to be attained prior to viscous flow initiation in viscoplastic shear-thinning nanofluids. Within a short distance of the plate surface, however a strong acceleration is generated with greater Casson parameter. This serves to decrease momentum boundary layer thickness effectively.

Fig. 3(a). Effect of \( \beta \) on velocity profiles

Fig. 3(b). Effect of \( \beta \) on temperature profiles

Fig. 3(c). Effect of \( \beta \) on concentration profiles

A similar observation has been reported by for example, Mustafa and Khan [33] and Makanda et al. [34]. The viscoplastic parameter modifies the shear term \( f'''' \) in the momentum boundary layer equation (8) with an inverse factor, \( 1/\beta \), and effectively assists momentum diffusion for \( \beta >1 \). This leads to a thinning in the hydrodynamic boundary layer and associated deceleration. The case \( \beta = 0 \) which corresponds to a Newtonian fluid is not considered. An increase in viscoplastic parameter however decreases both temperature and nanoparticle concentration magnitudes throughout the boundary layer, although the reduction is relatively weak. Thermal and nanoparticle concentration boundary layer thickness are both suppressed with greater viscoplasticity of the nanofluid.
Figures 4(a)-4(c) depict the effect of Prandtl number (Pr) on the velocity (f'), temperature (θ) and nanoparticle concentration (ϕ) distributions with transverse coordinate (η). Fig. 4a shows that with increasing Prandtl number there is a strong deceleration in the flow. The Prandtl number expresses the ratio of momentum diffusion rate to thermal diffusion rate. When Pr is unity both momentum and heat diffuse at the same rate and the velocity and thermal boundary layer thicknesses are the same. With Pr>1 there is a progressive decrease in thermal diffusivity relative to momentum diffusivity and this serves to retard the boundary layer flow.

![Fig. 4(a). Effect of Pr on velocity profiles](image)

![Fig. 4(b). Effect of Pr on temperature profiles](image)

![Fig. 4(c). Effect of Pr on concentration profiles](image)

Momentum boundary layer thickness therefore grows with Prandtl number on the surface of the vertical plate. It is also noteworthy that the peak velocity which is achieved close to the plate surface is systematically displaced closer to the surface with greater Prandtl number. The asymptotically smooth profiles of velocity which decays to zero in the free stream, also confirm the imposition of an adequately large infinity boundary condition. Fig. 4b indicates that increasing Prandtl number also suppresses temperatures in the boundary layer and therefore reduces thermal boundary layer thickness. Prandtl number is inversely proportional to thermal conductivity of the viscoplastic nanofluid. Higher thermal conductivity implies lower Prandtl number and vice versa. With greater Prandtl number, thermal conductivity is reduces and this inhibits thermal conduction heat transfer which cools the boundary layer. The monotonic decays in fig. 4b are also characteristic of the temperature distribution in curved surface boundary layer flows. Inspection of fig. 4c reveals that increasing
Prandtl number strongly elevates the nano-particle concentration magnitudes. In fact a concentration overshoot is induced near the plate surface. Therefore while thermal transport is reduced with greater Prandtl number, species diffusion is encouraged and nano-particle concentration boundary layer thickness grows.

Figures 5(a)–5(c) illustrate the evolution of velocity, temperature and concentration functions with a variation in the Lewis number, is depicted. Lewis number is the ratio of thermal diffusivity to mass (nano-particle) species diffusivity. \( Le=1 \) which physically implies that thermal diffusivity of the nanofluid and species diffusivity of the nano-particles are the same and both boundary layer thicknesses are equivalent. For \( Le<1 \), mass diffusivity exceeds thermal diffusivity and vice versa for \( Le>1 \). Both cases are examined in figs 5a-5c. In fig 5a, a consistently weak decrease in velocity accompanies an increase in Lewis number. Momentum boundary layer thickness is therefore increased with greater Lewis number. This is sustained throughout the boundary layer. Fig. 5b shows that increasing Lewis number also depresses the temperature magnitudes and therefore reduces thermal boundary layer thickness. Therefore judicious selection of nano-particles during doping of polymers has a pronounced influence on velocity (momentum) and thermal characteristics in enrobing flow, since mass diffusivity is dependent on the nature of nano-particle species in the base fluid. Fig 5c demonstrates that a more dramatic depression in nano-particle concentration results from an increase in Lewis number over the same range as figs. 5a,b. The concentration profile evolves from approximately linear decay to strongly parabolic decay with increment in Lewis number.
Figures 6(a)–6(c) illustrate the variation of velocity, temperature and nano-particle concentration with transverse coordinate \( \xi \), for different values of velocity slip factor \( (S_f) \). Velocity slip factor is imposed in the augmented wall boundary condition in eqn. (11). With increasing velocity slip factor, more heat is transmitted to the fluid and this energizes the boundary layer. This also leads to a general acceleration as observed in fig. 6a and also to a more pronounced restoration in temperatures in fig. 6b, in particular near the wall. Furthermore, the acceleration near the wall with increasing velocity slip effect has been computed by Subba Rao et al. [29] using Keller box method. The effect of velocity slip is progressively reduced with further distance from the wall (curved surface) into the boundary layer and vanishes some distance before the free stream. It is also apparent from fig. 6c that nanoparticle concentration is enhanced with greater Velocity slip effect. Momentum boundary layer thickness is therefore reduced whereas thermal and species boundary layer thickness are enlarged. Obviously the non-trivial responses computed in figs. 6a-c further emphasize the need to incorporate Velocity slip effects in realistic nano fluid enrobing flows.

Figures 7(a)–7(c) illustrate the variation of velocity, temperature and nano-particle concentration with transverse coordinate \( \eta \), for different values of thermal slip parameter \( (S_t) \). Thermal slip is imposed in the augmented wall boundary condition in eqn. (11). With increasing thermal slip less heat is transmitted to the fluid and this de-energizes the boundary layer. This also leads to a general deceleration as observed in fig. 7a and also to a more pronounced depletion in temperatures in fig. 7b, in particular near the wall. The effect of thermal slip is progressively reduced with
further distance from the wall (curved surface) into the boundary layer and vanishes some distance before the free stream. It is also apparent from fig. 7c that nanoparticle concentration is reduced with greater thermal slip effect.

Momentum boundary layer thickness is therefore increased whereas thermal and species boundary layer thickness are depressed. Evidently the non-trivial responses computed in figs. 7a-c further emphasize the need to incorporate thermal slip effects in realistic nano fluid enrobing flows.

Figures 8(a)–8(c) exhibit the profiles for velocity, temperature and concentration, respectively with increasing buoyancy ratio parameter, N. In general, increases in the value of N have the prevalent to cause more induced flow along the plate surface.
This behavior in the flow velocity increases in the fluid temperature and volume fraction species as well as slight decreased in the thermal and species boundary layers thickness as $N$ increases.

Figures 9(a)–9(c) illustrates the effect of the thermophoresis parameter ($N_t$) on the velocity ($f'$), temperature ($\theta$) and concentration ($\phi$) distributions, respectively. Thermophoretic migration of nano-particles results in exacerbated transfer of heat from the nano fluid regime to the plate surface.

This de-energizes the boundary layer and inhibits simultaneously the diffusion of momentum, manifesting in a reduction in velocity i.e. retardation in the boundary layer flow and increasing momentum (hydrodynamic) boundary layer thickness, as computed in fig. 9a. Temperature is similarly decreased with
greater thermophoresis parameter (fig. 9b). Conversely there is a substantial enhancement in nano-particle concentration (and species boundary layer thickness) with greater $Nt$ values. Similar observations have been made by Kunetsov and Nield [14] and Ferdows et al. [35] for respectively, both non-conducting Newtonian and electrically-conducting Newtonian flows.

Figures 10(a)–10(c) depict the response in velocity ($f$), temperature ($\theta$) and concentration ($\phi$) functions to a variation in the Brownian motion parameter ($N_{b}$). Increasing Brownian motion parameter physically correlates with smaller nanoparticle diameters, as elaborated in Rana et al. [11]. Smaller values of $N_{b}$ corresponding to larger nanoparticles, and imply that surface area is reduced which in turn decreases thermal conduction heat transfer to the plate surface. This coupled with enhanced macro-convection within the nanofluid energizes the boundary layer and accelerates the flow as observed in fig. 10a. Similarly the energization of the boundary layer elevates thermal energy which increases temperature in the viscoplastic nanofluid. Fig 10c however indicates that the contrary response is computed in the nano-particle concentration field. With greater Brownian motion number species diffusion is suppressed. Effectively therefore momentum and nanoparticle concentration boundary layer thickness is decreased whereas thermal boundary layer thickness is increased with higher Brownian motion parameter values.
Figures 11(a) – 11(c) present the distributions for velocity, temperature and concentration fields with stream wise coordinate $\xi$, for the viscoplastic nanofluid flow. Increasing $\xi$ values correspond to progression around the periphery of the vertical plate, from the leading edge ($\xi=0$). As $\xi$ increases, there is a weak deceleration in the flow (fig. 11a), which is strongest nearer the plate surface and decays with distance into the free stream. Conversely there is a weak elevation in temperatures (fig. 11b) and nano-particle concentration magnitudes (fig. 11c) with increasing stream wise coordinate.

6. Conclusions

A theoretical study has been conducted to simulate the viscoplastic nanofluid boundary layer flow in enrobing processes from a vertical plate with Partial slip effect using the Buongiorno formulation. The transformed momentum, heat and species boundary layer equations have been solved computationally with Keller’s finite difference method. Computations have been verified with Nakamura’s tridiagonal method. The present study has shown that:

(i) Increasing viscoplastic (Casson) parameter decelerates the flow and also decreases thermal and nano-particle concentration boundary layer thickness.

(ii) Increasing Prandtl number retards the flow and also decreases temperatures and nano-particle concentration values.
(iii) Increasing streamwise coordinate decelerates the flow whereas it enhances temperatures and species (nano-particle) concentrations.
(iv) Increasing velocity slip strongly enhances velocities and reduces temperatures and nano-particle concentrations.
(v) Increasing thermal slip strongly reduces velocities, temperatures and nano-particle concentrations.
(vi) Increasing Brownian motion accelerates the flow and enhances temperatures whereas it reduces nanoparticle concentration boundary layer thickness.
(vii) Increasing thermophoretic parameter increasing momentum (hydrodynamic) boundary layer thickness and nanoparticle boundary layer thickness whereas it reduces thermal boundary layer thickness.

The current study has explored an interesting viscoplastic model for nanomaterials which are currently of interest in aerospace coating applications. Time-dependent effects have been neglected. Future studies will therefore address transient enrobing viscoplastic nanofluid transport phenomena for alternative geometries (wedge, cone, sphere), also of interest in aerospace materials fabrication and will be communicated imminently.

References


**Nomenclature**

- **C**: dimensional concentration
- **C_p**: specific heat at constant pressure (J/kg K)
- **f**: skin friction coefficient
- **D_B**: Brownian diffusion coefficient (m²/s)
- **D_T**: thermophoretic diffusion coefficient (m²/s)
- **f**: non-dimensional stream function
- **g**: acceleration due to gravity
- **Gr**: Grashof (free convection) number
- **Le**: Lewis number
- **Nb**: Brownian motion parameter
- **Nt**: thermophoresis parameter
- **Nu**: local Nusselt number
- **Sh**: Sherwood number
- **T**: temperature
- **u**, **v**: non-dimensional velocity components along the x- and y- directions, respectively
- **x**: stream wise coordinate
- **y**: transverse coordinate

**Greek symbol**

- **α**: thermal diffusivity
- **β**: non-Newtonian Casson parameter
- **η**: dimensionless transverse coordinate
- **ν**: kinematic viscosity
- **θ**: non-dimensional temperature
- **ρ**: density of nanofluid
\( \xi \)    dimensionless stream wise coordinate

\( \mathcal{V} \)    dimensionless stream function

**Subscripts**

\( w \)    conditions on the wall